

A COMPLEMENT TO THE PAPER

“ON THE KOLÁŘ CONNECTION”

[ARCH. MATH. (BRNO) 49 (2013), 223–240]

W.M. MIKULSKI

On page 229 of [2], we have the following text

“From Corollary 19.8 in [1], we get immediately the following proposition

Proposition 1. *Let $p_Y: Y \rightarrow M$ be an $\mathcal{FM}_{m,n}$ -object and $p_E: E \rightarrow M$ be a $\mathcal{VB}_{m,n}$ -object, $y \in Y_x$, $x \in M$. Let $(\Gamma, \Lambda, \Phi, \Delta) \in \text{Con}(Y) \times \text{Con}_{\text{clas}}^o(M) \times \text{Par}(Y \times_M E) \times \text{Con}_{\text{lin}}(E)$. There exists a finite number $r = r(\Gamma, \Lambda, \Phi, \Delta, y)$ such that for any $(\Gamma_1, \Lambda_1, \Phi_1, \Delta_1) \in \text{Con}(Y) \times \text{Con}_{\text{clas}}^o(M) \times \text{Par}(Y \times_M E) \times \text{Con}_{\text{lin}}(E)$ we have the following implication*

$$\begin{aligned} (j_y^r \Gamma_1 = j_y^r \Gamma, j_x^r \Lambda_1 = j_x^r \Lambda, j_y^r \Phi_1 = j_y^r \Phi, j_x^r \Delta_1 = j_x^r \Delta) \\ \Rightarrow A(\Gamma_1, \Lambda_1, \Phi_1, \Delta_1)(y) = A(\Gamma, \Lambda, \Phi, \Delta)(y) .” \end{aligned}$$

One can show that the above proposition is true but it is not an immediate consequence of Corollary 19.8 in [1]. From Corollary 19.8, it follows immediately the following weaker result.

Proposition 1’. *Let $p_Y: Y \rightarrow M$ be an $\mathcal{FM}_{m,n}$ -object and $p_E: E \rightarrow M$ be a $\mathcal{VB}_{m,n}$ -object, $y \in Y_x$, $x \in M$. Let $(\Gamma, \Lambda, \Phi, \Delta) \in \text{Con}(Y) \times \text{Con}_{\text{clas}}^o(M) \times \text{Par}(Y \times_M E) \times \text{Con}_{\text{lin}}(E)$. There exists a finite number $r = r(\Gamma, \Lambda, \Phi, \Delta, y)$ such that for any $(\Gamma_1, \Lambda_1, \Phi_1, \Delta_1) \in \text{Con}(Y) \times \text{Con}_{\text{clas}}^o(M) \times \text{Par}(Y \times_M E) \times \text{Con}_{\text{lin}}(E)$ we have the following implications*

$$\begin{aligned} j_y^r \Gamma_1 = j_y^r \Gamma &\Rightarrow A(\Gamma_1, \Lambda, \Phi, \Delta)(y) = A(\Gamma, \Lambda, \Phi, \Delta)(y) , \\ j_x^r \Lambda_1 = j_x^r \Lambda &\Rightarrow A(\Gamma, \Lambda_1, \Phi, \Delta)(y) = A(\Gamma, \Lambda, \Phi, \Delta)(y) , \\ j_y^r \Phi_1 = j_y^r \Phi &\Rightarrow A(\Gamma, \Lambda, \Phi_1, \Delta)(y) = A(\Gamma, \Lambda, \Phi, \Delta)(y) , \\ j_x^r \Delta_1 = j_x^r \Delta &\Rightarrow A(\Gamma, \Lambda, \Phi, \Delta_1)(y) = A(\Gamma, \Lambda, \Phi, \Delta)(y) . \end{aligned}$$

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One can easily see that by Proposition 1' we get the assumptions (2), (3), (4) and (5) on page 229 in [2]. Namely, by Proposition 1' we can replace Γ by Γ_1 being polynomial. Next by the same argument we can replace Λ by Λ_1 being polynomial. Next, by the same argument we can replace Φ by Φ_1 being polynomial. Next, by the same argument we can replace Δ_1 being polynomial.

Then using the same arguments as in [2] we obtain Lemma 4.1 of [2]. From Lemma 4.1 of [2] we get immediately Proposition 1.

So, we propose to replace Proposition 1 in [2] by Proposition 1'.

REFERENCES

- [1] Kolář, I., Michor, P. W., Slovák, J., *Natural Operations in Differential Geometry*, Springer Verlag, 1993.
- [2] Mikulski, W.M., *On the Kolář connection*, Arch. Math. (Brno) **49** (2013), 223–240.

JAGIELLONIAN UNIVERSITY, INSTITUTE OF MATHEMATICS,
LOJASIEWICZA 6, KRAKÓW, POLAND
E-mail: Wlodzimierz.Mikulski@im.uj.edu