

Research Article

Stability Property for the Predator-Free Equilibrium Point of Predator-Prey Systems with a Class of Functional Response and Prey Refuges

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We investigate the stability property for the predator-free equilibrium point of predator-prey systems with a class of functional response and prey refuges by using the analytical approach. Under some very weakly assumption, we show that conditions that ensure the locally asymptotically stable of the predator-free equilibrium point are consistent with that of the globally asymptotically stable ones. Our result supplements the corresponding result of Ma et al., 2009.

1. Introduction

Stability analysis of a predator-prey system incorporating a given functional response becomes a popular issue in mathematical ecology during the last decade [1–10]. Ma et al. [10] considered the effects of prey refuges on a predator-prey model with a class of functional response, for example,

$$\begin{aligned}\dot{X} &= rX\left(1 - \frac{X}{K}\right) - p\varphi(X - \beta X)Y, \\ \dot{Y} &= (q\varphi(X - \beta X) - d)Y,\end{aligned}\tag{1.1}$$

where $X(t)$ and $Y(t)$ denote the density of prey and predator populations at time t , respectively. The term $\varphi(X)$ represents the functional response of the predator population and satisfies the following assumption:

$$\varphi(0) = 0, \quad \varphi'(X) > 0 \quad (X > 0).\tag{1.2}$$

By using the change of variables:

$$\phi : (R_0^+)^2 \longrightarrow (R_0^+)^2, \quad \phi(X, Y) = \left(\frac{x}{1-\beta}, (1-\beta)y \right), \quad (1.3)$$

system (1.1) is equivalent to the following model:

$$\begin{aligned} \dot{x} &= rx \left(1 - \frac{x}{(1-\beta)K} \right) - p\varphi(x)y, \\ \dot{y} &= (q\varphi(x) - d)y. \end{aligned} \quad (1.4)$$

Concerned with the stability property of the predator-free equilibrium, by analysing the Jacobian matrix, the authors obtained the following conclusions.

Conclusion 1. $E_1((1-\beta)K, 0)$ is locally asymptotically stable if and only if $q\varphi((1-\beta)K) - d < 0$.

Based on this conclusion, without any other deduction, they declared (see [10, Theorems 4.1(3) and 4.2(3)]).

Conclusion 2. If $1 - \varphi^{-1}(d/q)/K < \beta < 1$, then predator goes extinct while prey population reaches its maximum environment carrying capacity.

Note that Conclusion 1 is local one while Conclusion 2 reflects the globally property of the system (1.4). Obviously there is a gap between these two conclusions. To show the Conclusion 1 implies Conclusion 2, some more detail analysis is needed. The aim of this paper is try to show that under some very weakly assumption on φ , the local asymptotical stability of the predator-free equilibrium point do implies the global ones. More precisely, we obtain the following result.

Theorem 1.1. *Assume that $\varphi(x) = \varphi_1(x)x$ and there exists a positive constant L such that $\varphi_1(x) \leq L$ for all $x > 0$ holds, assume further that $1 - \varphi^{-1}(d/q)/K < \beta < 1$ holds. Then predator species will be extinct while prey population reaches its maximum environment carrying capacity.*

Remark 1.2. Many explicit forms for the predator functional response that have been used are satisfy above assumption. For example,

$$\begin{aligned} &\frac{bx}{a+x} \text{ [Holling type II]}, \\ &\frac{bx^2}{a+x^2} \text{ [Holling type III]}, \\ &a(1 - \exp\{-cx\}) \text{ [Ivlev]}, \\ &bx^\gamma, \quad 0 < \gamma < 1 \text{ [Rosenzweig]}. \end{aligned} \quad (1.5)$$

2. Proof of the Main Result

Proof. We first show that under the assumption of Conclusion 2, predator species will be driven to extinction.

It follows from $1 - \varphi^{-1}(d/q)/K < \beta < 1$ and the continuity of φ , for enough small positive constant ε , the following inequality holds:

$$\beta > 1 - \frac{\varphi^{-1}((d - \varepsilon)/q)}{K + \varepsilon}, \quad (2.1)$$

that is,

$$\varphi^{-1}\left(\frac{d - \varepsilon}{q}\right) > (1 - \beta)(K + \varepsilon). \quad (2.2)$$

Since $\varphi'(X) > 0$, $X > 0$, inequality (2.2) is equal to the following inequality:

$$d - \varepsilon > q\varphi((1 - \beta)(K + \varepsilon)). \quad (2.3)$$

From the first equation of system (1.4), we have

$$\dot{x} \leq rx \left(1 - \frac{x}{(1 - \beta)K}\right). \quad (2.4)$$

Therefore,

$$\limsup_{t \rightarrow +\infty} x(t) \leq (1 - \beta)K. \quad (2.5)$$

For ε defined by (2.1), inequality (2.5) shows that there exists an enough large T such that

$$x(t) < (1 - \beta)(K + \varepsilon), \quad \forall t \geq T. \quad (2.6)$$

And so, for $t \geq T$, from the second equation of system (1.4) and (2.3), one has

$$\dot{y} \leq (q\varphi((1 - \beta)(K + \varepsilon)) - d)y < -\varepsilon y. \quad (2.7)$$

That is,

$$y(t) \leq y(T) \exp\{-\varepsilon(t - T)\} \longrightarrow 0, \quad \text{as } t \longrightarrow +\infty. \quad (2.8)$$

For any small positive constant $\varepsilon_1 > 0$ which satisfies $\varepsilon_1 \leq r/2pL$, there exists a $T_1 > T$ such that

$$y(t) \leq \varepsilon_1, \quad \forall t > T_1. \quad (2.9)$$

On the other hand, since $\varphi(x) = \varphi_1(x)x$ and $\varphi_1(x) \leq L$ for all $x > 0$. Equation (2.9) together with the first equation of (1.4) leads to

$$\begin{aligned} \dot{x} &= rx \left(1 - \frac{x}{(1-\beta)K} \right) - p\varphi_1(x)xy \\ &\geq rx \left(1 - \frac{x}{(1-\beta)K} \right) x - pL\varepsilon_1 x \\ &\geq rx \left(\frac{1}{2} - \frac{x}{(1-\beta)K} \right), \end{aligned} \quad (2.10)$$

for all $t \geq T_1$. From this different inequality, one could easily obtain that,

$$\liminf_{t \rightarrow +\infty} x(t) \geq \frac{(1-\beta)K}{2}. \quad (2.11)$$

Now we introducing a transformation $z = x - (1-\beta)k$, then the first equation of system (1.4) is equivalent to

$$\dot{z} = -\frac{rz}{(1-\beta)k} (z + (1-\beta)k) - p\varphi(z + (1-\beta)k)y. \quad (2.12)$$

From (2.5), (2.11), and (2.12) we know that $z(t)$ is bounded differentiable on $(0, \infty)$, Let $\bar{z} = \limsup_{t \rightarrow +\infty} z(t)$, $\underline{z} = \liminf_{t \rightarrow +\infty} z(t)$, According to Fluctuation lemma [11], there exists sequences $\tau_n \rightarrow \infty$, $\sigma_n \rightarrow \infty$ such that $\dot{z}(\tau_n) \rightarrow 0$, $\dot{z}(\sigma_n) \rightarrow 0$, $z(\xi_n) \rightarrow \underline{z}$ and $z(\sigma_n) \rightarrow \bar{z}$. Also, it follows from (2.12) that

$$\begin{aligned} \dot{z}(\sigma_n) &= -\frac{rz(\sigma_n)}{(1-\beta)k} (z(\sigma_n) + (1-\beta)k) - p\varphi(z(\sigma_n) + (1-\beta)k)y(\sigma_n). \\ \dot{z}(\xi_n) &= -\frac{rz(\xi_n)}{(1-\beta)k} (z(\xi_n) + (1-\beta)k) - p\varphi(z(\xi_n) + (1-\beta)k)y(\xi_n). \end{aligned} \quad (2.13)$$

Since (2.11) implies that

$$\lim_{n \rightarrow +\infty} (z(\xi_n) + (1-\beta)k) \geq \frac{(1-\beta)K}{2}. \quad (2.14)$$

Taking limit in (2.13) and (2.14), it follows from (2.8) and (2.16) that

$$0 = \bar{z} = \underline{z}, \quad (2.15)$$

that is

$$\lim_{t \rightarrow +\infty} z(t) = 0, \quad (2.16)$$

which is equivalent to say that

$$\lim_{t \rightarrow +\infty} x(t) = (1 - \beta)K. \quad (2.17)$$

This ends the proof of Theorem 1.1. \square

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