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Research Article

Fixed Points of Weakly Compatible Maps Satisfying a General Contractive Condition of Integral Type

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We prove a fixed point theorem for weakly compatible maps satisfying a general contractive condition of integral type.

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1. Introduction

Branciari [1] obtained a fixed point result for a single mapping satisfying an analogue of Banach's contraction principle for an integral-type inequality. The authors in [2-6] proved some fixed point theorems involving more general contractive conditions. Also in [7], Suzuki shows that Meir-Keeler contractions of integral type are still Meir-Keeler contractions. In this paper, we establish a fixed point theorem for weakly compatible maps satisfying a general contractive inequality of integral type. This result substantially extends the theorems of [1,4,6].

Sessa [8] generalized the concept of commuting mappings by calling self-mappings A and S of metric space (X,d) a weakly commuting pair if and only if $d(ASx,SAx) \le d(Ax,Sx)$ for all $x \in X$. He and others proved some common fixed point theorems of weakly commuting mappings [8–11]. Then, Jungck [12] introduced the concept of compatibility and he and others proved some common fixed point theorems using this concept [12–16].

Clearly, commuting mappings are weakly commuting and weakly commuting mappings are compatible. Examples in [8, 12] show that neither converse is true.

Recently, Jungck and Rhoades [14] defined the concept of weak compatibility.

Definition 1.1 (see [14, 17]). Two maps $A,S:X \to X$ are said to be weakly compatible if they commute at their coincidence points.

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Again, it is obvious that compatible mappings are weakly compatible. Examples in [14, 17] show that neither converse is true. Many fixed point results have been obtained for weakly compatible mappings (see [14, 17–21]).

LEMMA 1.2 (see [22]). Let $\psi : \mathbb{R}^+ \to \mathbb{R}^+$ be a right continuous function such that $\psi(t) < t$ for every t > 0, then $\lim_{n \to \infty} \psi^n(t) = 0$, where ψ^n denotes the n-times repeated composition of ψ with itself.

2. Main result

Now we give our main theorem.

THEOREM 2.1. Let A, B, S, and T be self-maps defined on a metric space (X,d) satisfying the following conditions:

- (i) $S(X) \subseteq B(X)$, $T(X) \subseteq A(X)$,
- (ii) for all $x, y \in X$, there exists a right continuous function $\psi : \mathbb{R}^+ \to \mathbb{R}^+$, $\psi(0) = 0$, and $\psi(s) < s$ for s > 0 such that

$$\int_{0}^{d(Sx,Ty)} \varphi(t)dt \le \psi\left(\int_{0}^{M(x,y)} \varphi(t)dt\right),\tag{2.1}$$

where $\varphi: \mathbb{R}^+ \to \mathbb{R}^+$ is a Lebesque integrable mapping which is summable, nonnegative and such that

$$\int_{0}^{\varepsilon} \varphi(t)dt > 0 \quad \text{for each } \varepsilon > 0, \tag{2.2}$$

$$M(x,y) = \max \left\{ d(Ax,By), d(Sx,Ax), d(Ty,By), \frac{d(Sx,By) + d(Ty,Ax)}{2} \right\}. \tag{2.3}$$

If one of A(X), B(X), S(X), or T(X) is a complete subspace of X, then

- (1) A and S have a coincidence point, or
- (2) *B* and *T* have a coincidence point.

Further, if S and A as well as T and B are weakly compatible, then

(3) A, B, S, and T have a unique common fixed point.

Proof. Let $x_0 \in X$ be an arbitrary point of X. From (i) we can construct a sequence $\{y_n\}$ in X as follows:

$$y_{2n+1} = Sx_{2n} = Bx_{2n+1}, y_{2n+2} = Tx_{2n+1} = Ax_{2n+2}$$
 (2.4)

for all n = 0, 1, ... Define $d_n = d(y_n, y_{n+1})$. Suppose that $d_{2n} = 0$ for some n. Then $y_{2n} = y_{2n+1}$; that is, $Tx_{2n-1} = Ax_{2n} = Sx_{2n} = Bx_{2n+1}$, and A and S have a coincidence point. \square

Similarly, if $d_{2n+1} = 0$, then B and T have a coincidence point. Assume that $d_n \neq 0$ for each n.

Then, by (ii),

$$\int_{0}^{d(Sx_{2n},Tx_{2n+1})} \varphi(t)dt \le \psi\left(\int_{0}^{M(x_{2n},x_{2n+1})} \varphi(t)dt\right),\tag{2.5}$$

where

$$M(x_{2n}, x_{2n+1}) = \max \left\{ d(Ax_{2n}, Bx_{2n+1}), d(Sx_{2n}, Ax_{2n}), d(Tx_{2n+1}, Bx_{2n+1}), \frac{d(Sx_{2n}, Bx_{2n+1}) + d(Tx_{2n+1}, Ax_{2n})}{2} \right\}$$
(2.6)

 $= \max\{d_{2n}, d_{2n+1}\}.$

Thus from (2.5), we have

$$\int_{0}^{d_{2n+1}} \varphi(t)dt \le \psi\left(\int_{0}^{\max\{d_{2n}, d_{2n+1}\}} \varphi(t)dt\right). \tag{2.7}$$

Now, if $d_{2n+1} \ge d_{2n}$ for some n, then, from (2.7), we have

$$\int_{0}^{d_{2n+1}} \varphi(t)dt \le \psi\left(\int_{0}^{d_{2n+1}} \varphi(t)dt\right) < \int_{0}^{d_{2n+1}} \varphi(t)dt, \tag{2.8}$$

which is a contradiction. Thus $d_{2n} > d_{2n+1}$ for all n, and so, from (2.7), we have

$$\int_0^{d_{2n+1}} \varphi(t)dt \le \psi\left(\int_0^{d_{2n}} \varphi(t)dt\right). \tag{2.9}$$

Similarly,

$$\int_0^{d_{2n}} \varphi(t)dt \le \psi\left(\int_0^{d_{2n-1}} \varphi(t)dt\right). \tag{2.10}$$

In general, we have for all n = 1, 2, ...,

$$\int_0^{d_n} \varphi(t)dt \le \psi\left(\int_0^{d_{n-1}} \varphi(t)dt\right). \tag{2.11}$$

From (2.11), we have

$$\int_{0}^{d_{n}} \varphi(t)dt \leq \psi\left(\int_{0}^{d_{n-1}} \varphi(t)dt\right)$$

$$\leq \psi^{2}\left(\int_{0}^{d_{n-2}} \varphi(t)dt\right)$$

$$\vdots$$

$$\left(\int_{0}^{d_{0}} \varphi(t)dt\right)$$
(2.12)

 $\leq \psi^n \left(\int_0^{d_0} \varphi(t) dt \right),$

and, taking the limit as $n \to \infty$ and using Lemma 1.2, we have

$$\lim_{n\to\infty} \int_0^{d_n} \varphi(t)dt \le \lim_{n\to\infty} \psi^n \left(\int_0^{d_0} \varphi(t)dt \right) = 0, \tag{2.13}$$

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which, from (2.2), implies that

$$\lim_{n \to \infty} d_n = \lim_{n \to \infty} d(y_n, y_{n+1}) = 0.$$
 (2.14)

We now show that $\{y_n\}$ is a Cauchy sequence. For this it is sufficient to show that $\{y_{2n}\}$ is a Cauchy sequence. Suppose that $\{y_{2n}\}$ is not a Cauchy sequence. Then there exists an $\varepsilon > 0$ such that for each even integer 2k there exist even integers 2m(k) > 2n(k) > 2k such that

$$d(y_{2n(k)}, y_{2m(k)}) \ge \varepsilon. \tag{2.15}$$

For every even integer 2k, let 2m(k) be the least positive integer exceeding 2n(k) satisfying (2.15) such that

$$d(y_{2n(k)}, y_{2m(k)-2}) < \varepsilon. \tag{2.16}$$

Now

$$0 < \delta := \int_{0}^{\varepsilon} \varphi(t)dt \le \int_{0}^{d(y_{2n(k)}, y_{2m(k)})} \varphi(t)dt \le \int_{0}^{d(y_{2n(k)}, y_{2m(k)-2}) + d_{2m(k)-2} + d_{2m(k)-2} + d_{2m(k)-1}} \varphi(t)dt. \quad (2.17)$$

Then by (2.14), (2.15), and (2.16), it follows that

$$\lim_{k \to \infty} \int_{0}^{d(y_{2m(k)}, y_{2m(k)})} \varphi(t) dt = \delta.$$
 (2.18)

Also, by the triangular inequality,

$$|d(y_{2n(k)}, y_{2m(k)-1}) - d(y_{2n(k)}, y_{2m(k)})| \le d_{2m(k)-1}, |d(y_{2n(k)+1}, y_{2m(k)-1}) - d(y_{2n(k)}, y_{2m(k)})| \le d_{2m(k)-1} + d_{2n(k)},$$
(2.19)

and so

$$\int_{0}^{|d(y_{2n(k)}, y_{2m(k)-1}) - d(y_{2n(k)}, y_{2m(k)})|} \varphi(t)dt \leq \int_{0}^{d_{2m(k)-1}} \varphi(t)dt,$$

$$\int_{0}^{|d(y_{2n(k)+1}, y_{2m(k)-1}) - d(y_{2n(k)}, y_{2m(k)})|} \varphi(t)dt \leq \int_{0}^{d_{2m(k)-1} + d_{2n(k)}} \varphi(t)dt.$$
(2.20)

Using (2.18), we get

$$\int_0^{d(y_{2n(k)}, y_{2m(k)-1})} \varphi(t)dt \longrightarrow \delta, \tag{2.21}$$

$$\int_{0}^{d(y_{2n(k)+1},y_{2m(k)-1})} \varphi(t)dt \longrightarrow \delta, \qquad (2.22)$$

as $k \to \infty$. Thus

$$d(y_{2n(k)}, y_{2m(k)}) \le d_{2n(k)} + d(y_{2n(k)+1}, y_{2m(k)}) \le d_{2n(k)} + d(Sx_{2n(k)}, Tx_{2m(k)-1}),$$
 (2.23)

and so

$$\int_{0}^{d(y_{2n(k)}, y_{2m(k)})} \varphi(t)dt \le \int_{0}^{d_{2n(k)} + d(Sx_{2n(k)}, Tx_{2m(k)-1})} \varphi(t)dt. \tag{2.24}$$

Letting $k \to \infty$ on both sides of the last inequality, we have

$$\delta \leq \lim_{k \to \infty} \int_{0}^{d(Sx_{2n(k)}, Tx_{2m(k)-1})} \varphi(t)dt \leq \lim_{k \to \infty} \psi\left(\int_{0}^{M(x_{2n(k)}, x_{2m(k)-1})} \varphi(t)dt\right), \tag{2.25}$$

where

$$M(x_{2n(k)}, x_{2m(k)-1}) = \max \left\{ d(y_{2n(k)}, y_{2m(k)-1}), d_{2n(k)}, d_{2m(k)-1}, \frac{d(y_{2n(k)+1}, y_{2m(k)-1}) + d(y_{2n(k)}, y_{2m(k)})}{2} \right\}.$$
(2.26)

Combining (2.14), (2.15), (2.16), (2.18), (2.21), and (2.22) yields the following contradiction from (2.25):

$$\delta \le \psi(\delta) < \delta. \tag{2.27}$$

Thus $\{y_{2n}\}$ is a Cauchy sequence and so $\{y_n\}$ is a Cauchy sequence.

Now, suppose that A(X) is complete. Note that the sequence $\{y_{2n}\}$ is contained in A(X) and has a limit in A(X). Call it u. Let $v \in A^{-1}u$. Then Av = u. We will use the fact that the sequence $\{y_{2n-1}\}$ also converges to u. To prove that Sv = u, let r = d(Sv, u) > 0. Then taking x = v and $y = x_{2n-1}$ in (ii),

$$\int_{0}^{d(Sv, y_{2n})} \varphi(t)dt = \int_{0}^{d(Sv, Tx_{2n-1})} \varphi(t)dt \le \psi\left(\int_{0}^{M(v, x_{2n-1})} \varphi(t)dt\right), \tag{2.28}$$

where

$$M(v,x_{2n-1}) = \max \left\{ d(u,y_{2n-1}), d(Sv,u), d(y_{2n},y_{2n-1}), \frac{d(Sv,y_{2n-1}) + d(y_{2n},u)}{2} \right\}.$$
(2.29)

Since $\lim_n d(Sv, y_{2n}) = r$, $\lim_n d(u, y_{2n-1}) = \lim_n d(y_{2n}, y_{2n-1}) = 0$, and $\lim_n [d(Sv, y_{2n-1}) + d(y_{2n}, u)] = r$, we may conclude that

$$\int_{0}^{r} \varphi(t)dt \le \psi\left(\int_{0}^{r} \varphi(t)dt\right) < \int_{0}^{r} \varphi(t)dt, \tag{2.30}$$

which is a contradiction. Hence from (2.2), Sv = u. This proves (1).

Since $S(X) \subseteq B(X)$, Sv = u implies that $u \in B(X)$. Let $w \in B^{-1}u$. Then Bw = u. By using the argument of the previous section, it can be easily verified that Tw = u. This proves (2).

The same result holds if we assume that B(X) is complete instead of A(X).

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Now if T(X) is complete, then by (i), $u \in T(X) \subseteq A(X)$. Similarly if S(X) is complete, then $u \in S(X) \subseteq B(X)$. Thus (1) and (2) are completely established.

To prove (3), note that *S*, *A* and *T*, *B* are weakly compatible and

$$u = Sv = Av = Tw = Bw, (2.31)$$

then

$$Au = ASv = SAv = Su,$$

$$Bu = BTw = TBw = Tu.$$
(2.32)

If $Tu \neq u$ then, from (ii), (2.31) and (2.32),

$$\int_{0}^{d(u,Tu)} \varphi(t)dt = \int_{0}^{d(Sv,Tu)} \varphi(t)dt \le \psi\left(\int_{0}^{M(v,u)} \varphi(t)dt\right)
= \psi\left(\int_{0}^{d(u,Tu)} \varphi(t)dt\right) < \int_{0}^{d(u,Tu)} \varphi(t)dt,$$
(2.33)

which is a contradiction. So Tu = u. Similarly Su = u. Then, evidently from (2.32), u is a common fixed point of A, B, S, and T.

The uniqueness of the common fixed point follows easily from condition (ii).

Remark 2.2. Theorem 2.1 is a generalization of the main theorem of [1], Theorem 2 of [4], and Theorem 2 of [6].

If $\varphi(t) \equiv 1$, then Theorem 2.1 of this paper reduces to Theorem 2.1 of [17].

If $\varphi(t) \equiv 1$ and $\psi = ht$, $0 \le h < 1$, then Theorem 2.1 of this paper reduces to Corollary 3.1 of [20].

The following example shows that our main theorem is generalization of Corollary 3.1 of [20].

Example 2.3. Let $X = \{1/n : n \in N\} \cup \{0\}$ with Euclidean metric and S, T, A, B are self maps of X defined by

$$S\left(\frac{1}{n}\right) = \begin{cases} \frac{1}{n+1} & \text{if } n \text{ is odd,} \\ \frac{1}{n+2} & \text{if } n \text{ is even,} \\ 0 & \text{if } n = \infty, \end{cases} \qquad T\left(\frac{1}{n}\right) = \begin{cases} \frac{1}{n+1} & \text{if } n \text{ is even,} \\ \frac{1}{n+2} & \text{if } n \text{ is odd,} \\ 0 & \text{if } n = \infty, \end{cases}$$
(2.34)

$$A\left(\frac{1}{n}\right) = B\left(\frac{1}{n}\right) = \frac{1}{n} \quad \forall n \in \mathbb{N} \cup \{\infty\}.$$

Clearly $S(X) \subseteq B(X)$, $T(X) \subseteq A(X)$, A(X) is a complete subspace of X and A, S and B, T are weakly compatible.

Now suppose that the contractive condition of Corollary 3.1 of [20] is satisfying, that is, there exists $h \in [0,1)$ such that

$$d(Sx, Ty) \le hM(x, y) \tag{2.35}$$

for all $x, y \in X$. Therefore, for $x \neq y$, we have

$$\frac{d(Sx, Ty)}{M(x, y)} \le h < 1, \tag{2.36}$$

but since $\sup_{x \neq y} (d(Sx, Ty)/M(x, y)) = 1$, one has a contradiction. Thus the condition (2.35) is not satisfied.

Now we define $\varphi(t) = \max\{0, t^{1/t-2}[1 - \log t]\}$ for t > 0, $\varphi(0) = 0$. Then for any $\tau \in$ (0,e),

$$\int_0^\tau \varphi(t)dt = \tau^{1/\tau}.\tag{2.37}$$

Thus we must show that there exists a right continuous function $\psi : \mathbb{R}^+ \to \mathbb{R}^+$, $\psi(s) < s$ for s > 0, $\psi(0) = 0$ such that

$$(d(Sx, Ty))^{1/d(Sx, Ty)} \le \psi((M(x, y))^{1/M(x, y)})$$
 (2.38)

for all $x, y \in X$. Now we claim that (2.38) is satisfying with $\psi(s) = s/2$, that is,

$$(d(Sx, Ty))^{1/d(Sx, Ty)} \le \frac{1}{2} ((M(x, y))^{1/M(x, y)})$$
 (2.39)

for all $x, y \in X$. Since the function $\tau \to \tau^{1/\tau}$ is nondecreasing, we show sufficiently that

$$(d(Sx, Ty))^{1/d(Sx, Ty)} \le \frac{1}{2} ((d(x, y))^{1/d(x, y)})$$
 (2.40)

instead of (2.39). Now using Example 4 of [6], we have (2.40), thus the condition (2.38) is satisfied.

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