

## NONOSCILLATION THEOREMS FOR FUNCTIONAL DIFFERENTIAL EQUATIONS OF ARBITRARY ORDER

**JOHN R. GRAEF**

Department of Mathematics and Statistics, Mississippi State University, Mississippi State, Mississippi 39762.

**MYRON K. GRAMMATIKOPOULOS**

Department of Mathematics, University of Ioannina, Ioannina, Greece.

**YUICHI KITAMURA**

Department of Mathematics, Nagasaki University, Nagasaki 852, Japan.

**TAKA<sup>^</sup>SI KUSANO**

Department of Mathematics, Hiroshima University, Hiroshima 730, Japan.

**HIROSHI ONOSE**

Department of Mathematics, Ibaraki University, Mito, 310, Japan.

**PAUL W. SPIKES**

Department of Mathematics and Statistics, Mississippi State University, Mississippi State, Mississippi 39762.

(Received May 20, 1983)

**ABSTRACT.** The authors give sufficient conditions for all oscillatory solutions of a sublinear forced higher order nonlinear functional differential equation to converge to zero. They then prove a nonoscillation theorem for such equations. A few intermediate results are also obtained.

**KEY WORDS AND PHRASES.** *Convergence to zero, nonoscillation, oscillatory solutions.*  
*1980 MATHEMATICS SUBJECT CLASSIFICATION CODE. Primary 34K25, 34C10, 34C15.*

### 1. INTRODUCTION.

Consider the  $n$ -th order ( $n \geq 2$ ) nonlinear differential equation

$$(r(t)x^{(n-\nu)}(t))^{(\nu)} = f(t, x(t), x(g(t))) \quad (1.1)$$

where  $1 \leq \nu \leq n - 1$ , and the functions  $r, g : [t_0, \infty) \rightarrow \mathbb{R}$  and  $f : [t_0, \infty) \times \mathbb{R}^2 \rightarrow \mathbb{R}$  are continuous. We shall also require throughout that  $r(t) > 0$  and  $g(t) \rightarrow \infty$  as  $t \rightarrow \infty$ .

Our principal efforts here will be to obtain conditions which imply that certain classes of solutions of equation (1.1) are nonoscillatory and sufficient conditions to

ensure that some classes of oscillatory solutions of (1.1) tend to zero as  $t \rightarrow \infty$ . The results obtained here for oscillatory solutions extend results previously given in [6, 8, 10, and 13], and the nonoscillation results extend those found in [1, 5-8, 10, and 13]. We note that the only nonoscillation theorems known for higher order ordinary nonlinear equations are due to Chen [1], Graef [4], and Staikos and Philos [13]. In the case of higher order functional equations the nonoscillation problem is considerably more difficult than it is for ordinary equations with the only results to date being those of Graef et al. [5-7] and Singh [10]. For a discussion of the particular difficulties encountered in obtaining such results for functional differential equations the reader is referred to [8].

2. MAIN RESULTS

A solution  $x(t)$  of (1.1) will be called oscillatory if its set of zeros is unbounded and it will be called nonoscillatory otherwise. Without further mention we note that the results here pertain only to the continuable solutions of (1.1), and that a number of them will be for classes of solutions of (1.1) which satisfy a growth condition of the form

$$|x(t)| = O(m(t)) \text{ as } t \rightarrow \infty \tag{2.1}$$

where  $m : [t_0, \infty) \rightarrow \mathbb{R}$  is positive and continuous. The asymptotic behavior of certain solutions of functional differential equations which satisfy conditions of type (2.1) has also been studied by other authors, for example Staikos and Sficas [14] and Graef et al. [6, 8].

We will assume in the remainder of this paper that the function  $f$  in (1.1) satisfies an estimate of the form

$$|f(t, x, y)| \leq F(t, |x|, |y|) \tag{2.2}$$

where  $F : [t_0, \infty) \times \mathbb{R}_+^2 \rightarrow \mathbb{R}_+$  is continuous and

$$F(t, u, v) \leq F(t, u', v') \text{ for } 0 \leq u \leq u', 0 \leq v \leq v'.$$

It will also be convenient to use the notation

$$z(t) = r(t)x^{(n-v)}(t)$$

and

$$\omega_k(t) = \begin{cases} x^{(k)}(t), & \text{if } 0 \leq k \leq n - v - 1 \\ z^{(k-n+v)}(t), & \text{if } n - v \leq k \leq n \end{cases}$$

throughout the paper. Before stating our first result we note that if  $x(t)$  is an oscillatory solution of (1.1), then  $\omega_k(t)$  also oscillates for  $k = 1, 2, \dots, n - 1$ . The following lemma provides some useful expressions for  $\omega_k(t)$ ; they will be used in the remainder of this paper.

LEMMA 1. Let  $T_1 \leq T_2 \leq \dots \leq T_n$  be such that

$$\omega_{n-j}(T_j) = 0, \quad j = 1, 2, \dots, n. \tag{2.3}$$

Then for any  $t > T_n$  we have

$$\omega_{n-j}(t) = \int_{T_j}^t \int_{T_{j-1}}^{s_{j-1}} \dots \int_{T_1}^{s_1} f(s, x(s), x(g(s))) ds ds_1 \dots ds_{j-1} \tag{2.4}$$

for  $1 \leq j \leq \nu$ , and

$$\omega_{n-j}(t) = \int_{T_j}^t \dots \int_{T_{\nu+1}}^{s_{\nu+1}} [1/r(s_\nu)] \int_{T_\nu}^{s_\nu} \dots \int_{T_1}^{s_1} f(s, x(s), x(g(s))) ds ds_1 \dots ds_{j-1} \tag{2.5}$$

for  $\nu + 1 \leq j \leq n$ .

PROOF. The conclusions of the lemma follow from (1.1) by integrating from  $T_j$  to  $t$  successively for  $j = 1, 2, \dots, n$ .

THEOREM 2. Suppose that (2.2) holds and

$$\int_{t_0}^\infty [s^{n-\nu-1}/r(s)] \int_{t_0}^s (s-u)^{\nu-1} F(u, cm(u), cm(g(u))) du ds < \infty \tag{2.6}$$

for any constant  $c > 0$ . If  $x(t)$  is an oscillatory solution of (1.1) satisfying (2.1), then  $\omega_k(t) \rightarrow 0$  as  $t \rightarrow \infty$  for  $k = 0, 1, \dots, n - \nu - 1$ .

PROOF. Let  $x(t)$  be an oscillatory solution of (1.1) satisfying (2.1). Then there exists  $T > t_0$  and a constant  $c > 0$  so that  $|x(t)| \leq cm(t)$  and  $|x(g(t))| \leq cm(g(t))$  for  $t \geq T$ . Choose  $T_j$ ,  $1 \leq j \leq n$ , so that  $T \leq T_1 \leq T_2 \leq \dots \leq T_n$  and (2.3) holds. Integrating equation (1.1)  $j$ -times for  $\nu + 1 \leq j \leq n$  we obtain (2.5). Note that if  $t_1 < t_2 < t$ , then

$$\left| \int_{t_2}^t \int_{t_1}^s P(u) du ds \right| \leq \int_{t_2}^t \left| \int_{t_1}^s P(u) du \right| ds \leq \int_{t_1}^t \left| \int_{t_1}^s P(u) du \right| ds \leq \int_{t_1}^t \int_{t_1}^s |P(u)| du ds.$$

Hence from (2.1), (2.2), and (2.5) we have

$$\begin{aligned} |\omega_{n-j}(t)| &\leq \int_{T_1}^t \int_{T_1}^{s_{j-1}} \dots \int_{T_1}^{s_{\nu+1}} [1/r(s_\nu)] \int_{T_1}^{s_\nu} \dots \\ &\int_{T_1}^{s_1} F(u, cm(u), cm(g(u))) du ds_1 \dots ds_{j-1}. \end{aligned} \tag{2.7}$$

Condition (2.6) implies that  $\omega_k(t) = \omega_{n-j}(t) \rightarrow 0$  as  $t \rightarrow \infty$  for  $k = 0, 1, \dots, n - \nu - 1$ .

REMARK. If  $m(t) \equiv K$ , where  $K$  is a positive constant, then from Theorem 2 we have that all bounded oscillatory solutions of (1.1) tend to zero as  $t \rightarrow \infty$  together with  $\omega_k(t)$  for  $k = 1, 2, \dots, n - \nu - 1$ .

In view of Theorem 2 it is reasonable to ask if it is possible to obtain a similar result but with  $\omega_k(t) \rightarrow 0$  as  $t \rightarrow \infty$  for all  $k$  independent of the value of

i.e.,  $k = 0, 1, \dots, n - 1$ . If we choose  $T_1 \leq T_2 \leq \dots \leq T_n$  such that

$\omega_{n-j}(T_{n-j+1}) = 0$  for  $j = 1, 2, \dots, n$  and then integrate equation (1.1) from  $t < T_1$  to  $T_{n-j+1}$  for  $j = 1, 2, \dots, n$  successively we would obtain expressions for  $\omega_{n-j}(t)$  similar to (2.4) and (2.5) but having a factor of  $(-1)^j$  and variable lower limits. If we would then replace (2.6) by

$$\int [s^{n-v-1}/r(s)] \int_s^\infty (u-s)^{v-1} F(u, cm(u), cm(g(u))) du ds < \infty,$$

we would have that  $\omega_k(t) \rightarrow 0$  as  $t \rightarrow \infty$  for  $k = 0, 1, \dots, n - 1$ . This approach however is not useful in obtaining the type of results we desire in the remainder of this paper. Due to an error in the way the  $T_j$ 's were chosen and the integrations performed, several incorrect results have appeared in the literature (see the discussions in [6] and [12]). We will discuss this point further later in the paper.

In the next theorem we will ask that the function  $F$  satisfy the following sublinearity type condition. There exists a continuous function  $H : [T_0, \infty) \rightarrow R$  such that

$$\limsup_{v \rightarrow \infty} F(t, v, v)/v \leq H(t). \tag{2.8}$$

**THEOREM 3.** Let conditions (2.2), (2.6), and (2.8) hold with  $m(t) \equiv K$  where  $K$  is any positive constant. If in addition

$$g(t) \leq t \tag{2.9}$$

and

$$\int_{t_0}^\infty [s^{n-v-1}/r(s)] \int_{t_0}^s (s-u)^{v-1} H(u) du ds < \infty, \tag{2.10}$$

then every oscillatory solution of (1.1) is bounded.

**PROOF.** Assume that the conclusion of the theorem does not hold. Then there is an unbounded oscillatory solution  $x(t)$  of (1.1). Now (2.10) implies that there exists  $t_1 > t_0$  so that

$$\int_{t_2}^\infty [s^{n-v-1}/r(s)] \int_{t_2}^s (s-u)^{v-1} H(u) du ds < 1/4$$

for any  $t_2 \geq t_1$ , and (2.8) implies that there is a constant  $v_1 > 0$  such that for  $v \geq v_1$

$$F(t, v, v) \leq 2vH(t)$$

on  $[t_1, \infty)$ . Let  $t_1 < T < T_1 \leq T_2 \leq \dots \leq T_n$  be such that  $g(t) \geq t_1$  for  $t > T$  and (2.3) holds. Since  $x(t)$  is oscillatory and unbounded, there exists an interval  $[a, b]$  with  $T_n < a < b$ ,  $x(a) = x(b) = 0$ ,  $|x(t)|_1 > 0$  on  $(a, b)$ , and

$$M = \max \{ |x(t)| : a \leq t \leq b \} = \max \{ |x(t)| : t_1 \leq t \leq b \} > v_1.$$

Notice that (2.9) ensures that  $|x(g(t))| \leq M$  for  $t$  in  $[T, b]$ . Moreover, from (2.2) and the properties of  $F$  we have

$$|f(t, x(t), x(g(t)))| \leq F(t, |x(t)|, |x(g(t))|) \leq F(t, M, M)$$

for  $T \leq t \leq b$ . Next choose  $t_3$  in  $(a, b)$  so that  $M = |x(t_3)|$ . Then from (2.7) it follows that

$$M = |x(t_3)| \leq \int_{T_1}^{t_3} [s^{n-\nu-1}/r(s)] \int_{T_1}^s (s-u)^{\nu-1} F(u, M, M) du ds / (n-\nu-1)!(\nu-1)! \leq 2M \int_{T_1}^{\infty} [s^{n-\nu-1}/r(s)] \int_{T_1}^s (s-u)^{\nu-1} H(u) du ds < M/2$$

which is clearly impossible.

When equation (1.1) is sublinear we can combine Theorems 2 and 3 to obtain the following result.

**THEOREM 4.** If conditions (2.2), (2.6), and (2.8)-(2.10) hold with  $m(t) \equiv K$  for any constant  $K > 0$ , then every oscillatory solution  $x(t)$  of (1) satisfies  $\omega_k(t) \rightarrow 0$  as  $t \rightarrow \infty$  for  $k = 0, 1, \dots, n - \nu - 1$ .

**PROOF.** Let  $x(t)$  be an oscillatory solution of (1.1), then by Theorem 3  $x(t)$  is bounded. Thus the hypotheses of Theorem 2 are satisfied with  $m(t) \equiv K$  for some constant  $K > 0$ , and hence the conclusion follows from Theorem 2.

**REMARK.** Theorems 2-4 above generalize Theorems 1 and 2 and Corollary 3 in [6], Theorems 1 and 3 and Corollary 2 in [8], Corollary 1 in [13], and special cases of Lemma 3.2 and Theorem 3.1 in [10] and Theorem 1 in [13]. For a discussion of known results of this type for second order equations, we refer the reader to references [6, 8, 10, and 13]. In these papers the authors unified and generalized much of what is known on this problem for second order equations.

Next we will give conditions which guarantee that certain classes of solutions of (1.1) are nonoscillatory. In so doing the connection between convergence to zero of oscillatory solutions and nonoscillation will become apparent. For this purpose we will need the existence of continuous functions  $G : [T_0, \infty) \times R_+^2 \rightarrow R_+$  and  $h : [t_0, \infty) \rightarrow R$  such that

$$G(t, u, v) \leq G(t, u', v') \quad \text{for } 0 \leq u \leq u', 0 \leq v \leq v', \tag{2.11}$$

$$|f(t, x, y) - h(t)| \leq G(t, |x|, |y|) \quad \text{for } x, y \in R, \tag{2.12}$$

$$\int_{t_0}^{\infty} [s^{n-\nu-1}/r(s)] \int_{t_0}^s (s-u)^{\nu-1} |h(u)| du ds < \infty, \tag{2.13}$$

and

$$\int_{t_0}^{\infty} [s^{n-\nu-1}/r(s)] \int_{t_0}^s (s-u)^{\nu-1} G(u, cm(u), cm(g(u))) du ds < \infty \tag{2.14}$$

for all  $c > 0$ .

**THEOREM 5.** Let (2.11) - (2.14) hold. Then all solutions of (1.1) that satisfy (2.1) are nonoscillatory provided there exists a constant  $k > 0$  such that either

$$\liminf_{t \rightarrow \infty} \int_T^t [h(s) - G(s,k,k)] ds > 0 \tag{2.15}$$

or

$$\limsup_{t \rightarrow \infty} \int_T^t [h(s) + G(s,k,k)] ds < 0 \tag{2.16}$$

for all large  $T$ .

PROOF. Let  $x(t)$  be an oscillatory solution of (1.1) satisfying (2.1). Then from (2.11) and (2.12) we see that (2.2) holds with  $F(t,u,v) = |h(t)| + G(t,u,v)$ . This, in addition to (2.13) and (2.14), shows that all the hypotheses of Theorem 2 are satisfied and hence  $x(t) \rightarrow 0$  as  $t \rightarrow \infty$ . Therefore there exists  $t_1 \geq t_0$  so that  $|x(t)| < k$  and  $|x(g(t))| < k$  for  $t \geq t_1$ . Now choose  $T > t_1$  so that  $\omega_{n-1}(T) = (r(T)x^{(n-v)}(T))^{(v-1)} = 0$ . From equation (1.1) and condition (2.12) we have

$$h(t) - G(t,k,k) \leq \omega_n(t) \leq h(t) + G(t,k,k)$$

for  $t \geq T$ . Integrating we obtain

$$\int_T^t [h(s) - G(s,k,k)] ds \leq \omega_{n-1}(t) \leq \int_T^t [h(s) + G(s,k,k)] ds.$$

If either (2.15) or (2.16) holds, then  $\omega_{n-1}(t)$  eventually has fixed sign which contradicts the assumption that  $x(t)$  is oscillatory.

The final theorem in this paper gives sufficient conditions for all solutions of (1.1) to be nonoscillatory.

THEOREM 6. Suppose that conditions (2.9) and (2.11) - (2.13) hold,  $G$  is sub-linear in the sense of condition (2.8), i.e. there exists  $H_G : [t_0, \infty) \rightarrow \mathbb{R}$  such that  $\limsup_{v \rightarrow \infty} G(t,v,v)/v \leq H_G(t)$ ,

$$\int_{t_0}^{\infty} [s^{n-v-1}/r(s)] \int_{t_0}^s (s-u)^{v-1} H_G(u) du ds < \infty, \tag{2.17}$$

and condition (2.14) holds with  $m(t) \equiv K$  for any constant  $K > 0$ . If either (2.15) or (2.16) holds, then all solutions of equation (1.1) are nonoscillatory.

PROOF. Assume that (1.1) has an oscillatory solution  $x(t)$ . Clearly conditions (2.2) and (2.8) are satisfied with  $F(t,u,v) = G(t,u,v) + |h(t)|$  and  $H(t) = H_G(t) + |h(t)|$ . Furthermore (2.13) and (2.17) imply that (2.10) holds; (2.13) and (2.14) holding with  $m(t) \equiv K$  shows that (2.6) is satisfied. It then follows from Theorem 4 that  $x(t) \rightarrow 0$  as  $t \rightarrow \infty$ . The remainder of the proof follows by proceeding as in the proof of Theorem 5 to again obtain a contradiction.

REMARK. Theorem 5 generalizes Theorem 5 in [6] and Theorem 4 in [8] while Theorem 6 generalizes Theorems 4 and 6 in [5], Theorem 4 in [6], Theorem 3 in [7], Theorem 5 in [8], Corollary 4 in [13], and special cases of Theorems 3,4,7, and 8 in [1] and Theorem 3.5 in [10].

As was mentioned earlier several incorrect results on the convergence to zero of

oscillatory solutions of higher order ordinary and functional equations have appeared in the literature. This has in turn invalidated the nonoscillation criteria in these papers as well. In this regard we refer the reader to the discussions in [6] and [12] as well as the papers [2, 3, 9, and 11]. The only correct nonoscillation criteria for higher order equations to date appear in [1, 4-7, 10, and 13].

In order to illustrate Theorem 6 we will interpret this theorem for the forced higher order generalized Emden-Fowler type equation

$$[r(t)x^{(n-\nu)}]^{(\nu)} + q(t)b(x(g(t))) = a(t) \quad (2.18)$$

where  $q, a : [t_0, \infty) \rightarrow \mathbb{R}$  and  $b : \mathbb{R} \rightarrow \mathbb{R}$  are continuous and  $r, g,$  and  $\nu$  are as before. For equation (2.18) we ask that  $g(t) \leq t$ ,  $b(x)$  is nondecreasing,

$$\limsup_{x \rightarrow \infty} |b(x)|/x < \infty,$$

$$\int_{t_0}^{\infty} [s^{n-\nu-1}/r(s)] \int_{t_0}^s (s-u)^{\nu-1} |a(u)| du ds < \infty,$$

$$\int_{t_0}^{\infty} [s^{n-\nu-1}/r(s)] \int_{t_0}^s (s-u)^{\nu-1} |q(u)| du ds < \infty,$$

and for some  $k > 0$

$$\liminf_{t \rightarrow \infty} \int_T^t [a(s) - k|q(s)|] ds > 0 \quad (2.19)$$

for all large  $T$ . Then all solutions of (2.18) are nonoscillatory. Obviously (2.19) could be replaced by a condition analogous to (2.16).

As an example we consider the equation

$$[t^\alpha x^{(n-\nu)}]^{(\nu)} + (1/t^\beta)x^\gamma(t^\sigma) = 1/t^\epsilon, \quad t \geq 1 \quad (2.20)$$

where  $0 < \sigma \leq 1$  and  $\gamma$  is the ratio of odd positive integers with  $0 < \gamma \leq 1$ ,  $\alpha + \epsilon > n$ ,  $\alpha > n - 1$  and  $\beta \geq \epsilon$ . Here (2.19) and all the other conditions listed above hold so by Theorem 6 all solutions of (2.20) are nonoscillatory. None of the nonoscillation criteria in [1, 4-7, 10, or 13] apply to this equation even when  $\sigma = 1$ .

In conclusion we note that although Theorem 5 does cover the case of super-linear equations (e.g.  $b(x) = x^\gamma$ ,  $\gamma > 1$ ) there are no known nonoscillation criteria for superlinear functional differential equations even in the case  $n = 2$ .

ACKNOWLEDGEMENT. J.R. Graef's and P.W. Spikes' research was supported by the Mississippi State University Biological and Physical Sciences Research Institute. M.K. Grammatikopoulos's research was supported by the Ministry of Coordination of Greece.

## REFERENCES

1. CHEN, L., Sufficient conditions for nonoscillation of  $n$ -th order differential equations, Atti Accad. Naz. Lincei Rend. Cl. Sci. Fis. Mat. Natur. (8) 60 (1976), 27-31.
2. CHEN, L., On the oscillation and asymptotic properties for general nonlinear differential equations, Atti Accad. Naz. Lincei Rend. Cl. Sci. Fis. Mat. Natur. (8) 61 (1976), 211-216 (1977).
3. CHEN, L., A Lyapunov inequality and forced oscillations in general nonlinear  $n$ -th order differential-difference equations, Glasgow Math. J. 18 (1977), 161-166.
4. GRAEF, J.R., Some nonoscillation criteria for higher order nonlinear differential equations, Pacific J. Math. 66 (1976), 125-129.
5. GRAEF, J.R., Oscillation, nonoscillation, and growth of solutions of nonlinear functional differential equations of arbitrary order, J. Math. Anal. Appl. 60 (1977), 398-409.
6. GRAEF, J.R., Nonoscillation of higher order functional differential equations, J. Math. Anal. Appl., 92 (1983), 524-532.
7. GRAEF, J.R., GRAMMATIKOPOULOS, M.K., and SPIKES, P.W., Growth and oscillatory behavior of solutions of a differential equation with a deviating argument, Funkcial. Ekvac., 23 (1980), 279-287.
8. GRAEF, J.R., KITAMURA, Y., KUSANO, T., ONOSE, H., and SPIKES, P.W., On the nonoscillation of perturbed functional differential equations, Pacific J. Math. 83 (1979), 365-373.
9. SINGH, B., Forced oscillations in general ordinary differential equations, Tamkang J. Math. 6 (1975), 5-11.
10. SINGH, B., Necessary and sufficient conditions for eventually vanishing oscillatory solutions of functional equations with small delays, Internat. J. Math. Math. Sci. 1 (1978), 269-283.
11. STAIKOS, V.A., and PHILOS, C.G., Some oscillation and asymptotic properties for linear differential equations, Bull. Fac. Sci. Ibaraki Univ. 8 (1976), 25-30.
12. STAIKOS, V.A., and PHILOS, C.G., Correction to: Some oscillation and asymptotic properties for linear differential equations, Bull. Fac. Sci. Ibaraki Univ. 10 (1978), 81-83.
13. STAIKOS, V.A., and Philo, C. G. Nonoscillatory phenomena and damped oscillations, Nonlinear Analysis, Theory, Methods and Applications, 2 (1978), 197-210.
14. STAIKOS, V.A. and SFICAS, Y.G., Forced oscillations for differential equations of arbitrary order, J. Differential Equations 17 (1975), 1-11.