

Existence Theory for Nonlinear Volterra Integral and Differential Equations

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In this paper we prove the existence theorems for the integrodifferential equation

$$y'(t) = f\left(t, y(t), \int_0^t k(t, s, y(s)) \, ds\right), \quad t \in I = [0, T],$$
$$y(0) = y_0,$$

where in first part f, k, y are functions with values in a Banach space E and the integral is taken in the sense of Bochner. In second part f, k are weakly–weakly sequentially continuous functions and the integral is the Pettis integral. Additionally, the functions f and k satisfy some boundary conditions and conditions expressed in terms of measure of noncompactness or measure of weak noncompactness.

Keywords: Integral equations; Existence theorem; Pseudo-solutions;
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1 INTRODUCTION

In this paper we establish some existence principles for integrodifferential operator equations and present existence result for integrodifferential and integral equations.

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The paper is divided into two main sections.

In Section 1 we prove some existence theorems for the problem

$$\begin{aligned} y'(t) &= f\left(t, y(t), \int_0^t k(t, s, y(s)) \, ds\right), \\ y(0) &= y_0, \end{aligned} \quad (1)$$

where $I = [0, T]$, E is a Banach space with the norm $\|\cdot\|$, f, k, y are functions with values in a Banach space E and the integral is the Bochner integral.

In Section 2 we prove some existence theorem for the problem (1), where f, k, y are functions with values in a Banach space E , f, k are functions weakly-weakly sequentially continuous and the integral is the Pettis integral [1]. The results of this paper extends existence theorems from Krzyńska [12], Cichoń [6], Meehan and O'Regan [13], O'Regan [16,17], Cramer *et al.* [7].

In this paper we use the measure of noncompactness developed by Kuratowski [11], and the measure of weak noncompactness developed by de Blasi [4].

Let A be a bounded nonvoid subset of E . The Kuratowski measure of noncompactness $\alpha(A)$ is defined by

$$\alpha(A) = \inf\{\varepsilon > 0: \text{there exists } C \in \mathcal{K} \text{ such that } A \subset C + \varepsilon B_0\},$$

where \mathcal{K} is the set of compact subsets of E and B_0 is the norm unit ball.

The de Blasi measure of weak noncompactness $\beta(A)$ is defined by

$$\beta(A) = \inf\{t > 0: \text{there exists } C \in \mathcal{K}^w \text{ such that } A \subset C + tB_0\},$$

where \mathcal{K}^w is the set of weakly compact subsets of E and B_0 is the norm unit ball.

The properties of measure of noncompactness $\alpha(A)$ are:

- (1⁰) if $A \subset B$ then $\alpha(A) \leq \alpha(B)$;
- (2⁰) $\alpha(A) = \alpha(\bar{A})$, where \bar{A} denotes the closure of A ;
- (3⁰) $\alpha(A) = 0$ if and only if A is relatively compact;
- (4⁰) $\alpha(A \cup B) = \max\{\alpha(A), \alpha(B)\}$;

- (5⁰) $\alpha(\lambda A) = |\lambda|\alpha(A) \ (\lambda \in \mathbb{R});$
- (6⁰) $\alpha(A + B) \leq \alpha(A) + \alpha(B);$
- (7⁰) $\alpha(\text{conv } A) = \alpha(A).$

The properties of weak measure of noncompactness β are analogous to the properties of measure of noncompactness, see [2–5, 14]. Moreover, we can construct many other measures with the above properties, by using a scheme from [5]. We now gather some well-known definitions and results from the literature, which we will use throughout this paper.

DEFINITION 1 *A function $f: I \times E \times E \rightarrow E$ is L^1 -Carathéodory, if the following conditions hold:*

- (i) *the map $t \mapsto f(t, x, y)$ is measurable for all $(x, y) \in E^2$;*
- (ii) *the map $(x, y) \mapsto f(t, x, y)$ is continuous for almost all $t \in I$.*

DEFINITION 2 *A function $k: I \times I \times B \rightarrow E$ is L^1 -Carathéodory, if the following conditions hold:*

- (i) *the map $(t, s) \mapsto f(t, s, y)$ is measurable for all $y \in B$;*
- (ii) *the map $y \mapsto f(t, s, y)$ is continuous for almost all $(t, s) \in I^2$.*

In the proof of the main theorem in Section 1 we will apply the following fixed point theorem.

THEOREM 1 [15] *Let \mathcal{D} be a closed convex subset of E , and let F be a continuous map from \mathcal{D} into itself. If for some $x \in \mathcal{D}$ the implication*

$$\bar{V} = \overline{\text{conv}}(\{x\} \cup F(V)) \implies V \text{ is relatively compact,}$$

holds for every countable subset V of \mathcal{D} , then F has a fixed point.

In Section 2 we will apply the following theorem:

THEOREM 2 [10] *Let E be a metrizable locally convex topological vector space and let \mathcal{D} be a closed convex subset of E , and let F be a weakly sequentially continuous map of \mathcal{D} into itself. If for some $x \in \mathcal{D}$ the implication*

$$\bar{V} = \overline{\text{conv}}(\{x\} \cup F(V)) \implies V \text{ is relatively weakly compact,}$$

holds for every subset V of \mathcal{D} , then F has a fixed point.

2 AN EXISTENCE RESULT FOR INTEGRODIFFERENTIAL EQUATIONS

Observe that the problem (1) is equivalent to the integral equation

$$y(t) = y_0 + \int_0^t f\left(z, y(z), \int_0^z k(z, s, y(s)) ds\right) dz, \quad \text{for } t \in I. \quad (1')$$

Assume that

- (1) a function $a \in L^1[0, T]$,
- (2) $B = \{x: \|x\| \leq b, b = \|y_0\| + \int_0^T a(t) dt\}$,
- (3) k is a L^1 -Carathéodory function from $I^2 \times B$ into E ,
- (4) f is a L^1 -Carathéodory function from $I \times B \times B$ into E ,
- (5) $\|f(t, y(t), \int_0^t k(t, s, y(s)) ds)\| \leq a(t)$ almost everywhere on I for $y \in \tilde{B}$, where $\tilde{B} = \{y \in C[0, T]: \|y\| \leq b, b = \|y_0\| + \int_0^T a(t) dt\}$.

THEOREM 3 *Assume, that conditions (1)–(5) holds and in addition, that*

- (6) *there exists a constant c_1 such that $\alpha(f(t, A, C)) \leq c_1 \max\{\alpha(A), \alpha(C)\}$, for any subsets A, C of B ,*
- (7) *there exists an integrable function $c_2: I^2 \rightarrow R^+$ such that for every $t \in I$, $\varepsilon > 0$ and for every bounded subset X of B there exists a closed subset I_ε of I such that $\text{mes}(I \setminus I_\varepsilon) < \varepsilon$ and*

$$\alpha(k(t, T \times X)) \leq \sup_{s \in T} c_2(t, s) \alpha(X) \text{ for any compact subset } T \text{ of } I_\varepsilon.$$

- (8) *the zero function is the unique continuous solution of the inequality:*

$$p(t) \leq c_1 T \sup_{z \in I} \int_0^T c_2(z, s) p(s) ds \text{ on } I.$$

Then there exists at least one solution of problem (1).

Proof We define the operator $\mathbb{N}: C[0, T] \rightarrow C[0, T]$ by

$$\mathbb{N}y(t) = y_0 + \int_0^t f\left(z, y(z), \int_0^z k(z, s, y(s)) ds\right) dz.$$

We require that $N : \tilde{B} \rightarrow \tilde{B}$ is continuous. Because

(i)

$$\begin{aligned} \|Ny(t)\| &= \left\| y_0 + \int_0^t f\left(z, y(z), \int_0^z k(z, s, y(s)) \, ds\right) \, dz \right\| \\ &\leq \|y_0\| + \left\| \int_0^t f\left(z, y(z), \int_0^z k(z, s, y(s)) \, ds\right) \, dz \right\| \\ &\leq \|y_0\| + \int_0^t \left\| f\left(z, y(z), \int_0^z k(z, s, y(s)) \, ds\right) \right\| \, dz \\ &\leq \|y_0\| + \int_0^T a(t) \, dt = b \end{aligned}$$

so $Ny(t) \in B$, for $t \in I$.

Now we will show continuity of N .

(ii) Let $y_n \rightarrow y$ in $C[0, T]$. Then

$$\begin{aligned} \|Ny_n - Ny\| &= \sup_{t \in [0, T]} \left\| \int_0^t f\left(z, y_n(z), \int_0^z k(z, s, y_n(s)) \, ds\right) \, dz \right. \\ &\quad \left. - \int_0^t f\left(z, y(z), \int_0^z k(z, s, y(s)) \, ds\right) \, dz \right\| \\ &\leq \sup_{t \in [0, T]} \left\| \int_0^t \left[f\left(z, y_n(z), \int_0^z k(z, s, y_n(s)) \, ds\right) \right. \right. \\ &\quad \left. \left. - f\left(z, y(z), \int_0^z k(z, s, y(s)) \, ds\right) \right] \, dz \right\| \\ &\leq \sup_{t \in [0, T]} \int_0^t \left\| f\left(z, y_n(z), \int_0^z k(z, s, y_n(s)) \, ds\right) \right. \\ &\quad \left. - f\left(z, y(z), \int_0^z k(z, s, y(s)) \, ds\right) \right\| \, dz \\ &\leq \sup_{t \in [0, T]} \int_0^t \left\| f\left(z, y_n(z), \int_0^z k(z, s, y_n(s)) \, ds\right) \right. \\ &\quad \left. - f\left(z, y(z), \int_0^z k(z, s, y_n(s)) \, ds\right) \right\| \, dz \\ &\quad + \sup_{t \in [0, T]} \int_0^t \left\| f\left(z, y(z), \int_0^z k(z, s, y_n(s)) \, ds\right) \right. \\ &\quad \left. - f\left(z, y(z), \int_0^z k(z, s, y(s)) \, ds\right) \right\| \, dz. \end{aligned}$$

Because f and k are L^1 -Carathéodory functions and $\|y_n - y\| \rightarrow 0$ so $\|Ny_n - Ny\| \rightarrow 0$.

From (i) and (ii) follows that $N : \tilde{B} \rightarrow \tilde{B}$ is continuous.

Now we will show that the set $N(\tilde{B})$ is equicontinuous subset. This follows from inequality:

$$\begin{aligned} \|Ny(t) - Ny(\tau)\| &= \sup_{t \in [0, T]} \left\| \int_{\tau}^t f\left(z, y(z), \int_0^z k(z, s, y(s)) ds\right) dz \right\| \\ &\leq \sup_{t \in [0, T]} \left\| \int_{\tau}^t f\left(z, y(z), \int_0^z k(z, s, y(s)) ds\right) dz \right\| \\ &\leq \int_{\tau}^t a(z) dz \quad \text{for every } y \in B. \end{aligned}$$

Observe that the fixed point of the operator N is the solution of the problems (1) and (1'). Now we prove that fixed point of the operator N exists using fixed point Theorem 1.

Let $V \subset \tilde{B}$ be a countable set and $\bar{V} = \overline{\text{conv}}(N(V) \cup \{x\})$. Because V is an equicontinuous then $t \mapsto v(t) = \alpha(V(t))$ is continuous on I . Let $t \in I$ and $\varepsilon > 0$. Using the Lusin's theorem, there exists a compact subset I_ε of I such that $\text{mes}(I \setminus I_\varepsilon) < \varepsilon$ and a function $s \rightarrow c_2(t, s)$ is continuous on I_ε . We divide on interval $I = [0, T]$: $0 = t_0 < t_1 < \dots < t_n = T$, like this

$$\|c_2(t, s)v(r) - c_2(t, u)v(z)\| < \varepsilon \quad \text{for } s, r, u, z \in T_i = \mathcal{D}_i \cap I_\varepsilon,$$

where $\mathcal{D}_i = [t_{i-1}, t_i]$, $i = 1, 2, \dots, n$. Let $V_i = \{u(s) : u \in V, s \in \mathcal{D}_i\}$.

We notice

$$\begin{aligned} \alpha\left(\int_I k(t, s, V(s)) ds\right) &\leq \alpha\left(\int_{I_\varepsilon} k(t, s, V(s)) ds + \int_{I \setminus I_\varepsilon} k(t, s, V(s)) ds\right) \\ &\leq \alpha\left(\int_{I_\varepsilon} k(t, s, V(s)) ds\right) + \varepsilon_1, \end{aligned}$$

where $\varepsilon_1 \rightarrow 0$ if $\varepsilon \rightarrow 0$

and

$$\begin{aligned} \int_I k(z, s, V(s)) \, ds &\subset \sum_{i=1}^n \int_{T_i} k(z, s, V(s)) \, ds \\ &\subset \sum_{i=1}^n \text{mes } T_i \overline{\text{con } V} k(z, T_i \times V_i). \end{aligned}$$

Using the properties of measure of noncompactness α we have

$$\begin{aligned} \alpha \left(\int_I k(z, s, V(s)) \, ds \right) &\leq \sum_{i=1}^n \text{mes } T_i \alpha(k(z, T_i \times V_i)) \\ &\leq \sum_{i=1}^n \text{mes } T_i \sup_{s \in T_i} c_2(z, s) \alpha(V_i) \\ &= \sum_{i=1}^n \text{mes } T_i c_2(z, q_i) v(s_i), \end{aligned}$$

where $q_i \in T_i$, $s_i \in \mathcal{D}_i$.

Moreover, because $\|c_2(t, s)v(s) - c_2(t, q_i)v(s_i)\| < \varepsilon$ for $s \in T_i$ we have

$$\begin{aligned} &\sum_{i=1}^n \text{mes } T_i c_2(t, q_i) v(s_i) \\ &\leq \sum_{i=1}^n \text{mes } T_i \|c_2(t, q_i)v(s_i) - c_2(t, s_i)v(s_i)\| + \sum_{i=1}^n \text{mes } T_i c_2(t, s_i) v(s_i) \\ &\leq \varepsilon_2 + \sum_{i=1}^n \text{mes } T_i c_2(t, s_i) v(s_i), \end{aligned}$$

where $\varepsilon_2 \rightarrow 0$ if $\varepsilon \rightarrow 0$. So

$$\alpha \left(\int_I k(z, s, y(s)) \, ds \right) \leq \int_{I_\varepsilon} c_2(z, s) v(s) \, ds + \varepsilon_2$$

then, because $\varepsilon_2 \rightarrow 0$ if $\varepsilon \rightarrow 0$ so

$$\alpha \left(\int_I k(z, s, y(s)) \, ds \right) \leq \int_I c_2(z, s) v(s) \, ds.$$

Because $\bar{V} = \overline{\text{con}V}(N(V) \cup \{x\})$, then by the property of measure of noncompactness we have

$$\begin{aligned} \alpha(V(t)) &= \alpha(\overline{\text{con}V}(N(V(t)) \cup \{x\})) \leq \alpha(N(V(t))) \\ &\leq \alpha\left(\int_0^t f(z, V(z)), \int_0^z k(z, s, V(s)) \, ds\right) dz \\ &\leq \int_0^t \alpha\left(f(z, V(z)), \int_0^z k(z, s, V(s)) \, ds\right) dz \\ &\leq \int_0^t c_1 \cdot \max(\alpha(V(z)), \alpha\left(\int_0^z k(z, s, V(s)) \, ds\right)) dz \\ &\leq c_1 \cdot T \cdot \sup_{z \in I} \alpha\left(\int_0^z k(z, s, V(s)) \, ds\right) \\ &\leq c_1 \cdot T \cdot \sup_{z \in I} \int_I c_2(z, s)v(s) \, ds. \end{aligned}$$

So

$$v(t) \leq c_1 \cdot T \sup_{z \in I} \int_0^T c_2(z, s)v(s) \, ds.$$

By (8) we have that $v(t) = \alpha(V(t)) = 0$. Using Arzelá–Ascoli’s theorem we obtain that V is relatively compact. By Theorem 1 the operator N has a fixed point. This means that there exists a solution of problem (1).

Remark Theorem 1 extends the existence theorem from Meehan and O’Regan [13] and O’Regan [17].

3 AN EXISTENCE RESULT FOR INTEGRODIFFERENTIAL EQUATIONS IN WEAK SENSE

In this part we prove a theorem for the existence of pseudo-solutions to the Cauchy problem

$$\begin{aligned} y'(t) &= f\left(t, y(t), \int_0^t k(t, s, y(s)) \, ds\right), \\ y(0) &= y_0 \end{aligned} \tag{2}$$

in Banach spaces. Functions f and k will be assumed Pettis integrable but this assumption is not sufficient for the existence of solutions. We impose a weak compactness type condition expressed in terms of measures of weak noncompactness. Throughout this part $(E, \|\cdot\|)$ will

denote a real Banach space, E^* the dual space. Unless otherwise stated, we assume that “ \int ” denotes the Pettis integral.

A function $g : E \rightarrow E$ is said to be *weakly-weakly sequentially continuous* if for each weakly convergent sequence $(x_n) \subset E$, a sequence $(g(x_n))$ is weakly convergent in E .

Fix $x^* \in E^*$, and consider the equation

(9)

$$(x^*x)'(t) = x^*f\left(t, x(t), \int_0^t k(t, s, x(s)) \, ds\right), \quad t \in I.$$

Now, we can introduce the following definition:

DEFINITION 3 [6,8] *A function $x : I \rightarrow E$ is said to be a pseudo-solution of the Cauchy problem (2) if it satisfies the following conditions:*

- (i) $x(\cdot)$ is absolutely continuous,
- (ii) $x(0) = x_0$,
- (iii) for each $x^* \in E^*$ there exists a negligible set $A(x^*)$ (i.e. $\text{mes } A(x^*) = 0$), such that for each $t \notin A(x^*)$:

$$(x^*x)'(t) = x^*\left(f\left(t, x(t), \int_0^t k(t, s, y(s)) \, ds\right)\right).$$

In other words by a pseudo-solution of (2) we will understand an absolutely continuous function such that $x(0) = x_0$, and $x(\cdot)$ satisfies (2) a.e., for each $x^ \in E^*$.*

In this part we use a weak measure of noncompactness of de Blasi’s β . It is necessary to remark that the following lemma is true:

LEMMA 1 [9,14] *Let $\mathcal{H} \subset C_w(I, E)$ be a family of strongly equicontinuous functions. Then the function $t \mapsto v(t) = \beta(\mathcal{H}(t))$ is continuous and $\beta(\mathcal{H}(I)) = \sup\{\beta(\mathcal{H}(t)) : t \in I\}$.*

Assume that in addition to (1), (2), (5) and (6),

- (10) k is a Carathéodory’s weakly-weakly sequentially continuous function $I^2 \times B$ into E ;
- (11) f is Carathéodory’s weakly-weakly sequentially continuous function from $I \times B \times B$ into E ;
- (12) for any continuous function $y : I \rightarrow E$, functions $k(\cdot, \cdot, y(\cdot))$ and $f(\cdot, y(\cdot), \int_0^{\cdot} k(\cdot, s, y(s)) \, ds)$ are Pettis integrable.

THEOREM 4 Assume, in addition to (1), (2), (5) and (10–12) that

(13) there exists a constant c_3 such that for every interval $J \subset I$ and for any subsets A, C of B

$$\beta(f(J, A, C)) \leq c_3 \max\{\beta(A), \beta(C)\},$$

(14) there exists an integrable function $c_4 : I \rightarrow R^+$ such that for every $t \in I$, $\varepsilon > 0$ and for every bounded subset X of B there exists a closed subset I_ε of I such that $\text{mes}(I \setminus I_\varepsilon) < \varepsilon$ and

$$\beta(k(J, J \times X)) \leq \sup_{s \in J} c_4(s) \beta(X), \quad \text{for any } J \subset I.$$

Then there exists at least one pseudo-solution of the problem (2).

Proof We define the operator $G : C[0, T] \rightarrow C[0, T]$ by

$$Gy(t) = y_0 + \int_0^t f(z, y(z), \int_0^z k(z, s, y(s)) ds) dz.$$

We require that $G : \tilde{B} \rightarrow \tilde{B}$ is weakly sequentially continuous, where

$$\tilde{B} = \left\{ y \in C[0, T] : \|y\| \leq b, b = \|y_0\| + \int_0^T a(t) dt \right\}.$$

Because

(i) For any $y^* \in E^*$ such that $\|y^*\| \leq 1$ and for any $y \in B$,

$$\begin{aligned} & \left| y^* \left[f \left(z, y(z), \int_0^z k(z, s, y(s)) ds \right) \right] \right| \\ & \leq \|y^*\| \left\| f \left(z, y(z), \int_0^z k(z, s, y(s)) ds \right) \right\| \\ & \leq \left\| f \left(z, y(z), \int_0^z k(z, s, y(s)) ds \right) \right\| \leq a(z) \end{aligned}$$

so

$$\begin{aligned} |y^* Gy(t)| & \leq |y^* y_0| + \int_0^t \left| y^* \left[f \left(z, y(z), \int_0^z k(z, s, y(s)) ds \right) \right] \right| dz \\ & \leq \|y_0\| + \int_0^t a(t) dt \leq \|y_0\| + \int_0^T a(t) dt = b. \end{aligned}$$

From here

$$\sup\{|y^*Gy(t)|: y^* \in E^*, \|y^*\| \leq 1\} \leq b \text{ and } \|Gy(t)\| \leq b$$

so $Gy(t) \in B$.

- (ii) Now we will show that set $G(\tilde{B})$ is strongly equicontinuous subset. This follows from the inequality

$$\begin{aligned} & |y^*[Gy(t) - Gy(\tau)]| \\ &= \left| y^* \left[\int_{\tau}^t f(z, y(z), \int_0^z k(z, s, y(s)) ds) dz \right] \right| \\ &\leq \int_{\tau}^t \left| y^* f(z, y(z), \int_0^z k(z, s, y(s)) ds) \right| dz \leq \int_{\tau}^t a(z) dz. \end{aligned}$$

- (iii) Now we will show weakly sequentially continuity of G .

Let $y_n \rightarrow y$ in $(C[0, T], \omega)$.

Then

$$\begin{aligned} |y^*[Gy_n(t) - Gy(t)]| &= \left| y^* \left[\int_0^t f(z, y_n(z), \int_0^z k(z, s, y_n(s)) ds) dz \right. \right. \\ &\quad \left. \left. - \int_0^t f(z, y(z), \int_0^z k(z, s, y(s)) ds) dz \right] \right| \\ &\leq \int_0^t \left| y^* \left[f(z, y_n(z), \int_0^z k(z, s, y_n(s)) ds) \right. \right. \\ &\quad \left. \left. - f(z, y(z), \int_0^z k(z, s, y_n(s)) ds) \right] \right| dz \\ &\quad + \int_0^t \left| y^* \left[f(z, y(z), \int_0^z k(z, s, y_n(s)) ds) \right. \right. \\ &\quad \left. \left. - f(z, y(z), \int_0^z k(z, s, y(s)) ds) \right] \right| dz \\ &\leq \int_0^T \left| y^* \left[f(z, y_n(z), \int_0^z k(z, s, y_n(s)) ds) \right. \right. \\ &\quad \left. \left. - f(z, y(z), \int_0^z k(z, s, y_n(s)) ds) \right] \right| dz \\ &\quad + \int_0^T \left| y^* \left[f(z, y(z), \int_0^z k(z, s, y_n(s)) ds) \right. \right. \\ &\quad \left. \left. - f(z, y(z), \int_0^z k(z, s, y(s)) ds) \right] \right| dz. \end{aligned}$$

Because f and k are L^1 -Carathéodory functions and $y_n \rightarrow y$ in $(C[0, T], \omega)$ so

$$|y^*[Gy_n(t) - Gy(t)]| \rightarrow 0.$$

From here

$$\sup\{y^*[Gy_n(t) - Gy(t)]: y^* \in E^*, \|y^*\| \leq 1\} \rightarrow 0.$$

From (i) and (iii), follows that $G: \tilde{B} \rightarrow \tilde{B}$ is weakly-weakly sequentially continuous.

Observe that the fixed point of the operator G is the pseudo-solution of the problem

$$y(t) = y_0 + \int_0^t f\left(z, y(z), \int_0^z k(z, s, y(s)) ds\right) dz. \quad (2')$$

Now we prove that fixed point of the operator G exists using fixed point Theorem 2.

Let $V \subset \tilde{B}$ be a countable set and $\bar{V} = \overline{\text{conv}}(G(V) \cup \{0\})$. Because V is equicontinuous then $t \rightarrow v(t) = \beta(V(t))$ is continuous on I (by Lemma 1).

Let $t \in I$ and $\varepsilon > 0$. Using the Luzin's theorem, there exists a compact subset I_ε of I such that $\text{mes}(I \setminus I_\varepsilon) < \varepsilon$ and a function $s \rightarrow c_4(s)$ is continuous. We divide an interval $I = [0, T]: 0 = t_0 < t_1 < \dots < t_n = T$, like this $\|c_4(s)v(r) - c_4(u)v(z)\| < \varepsilon$ for $s, r, u, z \in T = \mathcal{D}_i \cap I_\varepsilon$, where $\mathcal{D}_i = [t_{i-1}, t_i]$.

We notice

$$\begin{aligned} & \beta\left(\int_I f\left(z, V(z), \int_0^z k(t, s, V(s)) ds\right) dz\right) \\ & \leq \beta\left(\int_{I_\varepsilon} f\left(z, V(z), \int_0^z k(t, s, V(s)) ds\right) dz\right) \\ & \quad + \beta\left(\int_{I \setminus I_\varepsilon} f\left(z, V(z), \int_0^z k(t, s, V(s)) ds\right) dz\right) \\ & \leq \beta\left(\int_{I_\varepsilon} f\left(z, V(z), \int_0^z k(t, s, V(s)) ds\right) dz\right) + \varepsilon'. \end{aligned}$$

Using the properties of weak measure of noncompactness β we have

$$\begin{aligned}
 & \beta\left(\int_{I_\varepsilon} f\left(z, V(z), \int_0^z k(t, s, V(s)) \, ds\right) \, dz\right) \\
 & \leq \beta\left(\sum_{i=1}^n \text{mes } T_i \overline{\text{conv}} f\left(T_i, V(T_i), \sum_{i=1}^n \text{mes } T_i \overline{\text{conv}} k(t_i, T_i, V_i)\right)\right) \\
 & \leq \sum_{i=1}^n \text{mes } T_i \beta\left(f\left(T_i, V(T_i), \sum_{i=1}^n \text{mes } T_i \overline{\text{conv}} k(T_i, T_i, V_i)\right)\right) \\
 & \leq \sum_{i=1}^n \text{mes } T_i c_3 \cdot \max \beta(V(T_i)), \beta\left(\sum_{i=1}^n \text{mes } T_i \overline{\text{conv}} k(T_i, T_i, V_i)\right) \\
 & \leq \sum_{i=1}^n \text{mes } T_i c_3 \sum_{i=1}^n \text{mes } T_i \beta(k(T_i, T_i, V_i)) \\
 & \leq Tc_3 \sum_{i=1}^n \text{mes } T_i \sup_{s \in T_i} c_4(s) \beta(V_i) \\
 & = Tc_3 \sum_{i=1}^n \text{mes } T_i c_4(s_i) \beta(V(T_i)) \\
 & = Tc_3 \left[\sum_{i=1}^n \text{mes } T_i c_4(t_i) \beta(V(t_i)) \right. \\
 & \quad \left. + \sum_{i=1}^n \text{mes } T_i [c_4(s_i) \beta(V(t_i)) - c_4(t_i) \beta(V(t_i))] \right]
 \end{aligned}$$

From here

$$\begin{aligned}
 & \beta\left(\int_I f\left(z, V(z), \int_0^z k(z, s, V(s)) \, ds\right) \, dz\right) \\
 & \leq Tc_3 \int_0^t c_4(s) \beta(V(s)) \, ds + \varepsilon_2,
 \end{aligned}$$

Because $\varepsilon_2 \rightarrow 0$ if $\varepsilon \rightarrow 0$ we have

$$\begin{aligned}
 & \beta(V(t)) \leq \beta(G(V(t))) \\
 & \leq \beta\left(\int_0^t f\left(z, y(z), \int_0^z k(z, s, y(s)) \, ds\right) \, dz\right) \\
 & \leq Tc_3 \int_0^t c_4(s) v(s) \, ds.
 \end{aligned}$$

So

$$v(t) \leq Tc_3 \int_0^t c_4(s)\beta(V(s)) ds.$$

By Gronwall's inequality we have that $v(t) = \beta(V(t)) = 0$.

Using Arzelá–Ascoli's theorem we obtain that V is weakly relatively compact.

By Theorem 2 the operator G has a fixed point. This means that there exists a pseudo-solution of problem (2).

Remark Theorem 4 extends the existence theorems from Krzyńska [12], Cichoń [6], O'Regan [16] and others.

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