



**UPPER AND LOWER SOLUTIONS METHOD FOR DISCRETE INCLUSIONS
WITH NONLINEAR BOUNDARY CONDITIONS**

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ABSTRACT. In this note the concept of lower and upper solutions combined with the nonlinear alternative of Leray-Schauder type is used to investigate the existence of solutions for first order discrete inclusions with nonlinear boundary conditions.

Key words and phrases: Discrete Inclusions, Convex valued multivalued map, Fixed point, Upper and lower solutions, Nonlinear boundary conditions.

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1. INTRODUCTION

This note is concerned with the existence of solutions for the discrete boundary multivalued problem

$$(1.1) \quad \Delta y(i-1) \in F(i, y(i)), \quad i \in [1, T] = \{1, 2, \dots, T\},$$

$$(1.2) \quad L(y(0), y(T+1)) = 0,$$

where $F : \mathbb{N} \times \mathbb{R} \longrightarrow \mathcal{P}(\mathbb{R})$ is a compact convex valued multivalued map and $L : \mathbb{N}^2 \rightarrow \mathbb{R}$ is a nonlinear single-valued map.

Very recently Agarwal *et al* [3] applied the concept of upper and lower solutions combined with the Leray-Schauder nonlinear alternative to a class of second order discrete inclusions subjected to Dirichlet conditions. For more details on recent results and applications of difference equations we recommend for instance the monographs by Agarwal *et al* [1], [2], Pachpatte [9] and the references cited therein.

In this note we shall apply the same tool as in [3] to first order discrete inclusions with nonlinear boundary conditions which include the initial, terminal and periodic conditions. The corresponding problem for differential inclusions was studied by Benchohra and Ntouyas in [4].

2. PRELIMINARIES

In this section, we introduce notation, definitions, and preliminary facts which are used throughout the note. $C([0, T], \mathbb{R})$ is the Banach space of all continuous functions from $[0, T]$ (discrete topology) into \mathbb{R} with the norm $\|y\| = \sup_{k \in [0, T]} |y(k)|$. Let $(X, |\cdot|)$ be a Banach space. A multivalued map $G : X \longrightarrow \mathcal{P}(X)$ has convex (closed) values if $G(x)$ is convex (closed) for all $x \in X$. G is bounded on bounded sets if $G(B)$ is bounded in X for each bounded set B of X (i.e. $\sup_{x \in B} \{\sup\{|y| : y \in G(x)\}\} < \infty$).

G is called upper semicontinuous (u.s.c.) on X if for each $x_0 \in X$ the set $G(x_0)$ is a nonempty, closed subset of X , and if for each open set N of X containing $G(x_0)$, there exists an open neighbourhood M of x_0 such that $G(M) \subseteq N$. G is said to be completely continuous if $G(B)$ is relatively compact for every bounded subset $B \subseteq X$.

If the multivalued G is completely continuous with nonempty compact values, then G is u.s.c. if and only if G has a closed graph (i.e. $x_n \longrightarrow x_*$, $y_n \longrightarrow y_*$, $y_n \in G(x_n)$ imply $y_* \in G(x_*)$). G has a fixed point if there is $x \in X$ such that $x \in G(x)$.

For more details on multivalued maps see the books of Deimling [5] and Hu and Papageorgiou [7].

Let us start by defining what we mean by a solution of problem (1.1) – (1.2).

Definition 2.1. A function $y \in C([0, T], \mathbb{R})$, is said to be a solution of (1.1) – (1.2) if y satisfies the inclusion $\Delta y(i-1) \in F(i, y(i))$ on $\{1, \dots, T\}$ and the condition $L(y(0), y(T+1)) = 0$.

For any $y \in C([0, T], \mathbb{R})$ we define the set

$$S_{F,y} = \{v \in C([0, T], \mathbb{R}) : v(i) \in F(i, y(i)) \text{ for } i \in \{1, \dots, T\}\}.$$

Definition 2.2. A function $\alpha \in C([0, T+1], \mathbb{R})$ is said to be a lower solution of (1.1) – (1.2) if for each $i \in [0, T+1]$ there exists $v_1(i) \in F(i, \alpha(i))$ with $\Delta \alpha(i-1) \leq v_1(i)$ and $L(\alpha(0), \alpha(T+1)) \leq 0$.

Similarly a function $\beta \in C([0, T+1], \mathbb{R})$ is said to be an upper solution of (1.1) – (1.2) if for each $i \in [0, T+1]$ there exists $v_2(i) \in F(i, \beta(i))$ with $\Delta \beta(i-1) \geq v_2(i)$ and $L(\beta(0), \beta(T+1)) \geq 0$.

Our existence result in the next section relies on the following fixed point principle.

Lemma 2.1 (Nonlinear Alternative [6]). *Let X be a Banach space with $C \subset X$ convex. Assume U is an open subset of C with $0 \in U$ and $G : \bar{U} \rightarrow \mathcal{P}(C)$ is a compact multivalued map, u.s.c. with convex closed values. Then either,*

- (i) G has a fixed point in \bar{U} ; or
- (ii) there is a point $u \in \partial U$ and $\lambda \in (0, 1)$ with $u \in \lambda G(u)$.

3. MAIN RESULT

We are now in a position to state and prove our existence result for the problem (1.1) – (1.2). We first list the following hypotheses:

- (H1) $y \mapsto F(i, y)$ is upper semicontinuous for all $i \in [1, T]$;
- (H2) for each $q > 0$, there exists $\phi_q \in C([1, T], \mathbb{R}_+)$ such that

$$\|F(i, y)\| = \sup\{|v| : v \in F(i, y)\} \leq \phi_q(i) \quad \text{for all } |y| \leq q \text{ and } i \in [1, T];$$

- (H3) there exist α and $\beta \in C([0, T + 1], \mathbb{R})$, lower and upper solutions for the problem (1.1) – (1.2) such that $\alpha \leq \beta$;
- (H4) L is a continuous single-valued map in $(x, y) \in [\alpha(0), \beta(0)] \times [\alpha(T + 1), \beta(T + 1)]$ and nonincreasing in $y \in [\alpha(T + 1), \beta(T + 1)]$.

Theorem 3.1. *Assume that hypotheses (H1) – (H4) hold. Then the problem (1.1) – (1.2) has at least one solution y such that*

$$\alpha(i) \leq y(i) \leq \beta(i) \quad \text{for all } i \in [1, T].$$

Proof. Transform the problem (1.1) – (1.2) into a fixed point problem. Consider the following modified problem

$$(3.1) \quad \Delta y(i - 1) + y(i) \in F_1(i, y(i)), \quad \text{on } [1, T]$$

$$(3.2) \quad y(0) = \tau(0, y(0) - L(\bar{y}(0), \bar{y}(T + 1))),$$

where

$$F_1(i, y) = F(i, \tau(i, y)) + \tau(i, y),$$

$$\tau(i, y) = \max(\alpha(i), \min(y, \beta(i)))$$

and

$$\bar{y}(i) = \tau(i, y).$$

A solution to (3.1) – (3.2) is a fixed point of the operator $N : C([1, T], \mathbb{R}) \longrightarrow \mathcal{P}(C([1, T], \mathbb{R}))$ defined by:

$$N(y) = \left\{ h \in C([1, T]) : h(k) = y(0) + \sum_{0 < l < k} [g(l) + \bar{y}(l)] - \sum_{0 < l < k} y(l), \quad g \in \tilde{S}_{F, \bar{y}}^1 \right\},$$

where

$$\tilde{S}_{F, \bar{y}}^1 = \{v \in S_{F, \bar{y}}^1 : v(i) \geq v_1(i) \text{ a.e. on } A_1 \text{ and } v(i) \leq v_2(i) \text{ on } A_2\},$$

$$S_{F, \bar{y}}^1 = \{v \in C([1, T]) : v(i) \in F(i, (\bar{y})(i)) \text{ for } i \in [1, T]\},$$

$$A_1 = \{i \in [1, T] : y(i) < \alpha(i) \leq \beta(i)\}, \quad A_2 = \{i \in [1, T] : \alpha(i) \leq \beta(i) < y(i)\}.$$

Remark 3.2. Notice that F_1 is an upper semicontinuous multivalued map with compact convex values, and there exists $\phi \in C([1, T], \mathbb{R}^+)$ such that

$$\|F_1(i, y)\| \leq \phi(i) + \max \left(\sup_{i \in [1, T]} |\alpha(i)|, \sup_{i \in [1, T]} |\beta(i)| \right).$$

We shall show that N satisfies the assumptions of Lemma 2.1. The proof will be given in several steps.

Step 1: $N(y)$ is convex for each $y \in C([1, T], \mathbb{R})$.

Indeed, if h_1, h_2 belong to $N(y)$, then there exist $g_1, g_2 \in \tilde{S}_{F, \bar{y}}^1$ such that for each $k \in [1, T]$ we have

$$h_i(k) = y(0) + \sum_{0 < l < k} [g_i(l) + \bar{y}(l)] - \sum_{0 < l < k} y(l), \quad i = 1, 2.$$

Let $0 \leq d \leq 1$. Then for each $k \in [1, T]$ we have

$$(dh_1 + (1-d)h_2)(k) = y(0) + \sum_{0 < l < k} [dg_1(l) + (1-d)g_2(l) + \bar{y}(l)] - \sum_{0 < l < k} y(l).$$

Since $\tilde{S}_{F_1, \bar{y}}^1$ is convex (because F_1 has convex values) then

$$dh_1 + (1-d)h_2 \in N(y).$$

Step 2: N maps bounded sets into bounded sets in $C([1, T], \mathbb{R})$.

Indeed, it is enough to show that for each $q > 0$ there exists a positive constant ℓ^* such that for each $y \in B_q = \{y \in C([1, T], \mathbb{R}) : \|y\|_\infty \leq q\}$ one has $\|N(y)\|_\infty \leq \ell^*$.

Let $y \in B_q$ and $h \in N(y)$ then there exists $g \in \tilde{S}_{F, \bar{y}}^1$ such that for each $k \in [1, T]$ we have

$$h(k) = y(0) + \sum_{0 < l < k} [g(l) + \bar{y}(l)] - \sum_{0 < l < k} y(l).$$

By (H2) we have for each $i \in [1, T]$

$$\begin{aligned} |h(k)| &\leq |y(0)| + \sum_{l=1}^k |g(l)| + \sum_{l=1}^k |\bar{y}(l)| + \sum_{l=1}^k |y(l)| \\ &\leq \max(|\alpha(0)|, |\beta(0)|) + k\|\phi_q\|_\infty \\ &\quad + k \max \left(q, \sup_{i \in [1, T]} |\alpha(i)|, \sup_{i \in [1, T]} |\beta(i)| \right) + kq := \ell^*. \end{aligned}$$

Step 3: N maps bounded set into equicontinuous sets of $C([1, T], \mathbb{R})$.

Let $k_1, k_2 \in [1, T]$, $k_1 < k_2$ and B_q be a bounded set of $C([1, T])$ as in Step 2. Let $y \in B_q$ and $h \in N(y)$ then there exists $g \in \tilde{S}_{F, \bar{y}}^1$ such that for each $k \in [1, T]$ we have

$$h(k) = y(0) + \sum_{0 < l < k} [g(l) + \bar{y}(l)] - \sum_{0 < l < k} y(l).$$

Then

$$|h(k_2) - h(k_1)| \leq \sum_{k_1 < l < k_2} [|g(l)| + |\bar{y}(l)|] + \sum_{k_1 < l < k_2} |y(l)|.$$

As $k_2 \rightarrow k_1$ the right-hand side of the above inequality tends to zero.

As a consequence of Steps 1 to 3 together with the Arzelá-Ascoli theorem we can conclude that $N : C([1, T], \mathbb{R}) \rightarrow \mathcal{P}(C([1, T], \mathbb{R}))$ is a completely continuous multivalued map.

Step 4: *A priori bounds on solutions exist.*

Let $y \in C([1, T], \mathbb{R})$ and $y \in \lambda N(y)$ for some $\lambda \in (0, 1)$. Then

$$y(k) = \lambda \left(y(0) - \sum_{0 < l < k} y(l) + \sum_{0 < l < k} [g(l) + \bar{y}(l)] \right).$$

Hence

$$\begin{aligned} |y(k)| &\leq |y(0)| + \sum_{l=1}^k |g(l)| + \sum_{l=1}^k |\bar{y}(l)| + \sum_{l=1}^k |y(l)| \\ &\leq \max(|\alpha(0)|, |\beta(0)|) + T\|\phi\|_\infty \\ &\quad + T \max \left(\sup_{i \in [1, T]} |\alpha(i)|, \sup_{i \in [1, T]} |\beta(i)| \right) + 2 \sum_{l=1}^k |y(l)|. \end{aligned}$$

Using the Pachpatte inequality (see [9, Theorem 2.5]) we get for each $k \in [1, T]$

$$|y(k)| \leq c_* \left[1 + 2 \sum_{l=1}^T \prod_{s=1}^{l-1} 2 \right],$$

where

$$c_* = \max(|\alpha(0)|, |\beta(0)|) + T\|\phi\|_\infty + T \max \left(\sup_{i \in [1, T]} |\alpha(i)|, \sup_{i \in [1, T]} |\beta(i)| \right).$$

Thus

$$\|y\|_\infty \leq c_*(1 + T2^{T+1}) := M.$$

Set

$$U = \{y \in C([1, T], \mathbb{R}) : \|y\|_\infty < M + 1\}.$$

As in Step 3 the operator $N : \bar{U} \rightarrow \mathcal{P}(C([1, T], \mathbb{R}))$ is continuous and completely continuous.

Step 5: N has a closed graph.

Let $y_n \in U \rightarrow y_*$, $h_n \in N(y_n)$, and $h_n \rightarrow h_*$. We shall prove that $h_* \in N(y_*)$.

$h_n \in N(y_n)$ means that there exists $g_n \in \tilde{S}_{F, \bar{y}_n}^1$ such that for each $t \in J$

$$h_n(i) = y_n(0) + \sum_{0 < l < i} [g_n(l) + \bar{y}_n(l)] - \sum_{0 < l < i} y_n(l).$$

We must prove that there exists $g_* \in \tilde{S}_{F, \bar{y}_*}^1$ such that for each $k \in [1, T]$

$$h_*(i) = y_*(0) + \sum_{0 < l < i} [g_*(l) + \bar{y}_*(l)] - \sum_{0 < l < i} y_*(l).$$

Since $y_n \in \bar{U}$, $k \in \mathbb{N}$, then (H2) guarantees (see [2, p. 262]) that there exists a compact set Ω of $C([1, T], \mathbb{R})$ with $\{g_n\} \in \Omega$. Thus there exists a subsequence $\{y_{n_m}\}$ with $y_{n_m} \rightarrow y_*$ as $k \rightarrow \infty$ and $y_{n_m}(i) \in F(i, y_{n_m}(i))$ together with the map $y \rightarrow F(i, y)$ upper semicontinuous for each $i \in \mathbb{N}$. Since τ and y are continuous, we have

$$\begin{aligned} &\left\| \left(h_n - y_n(0) - \sum_{0 < l < i} [\bar{y}_n(l) - y_n(l)] \right) \right. \\ &\quad \left. - \left(h_* - y_*(0) - \sum_{0 < l < i} [\bar{y}_*(l) - y_*(l)] \right) \right\|_\infty \rightarrow 0, \text{ as } n \rightarrow \infty. \end{aligned}$$

Consider the linear continuous operator (topology on \mathbb{N} is the discrete topology)

$$\begin{aligned}\Gamma : C([1, T], \mathbb{R}) &\longrightarrow C([1, T], \mathbb{R}) \\ g &\longmapsto (\Gamma g)(i) = \sum_{0 < l < i} g(l).\end{aligned}$$

Moreover, we have that

$$\left(h_n(i) - y_n(0) - \sum_{0 < l < i} [\bar{y}_n(l) - y_n(l)] \right) = \Gamma(g_n)(i) \in F_1(i, y_n(i)).$$

Since $y_n \longrightarrow y_*$, it that

$$\left(h_*(i) - y_*(0) - \sum_{0 < l < i} [\bar{y}_*(l) - y_*(l)] \right) = \sum_{0 < l < i} g_*(l)$$

for some $g_* \in \tilde{S}_{F, y_*}^1$.

Lemma 2.1 guarantees that N has a fixed point which is a solution to problem (3.1) – (3.2).

Step 6: *The solution y of (3.1) – (3.2) satisfies*

$$\alpha(i) \leq y(i) \leq \beta(i) \text{ for all } i \in J.$$

Let y be a solution to (3.1) – (3.2). We prove that

$$y(i) \leq \beta(i) \text{ for all } i \in [1, T].$$

Assume that $y - \beta$ attains a positive maximum on $[1, T]$ at $\bar{k} - 1 \in [1, T]$ that is,

$$(y - \beta)(\bar{k}) = \max\{y(k) - \beta(k) : k \in [1, T]\} > 0.$$

By the definition of τ one has

$$\Delta y(\bar{k}) + y(\bar{k}) \in F(t, \beta(\bar{k})) + \beta(\bar{k}).$$

Thus there exists $v(i) \in F(\bar{k}, \beta(\bar{k}))$, with $v(\bar{k}) \leq v_2(\bar{k})$ such that

$$\Delta y(\bar{k} - 1) = v(\bar{k}) + \beta(\bar{k} - 1) - y(\bar{k}),$$

$$\begin{aligned}\Delta y(\bar{k} - 1) &= v(\bar{k}) - y(\bar{k}) + \beta(\bar{k}) \\ &\leq v_2(\bar{k}) - (y(\bar{k}) - \beta(\bar{k})) < v_2(\bar{k}).\end{aligned}$$

Using the fact that β is an upper solution to (1.1) – (1.2) the above inequality yields

$$\begin{aligned}\beta(\bar{k}) - \beta(\bar{k} - 1) &\geq v_2(\bar{k}) \\ &> y(\bar{k}) - y(\bar{k} - 1).\end{aligned}$$

Thus we obtain the contradiction

$$y(\bar{k} - 1) - \beta(\bar{k} - 1) > y(\bar{k}) - \beta(\bar{k}).$$

Thus

$$y(i) \leq \beta(i) \text{ for all } i \in [1, T].$$

Analogously, we can prove that

$$y(i) \geq \alpha(i) \text{ for all } i \in [1, T].$$

This shows that the problem (3.1) – (3.2) has a solution in the interval $[\alpha, \beta]$.

Finally, we prove that every solution of (3.1) – (3.2) is also a solution to (1.1) – (1.2). We only need to show that

$$\alpha(0) \leq y(0) - L(\bar{y}(0), \bar{y}(T + 1)) \leq \beta(0).$$

Notice first that we can prove

$$\alpha(T+1) \leq y(T+1) \leq \beta(T+1).$$

Suppose now that $y(0) - L(\bar{y}(0), \bar{y}(T+1)) < \alpha(0)$. Then $y(0) = \alpha(0)$ and

$$y(0) - L(\alpha(0), \bar{y}(T)) \leq \alpha(0).$$

Since L is nonincreasing in y , we have

$$\alpha(0) \leq \alpha(0) - L(\alpha(0), \alpha(T+1)) \leq \alpha(0) - L(\alpha(0), \bar{y}(T+1)) < \alpha(0),$$

which is a contradiction. Analogously, we can prove that

$$y(0) - L(\bar{y}(0), \bar{y}(T+1)) \leq \beta(0).$$

Then y is a solution to (1.1) – (1.2). □

Remark 3.3. Observe that if $L(x, y) = ax - by - c$, then Theorem 3.1 gives an existence result for the problem

$$\begin{aligned} \Delta y(i) &\in F(i, y(i)), & i \in [1, T] = \{1, 2, \dots, T\}, \\ ay(0) - by(T) &= c, \end{aligned}$$

with $a, b \geq 0$, $a + b > 0$, which includes the periodic case ($a = b = 1$, $c = 0$) and the initial and the terminal problem.

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