

I. RAMISHVILI

FORMULAS OF VARIATION OF SOLUTION FOR QUASI-LINEAR
CONTROLLED NEUTRAL DIFFERENTIAL EQUATIONS

(Reported on March 17, 2003)

Let $J = [a, b]$ be a finite interval, $O \subset R^n$, $G \subset R^r$ be open sets. Let the function $f : J \times O^s \times G \rightarrow R^n$ satisfy the following conditions: for almost all $t \in J$ the function $f(t, \cdot) : O^s \times G \rightarrow R^n$ is continuously differentiable; for any $(x_1, \dots, x_s, u) \in O^s \times G$ the functions $f(t, x_1, \dots, x_s, u)$, $f_{x_i}(\cdot)$, $i = 1, \dots, s$, $f_u(\cdot)$ are measurable on J ; for arbitrary compacts $K \subset O$, $N \subset G$ there exists a function $m_{K,N}(\cdot) \in L(J, R_+)$, $R_+ = [0, \infty)$, such that for any $(x_1, \dots, x_s, u) \in K^s \times N$ and for almost all $t \in J$, the following inequality is fulfilled

$$|f(t, x_1, \dots, x_s, u)| + \sum_{i=1}^s |f_{x_i}(\cdot)| + |f_u(\cdot)| \leq m_{K,N}(t).$$

Let the scalar functions $\tau_i(t)$, $i = 1, \dots, s$, $t \in R$, and $\eta_j(t)$, $j = 1, \dots, k$, be absolutely continuous and continuously differentiable, respectively, and satisfying the conditions: $\tau_i(t) \leq t$, $\dot{\tau}_i(t) > 0$, $i = 1, \dots, s$, $\eta_j(t) < t$, $\dot{\eta}_j(t) > 0$, $j = 1, \dots, k$. Let Φ be the set of continuously differentiable functions $\varphi : J_1 = [\tau, b] \rightarrow O$, $\tau = \min\{\eta_1(a), \dots, \eta_k(a), \tau_1(a), \dots, \tau_s(a)\}$, $\|\varphi\| = \sup\{|\varphi(a)| + |\dot{\varphi}(t)| : t \in J\}$. Ω be the set of measurable functions $u : J \rightarrow G$, satisfying the condition $cl\{u(t) : t \in J\}$ is a compact lying in G , $\|u\| = \sup\{|u(t)| : t \in J\}$; $A_i(t)$, $t \in J$, $i = 1, \dots, k$, be continuous matrix functions with dimensions $n \times n$.

To every element $\mu = (t_0, x_0, \varphi, u) \in E = J \times O \times \Phi \times \Omega$ let us correspond the differential equation

$$\dot{x}(t) = \sum_{j=1}^k A_j(t)x(\eta_j(t)) + f(t, x(\tau_1(t)), \dots, x(\tau_s(t)), u(t)), \quad (1)$$

with discontinuous initial condition

$$x(t) = \varphi(t), \quad t \in [\tau, t_0], \quad x(t_0) = x_0. \quad (2)$$

Definition 1. Let $\mu = (t_0, x_0, \varphi, u) \in E$, $t_0 < b$. The function $x(t) = x(t; \mu) \in O$, $t \in [\tau, t_1]$, $t_1 \in (t_0, b]$ is said to be a solution corresponding to the element $\mu \in E$, defined on the interval $[\tau, t_1]$, if on the interval $[\tau, t_0]$ the function $x(t)$ satisfies the condition (2), while on the interval $[t_0, t_1]$ it is absolutely continuous and almost everywhere satisfies the equation (1).

Let us introduce the set of variation:

$$V = \{\delta\mu = (\delta t_0, \delta x_0, \delta\varphi, \delta u) \in E - \tilde{\mu} : |\delta t_0| \leq c, |\delta x_0| \leq c, \|\delta\varphi\| \leq c, \|\delta u\| \leq c\},$$

where $\tilde{\mu} \in E$ is a fixed element, $c > 0$ is a fixed number.

Let $\tilde{x}(t)$ be a solution corresponding to the element $\tilde{\mu} = (\tilde{t}_0, \tilde{x}_0, \tilde{\varphi}, \tilde{u}) \in E$, defined on the interval $[\tau, \tilde{t}_1]$, $\tilde{t}_i \in (a, b)$, $i = 0, 1$. There exist numbers $\varepsilon_1 > 0$, $\delta_1 > 0$, such that for an arbitrary $(\varepsilon, \delta\mu) \in [0, \varepsilon_1] \times V$ to the element $\tilde{\mu} + \varepsilon\delta\mu \in E$ there corresponds a solution $x(t; \tilde{\mu} + \varepsilon\delta\mu)$ defined on $[\tau, \tilde{t}_1 + \delta_1]$.

2000 Mathematics Subject Classification. 34K40.

Key words and phrases. Neutral differential equation, variation of solution.

Due to uniqueness, the solution $x(t; \bar{\mu})$ is a continuation of the solution $\bar{x}(t)$ to the interval $[\tau, \bar{t}_1 + \delta_1]$. Therefore the solution $\bar{x}(t)$ is assumed to be defined on the interval $[\tau, \bar{t}_1 + \delta_1]$.

Let us define the increment of the solution $\bar{x}(t) = x(t; \bar{\mu})$

$$\Delta x(t; \varepsilon \delta \mu) = x(t; \bar{\mu} + \varepsilon \delta \mu) - \bar{x}(t), \quad (t, \varepsilon, \delta \mu) \in [\tau, \bar{t}_1 + \delta_1] \times [0, \varepsilon_1] \times V.$$

In order to formulate the main results, we will need the following notation:

$$\begin{aligned} \sigma_i &= (\bar{t}_0, \underbrace{\bar{x}_0, \dots, \bar{x}_0}_i, \underbrace{\bar{\varphi}(\bar{t}_0), \dots, \bar{\varphi}(\bar{t}_0)}_{(p-i)}, \bar{\varphi}(\tau_{p+1}(\bar{t}_0)), \dots, \bar{\varphi}(\tau_s(\bar{t}_0))), \quad i = 0, \dots, p; \\ \sigma_i &= (\gamma_i, \bar{x}(\tau_1(\gamma_i)), \dots, \bar{x}(\tau_{i-1}(\gamma_i)), \bar{x}_0, \bar{\varphi}(\tau_{i+1}(\gamma_i)), \dots, \bar{\varphi}(\tau_s(\gamma_i))), \\ \sigma_i^0 &= (\gamma_i, \bar{x}(\tau_1(\gamma_i)), \dots, \bar{x}(\tau_{i-1}(\gamma_i)), \bar{\varphi}(\bar{t}_0), \bar{\varphi}(\tau_{i+1}(\gamma_i)), \dots, \bar{\varphi}(\tau_s(\gamma_i))), \\ i &= p+1, \dots, s; \quad \gamma_i = \gamma_i(\bar{t}_0), \quad \rho_i = \rho_i(\bar{t}_0), \quad \gamma_i(t) = \tau_i^{-1}(t), \quad \rho_i(t) = \eta_i^{-1}(t); \\ \omega &= (t, x_1, \dots, x_s), \quad \tilde{f}[\omega] = f(\omega, \tilde{u}(t)), \quad \tilde{f}_{x_i}[t] = f(t, \bar{x}(\tau_1(t)), \dots, \bar{x}(\tau_s(t)), \tilde{u}(t)). \end{aligned}$$

Theorem 1. *Let the following conditions be fulfilled:*

- 1) $\gamma_i = \bar{t}_0$, $i = 1, \dots, p$, $\gamma_{p+1} < \dots < \gamma_s < \bar{t}_1$, $\rho_j(\bar{t}_0) < \bar{t}_1$, $j = 1, \dots, k$;
- 2) there exists a number $\delta > 0$ such that

$$\gamma_1(t) \leq \dots \leq \gamma_p(t), \quad t \in (\bar{t}_0 - \delta, \bar{t}_0];$$

- 3) there exist the finite limits: $\hat{\gamma}_i^- = \dot{\gamma}_i(\bar{t}_0^-)$, $i = 1, \dots, s$,

$$\lim_{\omega \rightarrow \sigma_i} \tilde{f}[\omega] = f_i^-, \quad \omega \in (\bar{t}_0 - \delta, \bar{t}_0) \times O^s, \quad i = 0, \dots, p,$$

$$\lim_{(\omega_1, \omega_2) \rightarrow (\sigma_i, \sigma_i^0)} [\tilde{f}[\omega_1] - \tilde{f}[\omega_2]] = f_i^-, \quad \omega_1, \omega_2 \in (\gamma_i - \delta, \gamma_i) \times O^s, \quad i = p+1, \dots, s.$$

Then there exist numbers $\varepsilon_2 > 0$, $\delta_2 > 0$ such that for an arbitrary $(t, \varepsilon, \delta \mu) \in [\bar{t}_1 - \delta_2, \bar{t}_1 + \delta_2] \times (0, \varepsilon_2] \times V^-$, $V^- = \{\delta \mu \in V : \delta t_0 \leq 0\}$ the formula

$$\Delta x(t; \varepsilon \delta \mu) = \varepsilon \delta x(t; \varepsilon \delta \mu) + o(t; \varepsilon \delta \mu) \quad (3)$$

is valid, where

$$\begin{aligned} \delta x(t; \delta \mu) &= \{Y(\bar{t}_0^-; t)[\dot{\bar{\varphi}}(\bar{t}_0) - \sum_{j=1}^k A_j(\bar{t}_0)\dot{\bar{\varphi}}(\eta_j(\bar{t}_0)) + \sum_{i=0}^p (\hat{\gamma}_{i+1}^- - \hat{\gamma}_i^-)f_i^-] - \\ &\quad - \sum_{i=p+1}^s Y(\gamma_i^-; t)f_i^- \hat{\gamma}_i^-\} \delta t_0 + \beta(t; \delta \mu), \\ \hat{\gamma}_0^- &= 1, \quad \hat{\gamma}_i^- = \dot{\gamma}_i^-, \quad i = 1, \dots, p, \quad \hat{\gamma}_{p+1}^- = 0; \\ \beta(t; \delta \mu) &= \Phi(\bar{t}_0; t)[\delta x_0 - \dot{\bar{\varphi}}(\bar{t}_0)\delta t_0] + \sum_{i=p+1}^s \int_{\tau_i(\bar{t}_0)}^{\bar{t}_0} Y(\gamma_i(\xi); t)\tilde{f}_{x_i}[\gamma_i(\xi)]\delta \varphi(\xi)\dot{\gamma}_i(\xi)d\xi + \\ &\quad + \sum_{j=1}^k \int_{\rho_j(\bar{t}_0)}^{\bar{t}_0} Y(\rho_j(\xi); t)A_j(\rho_j(\xi))\delta \varphi(\xi)\dot{\rho}_j(\xi)d\xi + \int_{\bar{t}_0}^t Y(\xi; t)\tilde{f}_u[\xi]\delta u(\xi)d\xi; \\ \lim_{\varepsilon \rightarrow 0} o(t; \varepsilon \delta \mu)/\varepsilon &= 0, \end{aligned}$$

uniformly with respect to $(t, \delta \mu) \in [\bar{t}_1 - \delta_2, \bar{t}_1 + \delta_2] \times V^-$; $\Phi(\xi; t)$, $Y(\xi; t)$ are matrix functions satisfying the system

$$\begin{cases} \frac{\partial \Phi(\xi; t)}{\partial \xi} = - \sum_{i=1}^s Y(\gamma_i(\xi); t)\tilde{f}_{x_i}[\gamma_i(\xi)]\dot{\gamma}_i(\xi), \\ Y(\xi; t) = \Phi(\xi; t) + \sum_{j=1}^k Y(\rho_j(\xi); t)A_j(\rho_j(\xi))\dot{\rho}_j(\xi), \quad \xi \in [\bar{t}_0, t]; \end{cases}$$

and the condition

$$\Phi(\xi; t) = Y(\xi; t) = \begin{cases} I, & s = t, \\ \Theta, & \xi > t. \end{cases}$$

Here I is the identity matrix, Θ is the zero matrix.

Theorem 2. Let the condition 1) of Theorem 1 and the following conditions be fulfilled:

4) there exists number $\delta > 0$ such that

$$\gamma_1(t) \leq \dots \leq \gamma_p(t), \quad t \in [\tilde{t}_0, \tilde{t}_0 + \delta);$$

5) there exists the finite limits: $\hat{\gamma}_i^+ = \hat{\gamma}_i(\tilde{t}_0^+)$, $i = 1, \dots, s$,

$$\lim_{\omega \rightarrow \sigma_i} \tilde{f}[\omega] = f_i^+, \quad \omega \in [\tilde{t}_0, \tilde{t}_0 + \delta) \times O^s, \quad i = 0, \dots, p,$$

$$\lim_{(\omega_1, \omega_2) \rightarrow (\sigma_i, \sigma_i^0)} [\tilde{f}[\omega_1] - \tilde{f}[\omega_2]] = f_i^+, \quad \omega_1, \omega_2 \in [\gamma_i, \gamma_i + \delta) \times O^s.$$

Then there exist numbers $\varepsilon_2 > 0$, $\delta_2 > 0$ such that for an arbitrary $(t, \varepsilon, \mu) \in [\tilde{t}_1 - \delta_2, \tilde{t}_1 + \delta_2] \times [0, \varepsilon_2] \times V^+$, $V^+ = \{\delta\mu \in V : \delta t_0 \geq 0\}$ the formula (3) is valid, where $\delta x(t; \delta\mu)$ has the form

$$\begin{aligned} \delta x(t; \delta\mu) = & \{Y(\tilde{t}_0^+; t)[\dot{\tilde{\varphi}}(\tilde{t}_0) - \sum_{j=1}^k A_j(\tilde{t}_0)\dot{\tilde{\varphi}}(\eta_j(\tilde{t}_0)) + \sum_{i=0}^p (\hat{\gamma}_{i+1}^+ - \hat{\gamma}_i^+)f_i^+ - \\ & - \sum_{i=p+1}^s Y(\gamma_i^+; t)f_i^+ \hat{\gamma}_i^+\} \delta t_0 + \beta(t; \delta\mu), \\ & \hat{\gamma}_0^+ = 1, \quad \hat{\gamma}_i^+ = \hat{\gamma}_i^+, \quad i = 1, \dots, p, \quad \hat{\gamma}_{p+1}^+ = 0. \end{aligned}$$

Theorem 3. Let the assumptions of Theorems 1, 2 be fulfilled and

$$\gamma_i, \tilde{t}_0 \notin \{\eta_{k_1}(\eta_{k_2}(\dots(\eta_{k_e}(\tilde{t}_1)), \dots))\} \in (a, \tilde{t}_1) :$$

$$e = 1, 2, \dots, m = 1, \dots, e, \quad k_m = 1, \dots, k\}, \quad i = p+1, \dots, s;$$

$$\sum_{i=0}^p (\hat{\gamma}_{i+1}^- - \hat{\gamma}_i^-)f_i^- = \sum_{i=0}^p (\hat{\gamma}_{i+1}^+ - \hat{\gamma}_i^+)f_i^+ = f_0, \quad f_i^- \hat{\gamma}_i = f_i^+ \hat{\gamma}_i^+ = f_i, \quad i = p+1, \dots, s.$$

Then there exist numbers $\varepsilon_2 > 0$, $\delta_2 > 0$ such that for an arbitrary $(t, \varepsilon, \delta\mu) \in [\tilde{t}_1 - \delta_2, \tilde{t}_1 + \delta_2] \times [0, \varepsilon_2] \times V$ the formula (3) is valid, where $\delta x(t; \delta\mu)$ has the form

$$\delta x(t; \delta\mu) = \{Y(\tilde{t}_0; t)[\dot{\tilde{\varphi}}(\tilde{t}_0) - \sum_{j=1}^k A_j(\tilde{t}_0)\dot{\tilde{\varphi}}(\eta_j(\tilde{t}_0)) - f_0] + \sum_{i=p+1}^s Y(\gamma_i; t)f_i\} \delta t_0 + \beta(t; \delta\mu).$$

Finally we note that the formulas of variation of solution for various classes of delay and neutral differential equations are given in [1–6].

REFERENCES

1. T. TADUMADZE AND N. GORGODZE, Differentiability of solutions of differential equations with deviating argument with respect to the initial data and the right-hand side. *Semin. I. Vekua Inst. Appl. Math. Rep.* **23**(1997), 106–117.
2. N. GORGODZE AND T. TADUMADZE, Differentiability of solutions of neutral type quasi-linear differential equations with respect to the initial data and right-hand side. *Rep. Enlarged Sess. Semin. I. Vekua Appl. Math.* **13**(1998), No. 3, 17–20.
3. G. KHARATISHVILI, T. TADUMADZE AND N. GORGODZE, Continuous dependence and differentiability of solution with respect to initial data and right-hand side for differential

equations with deviating argument. *Mem. Differential Equations Math. Phys.* **19**(2000), 3–105.

4. T. TADUMADZE, Local representations for the variations of solutions of delay differential equations. *Mem. Differential Equations Math. Phys.* **21**(2000), 138–141.

5. N. GORGODZE, Local Representations for the variations of solutions of some class neutral differential equations. *Rep. Enlarged Sess. Semin. I. Vekua Appl. Math.* **15**(2000), No. 1–3, 58–61.

6. L. ALKHAZISHVILI, About local representation of the variation of solutions for one class controlled system with delays. *Rep. Enlarged Sess. Semin. I. Vekua Appl. Math.* **15**(2000), No. 1–3, 37–39.

Author's address:

Department of Mathematics No. 99
Georgian Technical University
77, M. Kostava St., Tbilisi 0175
Georgia