

**A VIABLE RESULT FOR NONCONVEX DIFFERENTIAL  
INCLUSIONS WITH MEMORY**

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**Abstract:** Let  $X$  be a separable Banach space,  $\sigma > 0$  and  $\mathcal{C}_\sigma := \mathcal{C}([-\sigma, 0], X)$  the Banach space of the continuous functions from  $[-\sigma, 0]$  into  $X$ ,  $K$  a locally closed set in  $X$  and  $F: [a, b] \times \mathcal{C}_\sigma \rightarrow 2^X$  a closed valued and locally integrable bounded multifunction, with  $F(\cdot, \varphi)$  measurable and  $F(t, \cdot)$  Lipschitz continuous in the Hausdorff–Pompeiu metric. In this paper we establish some sufficient conditions in order that, for each  $\tau \in [a, b]$  and for each  $\varphi \in \mathcal{C}_\sigma$  with  $\varphi(0) \in K$ , there exist at least one solution  $u: [\tau - \sigma, T] \rightarrow X$  of the differential inclusion  $u'(t) \in F(t, u_t)$ , such that  $u_\tau = \varphi$  on  $[-\sigma, 0]$  and  $u(t) \in K$  for every  $t \in [\tau, T]$ .

**1 – Introduction**

Let  $X$  be a separable Banach space,  $\sigma > 0$  and  $\mathcal{C}_\sigma := \mathcal{C}([-\sigma, 0], X)$  the Banach space of the continuous functions from  $[-\sigma, 0]$  into  $X$ , endowed with the norm  $\|\varphi\|_\sigma := \sup\{\|\varphi(s)\|; s \in [-\sigma, 0]\}$ . If  $u \in \mathcal{C}([\tau - \sigma, T], X)$  is a given function then, for each  $t \in [\tau, T]$ , we define the function  $u_t \in \mathcal{C}_\sigma$  by

$$u_t: [-\sigma, 0] \rightarrow X, \quad u_t(s) = u(t + s), \quad \text{for every } s \in [-\sigma, 0].$$

If  $K$  is a given subset in  $X$  then we introduce the following set  $\mathcal{K}_0 := \{\varphi \in \mathcal{C}_\sigma; \varphi(0) \in K\}$ .

Let  $\mathcal{I} := [a, b]$  be given,  $F: \mathcal{I} \times \mathcal{C}_\sigma \rightarrow 2^X$  a multifunction with nonempty and closed values and  $K$  a nonempty subset in  $X$ . We consider the following differential inclusions

$$(1.1) \quad u'(t) \in F(t, u_t), \quad t \in \mathcal{I}$$

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and we are interested in finding sufficient conditions in order for  $K$  to be a *viable domain* for (1.1) i.e. that for each  $(\tau, \varphi) \in \mathcal{I} \times \mathcal{K}_0$  there exists at least one solution  $u: [\tau - \sigma, T] \rightarrow X$  of (1.1) satisfying the initial condition

$$(1.2) \quad u_\tau = \varphi$$

and such that  $u(t) \in K$  for every  $t \in [\sigma, T]$ .

We recall that a continuous function  $u: [\tau - \sigma, T] \rightarrow X$ , is said to be a *solution* of (1.1) and (1.2) if there exists  $f \in L^1([\tau, T], X)$  with  $f(t) \in F(t, u_t)$  a.e. on  $[\tau, T]$  such that

$$(1.3) \quad u(t) = \begin{cases} \varphi(t - \tau), & t \in [\tau - \sigma, \tau] \\ \varphi(0) + \int_\tau^t f(s) ds, & t \in [\tau, T]. \end{cases}$$

The existence of the viable solutions for the differential inclusion (1.1), in the case in which  $F$  is single-valued, were studied by many authors. For result and references in this framework see [1], [3], [11], [12] and [13].

The first viability result for differential inclusions with memory were given by Haddad [8], [9] in the case in which  $F$  is upper semi-continuous and with convex compact values and  $X$  is a finite dimensional space. The Haddad's result has been extended by Syam [14] and Gavioli and Malaguti [6] in the case in which  $X$  is a separable Banach space.

As is well known, any viability result need a tangential conditions in order to keep the trajectory  $u(t)$  inside in  $K$ . The tangential conditions use in the papers mentioned above are given in terms of classical contingent cone (Bouligand–Severi cone).

The aim of this paper is to established a viable result for non-convex differential inclusion (1.1) using the same kind of tangential condition that in Duc Ha [7], accordingly adapted. Also, the construction method for a sequence of approximate solutions of (1.1), defined on an apriori given interval, is closed to the one used by Cârjă and Vrabie [4].

## 2 – Preliminaries and main result

In this paper we denote by  $X$  a separable Banach space with the norm  $\|\cdot\|$  and by  $\mathcal{C}(X)$  the family of nonempty closed subset of  $X$ . For the subset  $A, B \in \mathcal{C}(X)$  and for  $a \in A$  we denote  $d(a, B) := \inf\{\|a - b\|; b \in B\}$ ,  $d(A, B) :=$

$\sup\{d(a, B); a \in A\}$  and by  $d_{HP}(A, B) := \max\{d(A, B), d(B, A)\}$  the Hausdorff–Pompeiu distance between  $A$  and  $B$ . Also, we denote by  $\mathcal{L}$  the  $\sigma$ -field of the (Lebesgue) measurable subset of  $\mathcal{I} := [a, b)$ .

We recall that a multifunction  $G: \mathcal{I} \rightarrow \mathcal{C}(X)$  is called measurable if  $\{t \in \mathcal{I}; G(t) \cap V \neq \emptyset\} \in \mathcal{L}$  for each open  $V \subset X$ . Notice that the condition  $\{t \in \mathcal{I}; G(t) \subset V\} \in \mathcal{L}$  for each open  $V$  implies the measurability of  $G$ . For compact-valued multifunctions the reverse also holds (see Himmelberg [10, Theorem 3.1]).

In what follows we shall use the assumptions:

(H<sub>0</sub>)  $X$  is a separable Banach space,  $K$  is a locally closed subset in  $X$  and  $F: \mathcal{I} \times \mathcal{K}_0 \rightarrow 2^X$  is a nonempty and closed values multifunction;

(H<sub>1</sub>) For each  $(\tau, \varphi) \in \mathcal{I} \times \mathcal{K}_0$  there exist  $\rho > 0, r > 0$  and  $\chi \in L^1([\tau, \tau + \rho], \mathbb{R}_+)$  such that

$$\sup\{|F(t, \psi)|; \psi \in \mathcal{K}_0 \times B_\sigma(\varphi, r)\} \leq \chi(t)$$

a.e. on  $[\tau, \tau + \rho]$ , where  $|F(t, \varphi)| := \sup\{\|y\|; y \in F(t, \varphi)\}$  and

$$B_\sigma(\varphi, r) := \{\psi \in \mathcal{C}_\sigma; \|\psi - \varphi\| \leq r\};$$

(H<sub>2</sub>) For each  $(\tau, \varphi) \in \mathcal{I} \times \mathcal{K}_0$  there exist  $\rho > 0, r > 0$  and  $\mu \in L^1([\tau, \tau + \rho], \mathbb{R}_+)$  and a negligible subset  $\mathcal{Z} \subset [\tau, \tau + \rho]$  such that

$$d_{HP}(F(t, \varphi_1), F(t, \varphi_2)) \leq \mu(t) \|\varphi_1 - \varphi_2\|_\sigma$$

for every  $t \in [\tau, \tau + \rho] \setminus \mathcal{Z}$  and every  $\varphi_1, \varphi_2 \in \mathcal{K}_0 \times B_\sigma(\varphi, r)$ ;

(H<sub>3</sub>) For each  $\varphi \in \mathcal{K}_0$ , the multifunction  $F(\cdot, \varphi): \mathcal{I} \rightarrow 2^X$  is  $\mathcal{L}$ -measurable;

(H<sub>4</sub>) For every  $(\tau, \varphi) \in \mathcal{I} \times \mathcal{K}_0$  and for every locally integrable selection  $f(\cdot) \in F(\cdot, \varphi)$  holds the following tangential condition:

$$\liminf_{h \downarrow 0} \frac{1}{h} d\left(\varphi(0) + \int_\tau^{\tau+h} f(s) ds, K\right) = 0.$$

We are now ready to state the main result of this paper.

**Theorem 2.1.** *If (H<sub>0</sub>)–(H<sub>4</sub>) are satisfied, then  $K$  is a viable domain for (1.1).*

In order to prove our theorem we need the following technical result, concerning measurable multifunction in Banach spaces, established by Q.I. Zhu [15].

**Theorem 2.2.** *Let  $X$  be a separable Banach space,  $\psi: [a, b] \rightarrow X$  a measurable function and  $G(\cdot): [a, b] \rightarrow 2^X$  a measurable multifunction with nonempty and closed values. Then for any positive measurable function  $\nu: [a, b] \rightarrow \mathbb{R}_+$ , there exists a measurable selection  $g(\cdot) \in G(\cdot)$  such that*

$$\|g(t) - \psi(t)\| \leq d(\psi(t), G(t)) + \nu(t)$$

a.e. on  $[a, b]$ . ■

In the following we recall a general principle on ordered sets due to Brézis and Browder [2]. It will be use in the next section in order to obtain some “maximal” elements in an ordered set.

**Theorem 2.3.** *Let  $\preceq$  be a given preorder on the nonempty set  $M$  and  $S: M \rightarrow \mathbb{R} \cup \{+\infty\}$  be an increasing function. Suppose that each increasing sequence in  $M$  is majorated in  $M$ . Then, for each  $\xi_0 \in M$ , there exists  $\bar{\xi} \in M$  with  $\xi_0 \preceq \bar{\xi}$  such that  $\bar{\xi} \preceq \xi$  implies  $S(\bar{\xi}) = S(\xi)$ . ■*

In the paper by Brézis and Browder, the function  $\mathcal{S}$  is supposed to be finite and bounded from above, but, as remarked in [5], this restriction can be removed by replacing the function  $\mathcal{S}$  by  $\xi \rightarrow \arctan(\mathcal{S}(\xi))$ .

Finally, let  $u$  a function defined on interval  $\mathcal{J}$  of  $\mathbb{R}$  with values into  $X$ . Thus, for some  $\delta > 0$ , we denote by  $\omega(u, \mathcal{J}_0, \delta)$  the *modulus of continuity* of a function  $u$  defined on interval  $\mathcal{J}_0 \subset \mathcal{J}$ , given by

$$\omega(u, \mathcal{J}_0, \delta) = \sup \left\{ \|u(t) - u(s)\|; t, s \in \mathcal{J}_0, |t - s| \leq \delta \right\} .$$

### 3 – Proof of the main result

We shall show that the tangential conditions  $(H_4)$  and Theorem 2.3 imply that, for each  $(\tau, \varphi) \in \mathcal{I} \times \mathcal{K}_0$ , there exists one sequence  $u^n: [\tau - \sigma, T] \rightarrow X$  of “approximate solutions” of (1.1) and (1.2), defined on same interval, such that  $(u^n)_n$  converges in some sense to a solution of (1.1) satisfying (1.2).

Assume that the hypotheses  $(H_0)$ – $(H_4)$  are satisfied and we begin by fixing an arbitrary initial data  $(\tau, \varphi) \in \mathcal{I} \times \mathcal{K}_0$ . Since the hypotheses  $(H_1)$  and  $(H_2)$  have a locally character and  $K$  is locally closed we can choose  $r > 0$ ,  $\rho \in (0, b - \tau)$ ,  $\chi$  and  $\mu$  in  $L^1([\tau, \tau + \rho], \mathbb{R}_+)$  such that  $K \cap B(\varphi(0), r)$  is closed in  $X$  and the relations (2.1) and (2.2) are satisfied on  $[\tau, \tau + \rho] \times B_\sigma(\varphi, r)$ . We emphasize that this choice for  $r$ ,  $\rho$ ,  $\chi$  and  $\mu$  is same along of this paper.

**Remark 3.1.** The following statements hold:

- (i) If  $\alpha \in \mathcal{K}_0 \cap B_\sigma(\varphi, r)$  then  $\alpha(0) \in K \cap B(\varphi(0), r)$ ,
- (ii) If  $K \cap B(\varphi(0), r)$  is closed in  $X$  then  $\mathcal{K}_0 \cap B_\sigma(\varphi, r)$  is closed in  $\mathcal{C}_\sigma$ .  $\square$

Indeed, the first statement is obvious. For the second statement, we assume that  $K \cap B(\varphi(0), r)$  is closed in  $X$  and we consider a sequence  $(\alpha_n)_n$  in  $\mathcal{K}_0 \cap B_\sigma(\varphi, r)$  that is convergent (in the norm  $\|\cdot\|_\sigma$ ) to  $\alpha \in \mathcal{C}_\sigma$ . Then follows that  $\alpha \in B_\sigma(\varphi, r)$ ,  $\alpha_n(0) \rightarrow \alpha(0)$  and  $\alpha_n(0) \in K \cap B(\varphi(0), r)$ ; therefore, since  $K \cap B(\varphi(0), r)$  is closed, we obtain that  $\alpha(0) \in K$  and thus  $\alpha \in \mathcal{K}_0 \cap B_\sigma(\varphi, r)$ .

In the following, we denote by  $\bar{\chi}: [\tau, \tau + \rho] \rightarrow \mathbb{R}_+$  the function defined by

$$(3.1) \quad \bar{\chi}(t) = \int_\tau^t \chi(s) ds, \quad \text{for every } t \in [\tau, \tau + \rho]$$

and with  $\tilde{\omega}: \mathbb{R}_+ \rightarrow \mathbb{R}_+$  the function defined by

$$(3.2) \quad \tilde{\omega}(\delta) = \omega(\varphi, [-\sigma, 0], \delta) + \omega(\bar{\chi}, [\tau, \tau + \rho], \delta) + \delta,$$

for every  $\delta > 0$ .

It is obvious that  $\tilde{\omega}$  is increasing and  $\lim_{\delta \downarrow 0} \tilde{\omega}(\delta) = 0$ .

We shall define the ‘‘approximate solution’’ concept.

**Definition 3.1.** Let  $\varepsilon \in (0, 1)$  and  $\psi \in L^1([\tau, \tau + \rho], X)$  be arbitrary fixed. By the  $(\varepsilon, \psi)$ -approximate solution of (1.1) and (1.2), defined on an interval  $[\tau - \sigma, \nu] \subset [\tau - \sigma, \tau + \rho]$ , we mean a 4-tuple  $(\theta, g, f, u)$  that is compose of the functions  $\theta: [\tau, \nu] \rightarrow [\tau, \nu]$ ,  $g \in L^\infty([\tau, \nu], X)$ ,  $f \in L^1([\tau, \nu], X)$  and of the continuous function  $u: [\tau - \sigma, \nu] \rightarrow X$  defined by

$$(3.3) \quad u(t) = \begin{cases} \varphi(t - \tau), & t \in [\tau - \sigma, \tau], \\ \varphi(0) + \int_\tau^t f(s) ds + \int_\tau^t g(s) ds, & t \in [\tau, \nu], \end{cases}$$

such that:

- (A<sub>1</sub>)  $u_{\theta(t)} \in \mathcal{K}_0 \cap B_\sigma(\varphi, r)$  for every  $t \in [\tau, \nu]$ ;
- (A<sub>2</sub>)  $0 \leq t - \theta(t)$  and  $\tilde{\omega}(t - \theta(t)) \leq \varepsilon$  for every  $t \in [\tau, \nu]$ ;
- (A<sub>3</sub>)  $\|g(t)\| \leq \varepsilon$  a.e. on  $[\tau, \nu]$ ;
- (A<sub>4</sub>)  $f(t) \in F(t, u_{\theta(t)})$  a.e. on  $[\tau, \nu]$ ;
- (A<sub>5</sub>)  $\|f(t) - \psi(t)\| \leq d(\psi(t), F(t, u_{\theta(t)})) + \varepsilon\mu(t)$  a.e. on  $[\tau, \nu]$ ;
- (A<sub>6</sub>)  $u_\nu \in \mathcal{K}_0 \cap B_\sigma(\varphi, r)$ .  $\square$

**Remark 3.2.** We emphasize that for to define an  $(\varepsilon, \psi)$ -approximate solution it is sufficiently to indicate the interval  $[\tau - \sigma, \nu] \subset [\tau - \sigma, \tau + \rho]$  and the functions  $\theta, g$  and  $f$ . Although the function  $u$  is uniquely determined by  $g$  and  $f$ , for sake of simplicity, we preferred to consider it is a component of  $(\theta, g, f, u)$ .  $\square$

**Remark 3.3.** Let  $\nu \in (\tau, \tau + \rho]$ ,  $g \in L^\infty([\tau, \nu], X)$ ,  $f \in L^1([\tau, \nu], X)$  and  $u: [\tau - \sigma, \nu] \rightarrow X$  defined by (3.3). If  $\|f(t)\| \leq \chi(t)$  and  $\|g(t)\| \leq 1$  a.e. on  $[\tau, \nu]$  then for every  $t, s \in [\tau, \nu]$  we have

$$(3.4) \quad \|u_t - u_s\|_\sigma \leq \tilde{\omega}(|t - s|) . \square$$

Indeed, for every  $t, s \in [\tau, \nu]$  we have

$$\begin{aligned} \|u_t - u_s\|_\sigma &= \sup_{\alpha \in [-\sigma, 0]} \|u_t(\alpha) - u_s(\alpha)\| \\ &= \sup_{\alpha \in [-\sigma, 0]} \|u(t+\alpha) - u(s+\alpha)\| \\ &\leq \omega(u, [\tau - \sigma, \nu], |t - s|) \\ &\leq \omega(u, [\tau - \sigma, \tau], |t - s|) + \omega(u, [\tau, \nu], |t - s|) . \end{aligned}$$

Further on, from  $u_\tau = \varphi$  it follows that

$$\omega(u, [\tau - \sigma, \tau], |t - s|) = \omega(\varphi, [-\sigma, 0], |t - s|) .$$

On the other hand, by definition of  $u$  on  $[\tau, \nu]$  and (3.1), we have

$$\|\varphi(t) - \varphi(s)\| \leq \left| \int_s^t \chi(\rho) d\rho \right| + |t - s| < |\bar{\chi}(t) - \bar{\chi}(s)| + |t - s|$$

and so

$$\omega(u, [\tau, \nu], |t - s|) \leq \omega(\bar{\chi}, [\tau, \tau + \rho], |t - s|) + |t - s| .$$

Therefore

$$\|u_t - u_s\|_\sigma \leq \omega(\varphi, [-\sigma, 0], |t - s|) + \omega(\bar{\chi}, [\tau, \tau + \rho], |t - s|) + |t - s| ,$$

hence (3.4).

**Remark 3.4.** Let  $(\theta, g, f, u)$  be an  $(\varepsilon, \psi)$ -approximate solution of (1.1) and (1.2) defined on  $[\tau - \sigma, \nu] \subset [\tau - \sigma, \tau + \rho]$ . By  $(A_1)$ ,  $(A_3)$  and  $(A_4)$  follows that  $\|f(t)\| \leq \chi(t)$  and  $\|g(t)\| \leq 1$  a.e. on  $[\tau, \nu]$  and by Remark 3.3 and  $(A_2)$  we deduce that

$$(3.5) \quad \|u_t - u_{\theta(t)}\|_\sigma \leq \varepsilon , \quad \text{for every } t \in [\tau, \nu] . \square$$

Further on, we show how to define an  $(\varepsilon, \psi)$ -approximate solution of (1.1) and (1.2) defined on an interval  $[\tau - \sigma, T]$  with  $T \in (\tau, \tau + \rho]$ .

**Lemma 3.1.** *Assume that the hypotheses  $(H_0)$ – $(H_4)$  are satisfied. There exists  $T \in (\tau, \tau + \rho]$  with  $\int_{\tau}^T \mu(s) ds \leq \frac{1}{2}$  such that for every  $\varepsilon \in (0, 1)$  and for every  $\psi \in L^\infty([\tau, \tau + \rho], X)$  the problem (1.1) and (1.2) have at least one  $(\varepsilon, \psi)$ -approximate solution on  $[\tau - \sigma, T]$ .*

**Proof:** We fixed  $T \in (\tau, \tau + \rho]$  such that

$$(3.6) \quad \tilde{\omega}(T - \tau) \leq r \quad \text{and} \quad \int_{\tau}^T \mu(s) ds \leq 1/2 .$$

This choice is always possible because  $\mu \in L^1([\tau, \tau + \rho], \mathbb{R}_+)$  and  $\lim_{\delta \downarrow 0} \tilde{\omega}(\delta) = 0$ .

We denote by  $\mathcal{M}_T$  the set of all  $(\varepsilon, \psi)$ -approximate solutions  $(\theta, g, f, u)$  on  $[\tau - \sigma, \nu] \subset [\tau - \sigma, T]$  and we show that  $\mathcal{M}_T$  is nonempty set.

Applying Theorem 2.2 to  $G(\cdot) = F(\cdot, \varphi)$  on  $[\tau, \tau + \rho]$  we obtain that there exists a measurable function  $\bar{f}: [\tau, \tau + \rho] \rightarrow X$  such that  $\bar{f}(t) \in F(t, \varphi)$  a.e. on  $[\tau, \tau + \rho]$  and

$$\|\bar{f}(t) - \psi(t)\| \leq d(\psi(t), F(t, \varphi)) + \varepsilon \mu(t) \quad \text{a.e. on } [\tau, \tau + \rho] .$$

Moreover, from  $(H_1)$  we obtain that  $\|\bar{f}(t)\| \leq \chi(t)$  a.e. on  $[\tau, \tau + \rho]$  and therefore  $\bar{f} \in L^1([\tau, \tau + \rho], X)$ . Using tangential condition  $(H_4)$  applied at  $(\tau, \varphi) \in \mathcal{I} \times \mathcal{K}_0$  for integrable selection  $\bar{f}(\cdot) \in F(\cdot, \varphi)$  we obtain that there exist  $(h_n)_n$  in  $\mathbb{R}_+$  with  $h_n \downarrow 0$  and  $(q_n)_n$  in  $X$  with  $q_n \rightarrow 0$  such that

$$(3.7) \quad \varphi(0) + \int_{\tau}^{\tau+h_n} \bar{f}(s) ds + h_n q_n \in K, \quad \text{for every } n \in \mathbb{N} .$$

Since  $\lim_{\delta \downarrow 0} \tilde{\omega}(\delta) = 0$  we can fix  $n_0 \in \mathbb{N}$  such that  $h_{n_0} \in (0, T - \tau]$ ,  $\tilde{\omega}(h_{n_0}) \leq \varepsilon$  and  $\|q_{n_0}\| \leq \varepsilon$ . For  $n_0$  fixed as above, we define:  $\nu_0 := \tau + h_{n_0}$ ,  $\theta(t) := \tau$  for every  $t \in [\tau, \nu_0]$ ,  $g(t) := q_{n_0}$  and  $f(t) := \bar{f}(t)$  a.e. on  $[\tau, \nu_0]$  and we show that  $(\theta, g, f, u)$ , with  $u$  defined by (3.3), is an  $(\varepsilon, \psi)$ -approximate solution on  $[\tau - \sigma, \nu_0] \subset [\tau - \sigma, T]$ .

Indeed, it is easily to see that the conditions  $(A_1)$ – $(A_5)$  are fulfilled. Then  $\|f(t)\| \leq \chi(t)$  and  $\|g(t)\| \leq \varepsilon \leq 1$  a.e.  $t \in [\tau, \nu_0]$  and therefore, by (3.4) and (3.6), we have

$$\|u_{\nu_0} - \varphi\|_{\sigma} = \|u_{\nu_0} - u_{\tau}\|_{\sigma} \leq \tilde{\omega}(h_{n_0}) \leq \tilde{\omega}(T - \tau) \leq r ,$$

hence  $u_{\nu_0} \in B_\sigma(\varphi, r)$ . Since, by (3.3) and (3.7), we have

$$u_{\nu_0}(0) = u(\nu_0) = \varphi(0) + \int_\tau^{\tau+h_{n_0}} \bar{f}(s) ds + h_{n_0}q_{n_0} \in K ,$$

it follows that  $u_{\nu_0} \in \mathcal{K}_0 \cap B_\sigma(\varphi, r)$  and thus  $(A_6)$  is also satisfied. Therefore,  $(\theta, g, f, u)$  is an  $(\varepsilon, \psi)$ -approximate solution on  $[\tau - \sigma, \nu_0]$  and thus we have that  $\mathcal{M}_T$  is a nonempty set.

Next, we show that there exists at least one  $(\varepsilon, \psi)$ -approximate solution of (1.1) and (1.2), defined on the whole interval  $[\tau - \sigma, T]$ . For this aim we shall use Theorem 2.3 as follows. On  $\mathcal{M}_T$  we introduce a preorder as follows.

If  $(\theta^1, g^1, f^1, u^1)$  and  $(\theta^2, g^2, f^2, u^2)$  are two  $(\varepsilon, \psi)$ -approximate solutions on  $[\tau - \sigma, \nu^1]$  and respectively on  $[\tau - \sigma, \nu^2]$ , then we say that

$$(\theta^1, g^1, f^1, u^1) \preceq (\theta^2, g^2, f^2, u^2)$$

if and only if  $\nu^1 \leq \nu^2$ ,  $\theta^1(t) = \theta^2(t)$ ,  $g^1(t) = g^2(t)$  and  $f^1(t) = f^2(t)$  on  $[\tau, \nu^1]$ .

Let us define the function  $\mathcal{S}: \mathcal{M}_T \rightarrow \mathbb{R}$  by

$$\mathcal{S}((\theta, g, f, u)) = \nu ,$$

for every  $(\varepsilon, \psi)$ -approximate solution defined on  $[\tau - \sigma, \nu] \subset [\tau - \sigma, T]$ .

It is clear that  $\mathcal{S}$  is increasing on  $\mathcal{M}_T$ . Further on, we show that each increasing sequence  $((\theta^i, g^i, f^i, u^i))_{i \in \mathbb{N}}$  in  $\mathcal{M}_T$  is majorated in  $\mathcal{M}_T$ . We define a majorant as follows. We define

$$\nu^* = \lim_i \nu^i$$

and we observe that  $\nu^* \in (\tau, T]$ . For each  $i \in \mathbb{N}$ , we define  $\theta^*(t) = \theta^i(t)$  if  $t \in [\tau, \nu^i]$  and  $\theta^*(\nu^*) = \nu^*$ ,  $g^*(t) = g^i(t)$  and  $f^*(t) = f^i(t)$  if  $t \in [\tau, \nu^i]$ , and we observe that, by the fact that  $((\theta^i, g^i, f^i, u^i))_{i \in \mathbb{N}}$  is an increasing sequence in  $\mathcal{M}_T$ , the functions  $\theta^*$ ,  $g^*$ , and  $f^*$  are well defined. Moreover, since for every  $i \in \mathbb{N}$  we have that  $\|f^i(t)\| \leq \chi(t)$  and  $\|g^i(t)\| \leq \varepsilon$  a.e. on  $[\tau, \nu^i]$  it follows that

$$(3.8) \quad \|f^*(t)\| \leq \chi(t) \quad \text{and} \quad \|g^*(t)\| \leq \varepsilon \quad \text{a.e. on} \quad [\tau, \nu^*]$$

and thus we obtain that  $g^* \in L^\infty([\tau, \nu^*], X)$  and  $f^* \in L^1([\tau, \nu^*], X)$ .

It is obvious that  $\theta^*: [\tau, \nu^*] \rightarrow [\tau, \nu^*]$ . Therefore, we can consider the 4-tuple  $(\theta^*, g^*, f^*, u^*)$  with the function  $u^*: [\tau - \sigma, \nu^*] \rightarrow X$  defined by (3.3). Now, we show that  $(\theta^*, g^*, f^*, u^*) \in \mathcal{M}_T$ . For this, we fixed an arbitrary  $i \in \mathbb{N}$  and we



observe that for every  $t \in [\tau - \sigma, \tau]$  we have  $u^*(t) = \varphi(t - \tau) = u^i(t)$  and for every  $t \in [\tau, \nu^i]$  we have

$$\begin{aligned} u^*(t) &= \varphi(0) + \int_{\tau}^t f^*(s) ds + \int_{\tau}^t g^*(s) ds \\ &= \varphi(0) + \int_{\tau}^t f^i(s) ds + \int_{\tau}^t g^i(s) ds = u^i(t) . \end{aligned}$$

Therefore,  $u^*(t) = u^i(t)$  for every  $t \in [\tau - \sigma, \nu^i]$ . Moreover, since for every  $t \in [\tau, \nu^i]$  and every  $s \in [-\sigma, 0]$  we have

$$\tau - \sigma \leq \theta^*(t) + s = \theta^i(t) + s \leq t + s \leq t \leq \nu^i$$

we obtain that

$$u_{\theta^*(t)}^*(s) = u^*(\theta^*(t) + s) = u^*(\theta^i(t) + s) = u^i(\theta^i(t) + s) = u_{\theta^i(t)}^i(s)$$

and thus

$$(3.9) \quad u_{\theta^*(t)}^* = u_{\theta^i(t)}^i \quad \text{for every } t \in [\tau, \nu^i] .$$

Further on, let us observe that  $(\theta^*, g^*, f^*, u^*)$  satisfies  $(A_2)$ – $(A_5)$ .

Let us verify the conditions  $(A_1)$  and  $(A_6)$ . For any  $t \in [\tau, \nu^*]$  there exists  $i \in \mathbb{N}$  such that  $t \in [\tau, \nu^i]$  and by (3.9) it follows that

$$u_{\theta^*(t)}^* = u_{\theta^i(t)}^i \in \mathcal{K}_0 \cap B_{\sigma}(\varphi, r) .$$

For  $t = \nu^*$  we have  $\theta^*(\nu^*) = \nu^*$  and  $u_{\theta^*(\nu^*)}^* = u_{\nu^*}^*$ . Then, by (3.8), we can use the relation (3.4) that, together with (3.6), implies

$$\|u_{\nu^*}^* - \varphi\|_{\sigma} = \|u_{\nu^*}^* - u_{\tau}^*\|_{\sigma} \leq \tilde{\omega}(\nu^* - \tau) \leq r .$$

and thus  $u_{\theta^*(\nu^*)}^* = u_{\nu^*}^* \in B_{\sigma}(\varphi, r)$ .

By the continuity of  $u^*$  we have

$$u_{\nu^*}^*(0) = u^*(\nu^*) = \lim_i u^*(\nu^i) = \lim_i u^i(\nu^i)$$

and since  $u_{\nu^i}^i \in \mathcal{K}_0 \cap B_{\sigma}(\varphi, r)$  for every  $i \in \mathbb{N}$  we have that  $u_{\nu^i}^i(0) \in K \cap B(\varphi(0), r)$  for every  $i \in \mathbb{N}$ . Therefore, since  $K \cap B(\varphi(0), r)$  is closed set we obtain that  $u_{\nu^*}^*(0) \in K \cap B(\varphi(0), r)$  and hence we have that  $u_{\theta^*(\nu^*)}^* = u_{\nu^*}^* \in \mathcal{K}_0$ .

Thus we conclude that  $(\theta^*, g^*, f^*, u^*) \in \mathcal{M}_T$ . In addition  $(\theta^i, g^i, f^i, u^i) \preceq (\theta^*, g^*, f^*, u^*)$  for each  $i \in \mathbb{N}$  and thus the sequence  $((\theta^i, g^i, f^i, u^i))_{i \in \mathbb{N}}$  is majorated in  $\mathcal{M}_T$ . Therefore, the set  $\mathcal{M}_T$ , endowed with the preorder  $\preceq$ , and the function  $\mathcal{S}$  satisfies the hypotheses of Theorem 2.3.

Before to use the conclusion of Theorem 2.3, we show that every  $(\theta, g, f, u) \in \mathcal{M}_T$  with  $\mathcal{S}((\theta, g, f, u)) < T$  is majorated in  $\mathcal{M}_T$  by an element  $(\tilde{\theta}, \tilde{g}, \tilde{f}, \tilde{u}) \in \mathcal{M}_T$  with  $\mathcal{S}((\theta, g, f, u)) < \mathcal{S}((\tilde{\theta}, \tilde{g}, \tilde{f}, \tilde{u}))$ .

For this aim let us consider  $(\theta, g, f, u)$  an  $(\varepsilon, \psi)$ -approximate solution defined  $[\tau - \sigma, \nu]$  with  $\nu \in (\tau, T)$ . Since  $u_\nu \in \mathcal{K}_0 \cap B_\sigma(\varphi, r)$  we can apply the Theorem 2.3 on  $[\nu, \tau + \rho]$  for  $G(\cdot) = F(\cdot, u_\nu)$ . We obtain that there exists a measurable function  $\bar{f}: [\nu, \tau + \rho] \rightarrow X$  such that  $\bar{f}(t) \in F(t, u_\nu)$  a.e. on  $[\nu, \tau + \rho]$  and

$$\|\bar{f}(t) - \psi(t)\| \leq d(\psi(t), F(t, u_\nu)) + \varepsilon \mu(t) \quad \text{a.e. on } [\nu, \tau + \rho].$$

By  $(H_1)$  it follows that  $\|\bar{f}(t)\| \leq \chi(t)$  a.e. on  $[\nu, \tau + \rho]$  and hence  $\bar{f} \in L^1(\nu, \tau + \rho; X)$ . Using tangential condition  $(H_4)$  applied at  $(\nu, u_\nu) \in \mathcal{I} \times \mathcal{K}_0$  for integrable selection  $\bar{f}(\cdot) \in F(\cdot, u_\nu)$  we obtain that there exist  $(h_n)_n$  in  $\mathbb{R}_+$  with  $h_n \downarrow 0$  and  $(q_n)_n$  in  $X$  with  $q_n \rightarrow 0$  such that

$$(3.10) \quad u_\nu(0) + \int_\nu^{\nu+h_n} \bar{f}(s) ds + h_n q_n \in K, \quad \text{for every } n \in \mathbb{N}.$$

Since  $\lim_{\delta \downarrow 0} \tilde{\omega}(\delta) = 0$  we can fix  $\tilde{n} \in \mathbb{N}$  such that  $h_{\tilde{n}} \in (0, T - \tau]$ ,  $\tilde{\omega}(h_{\tilde{n}}) \leq \varepsilon$ , and  $\|q_{\tilde{n}}\| \leq \varepsilon$ . Further on, we define  $\tilde{\nu} := \nu + h_{\tilde{n}}$  and

$$\begin{aligned} \tilde{\theta}(t) &:= \begin{cases} \theta(t) & \text{if } t \in [\tau, \nu], \\ \nu & \text{if } t \in (\nu, \tilde{\nu}]; \end{cases} \\ \tilde{g}(t) &:= \begin{cases} g(t) & \text{if } t \in [\tau, \nu], \\ q_{\tilde{n}} & \text{if } t \in (\nu, \tilde{\nu}]; \end{cases} \\ \tilde{f}(t) &:= \begin{cases} f(t) & \text{if } t \in [\tau, \nu], \\ \bar{f}(t) & \text{if } t \in (\nu, \tilde{\nu}]. \end{cases} \end{aligned}$$

We show that  $(\tilde{\theta}, \tilde{g}, \tilde{f}, \tilde{u})$ , with  $\tilde{u}$  given by (3.3), is an  $(\varepsilon, \psi)$ -approximate solution defined on  $[\tau - \sigma, \tilde{\nu}] \subset [\tau - \sigma, T]$ . First, we observe that

$$\tilde{u}(t) = u(t) \quad \text{for every } t \in [\tau - \sigma, \nu]$$

and

$$\begin{aligned} \tilde{u}(t) &= \varphi(0) + \int_{\tau}^t \tilde{f}(s) ds + \int_{\tau}^t \tilde{g}(s) ds \\ &= \tilde{u}(\nu) + \int_{\nu}^t \tilde{f}(s) ds + \int_{\nu}^t \tilde{g}(s) ds \\ &= u_{\nu}(0) + \int_{\nu}^t \bar{f}(s) ds + (t-\nu) q_{\bar{n}} , \end{aligned}$$

for every  $t \in [\nu, \tilde{\nu}]$ . Also, it is obvious that  $(\tilde{\theta}, \tilde{g}, \tilde{f}, \tilde{u})$  satisfies  $(A_2)$ – $(A_5)$  on  $[\tau, \nu]$  and on  $(\nu, \tilde{\nu}]$  they are satisfied by our choice of  $\bar{f}$ ,  $h_{\bar{n}}$  and  $q_{\bar{n}}$ . Since for every  $t \in [\tau, \nu]$  we have

$$\tilde{u}_{\tilde{\theta}(t)} = \tilde{u}_{\theta(t)} = u_{\theta(t)} \in \mathcal{K}_0 \cap B_{\sigma}(\varphi, r)$$

and for every  $t \in (\nu, \tilde{\nu})$  we have

$$\tilde{u}_{\tilde{\theta}(t)} = \tilde{u}_{\nu} = u_{\nu} \in \mathcal{K}_0 \cap B_{\sigma}(\varphi, r) ,$$

we deduce that  $(A_1)$  is fulfilled.

Let us verify the condition  $(A_6)$ . By  $(A_1)$ ,  $(A_3)$  and  $(A_4)$  we have that  $\|f(t)\| \leq \chi(t)$  and  $\|g(t)\| \leq \varepsilon \leq 1$  a.e. on  $[\tau, \tilde{\nu}]$  and therefore we can use (3.4) that, together with (3.6), implies

$$\|\tilde{u}_{\tilde{\nu}} - \varphi\|_{\sigma} = \|\tilde{u}_{\tilde{\nu}} - \tilde{u}_{\tau}\|_{\sigma} \leq \tilde{\omega}(\tilde{\nu} - \tau) \leq \tilde{\omega}(T - \tau) \leq r$$

and thus  $\tilde{u}_{\tilde{\nu}} \in B_{\sigma}(\varphi, r)$ . Since by (3.2) and (3.10) we have

$$\tilde{u}_{\tilde{\nu}}(0) = \tilde{u}(\tilde{\nu}) = u_{\nu}(0) + \int_{\nu}^{\nu+h_{\bar{n}}} \bar{f}(s) ds + h_{\bar{n}} q_{\bar{n}} \in K ,$$

it follows that  $\tilde{u}_{\tilde{\nu}} \in \mathcal{K}_0 \cap B_{\sigma}(\varphi, r)$ . Therefore,  $(\tilde{\theta}, \tilde{g}, \tilde{f}, \tilde{u})$  is an  $(\varepsilon, \psi)$ -approximate solution defined on  $[\tau - \sigma, \tilde{\nu}]$ . Moreover, by construction, we have that  $(\theta, g, f, u) \preceq (\tilde{\theta}, \tilde{g}, \tilde{f}, \tilde{u})$  and  $\mathcal{S}((\theta, g, f, u)) = \nu < \tilde{\nu} = \mathcal{S}((\tilde{\theta}, \tilde{g}, \tilde{f}, \tilde{u}))$ .

Now, let  $(\theta^0, g^0, f^0, u^0)$  be arbitrary fixed in  $\mathcal{M}_T$ . By Theorem 2.3 we deduce that there exists  $(\theta, g, f, u) \in \mathcal{M}_T$ , with  $(\theta^0, g^0, f^0, u^0) \preceq (\theta, g, f, u)$ , such that  $\mathcal{S}((\theta, g, f, u)) = \mathcal{S}((\tilde{\theta}, \tilde{g}, \tilde{f}, \tilde{u}))$ , for each  $(\tilde{\theta}, \tilde{g}, \tilde{f}, \tilde{u}) \in \mathcal{M}_T$  with  $(\theta, g, f, u) \preceq (\tilde{\theta}, \tilde{g}, \tilde{f}, \tilde{u})$ .

It follows that  $\mathcal{S}((\theta, g, f, u)) = T$  because, contrary, by precedent step, there exists  $(\tilde{\theta}, \tilde{g}, \tilde{f}, \tilde{u}) \in \mathcal{M}_T$  with  $(\theta, g, f, u) \preceq (\tilde{\theta}, \tilde{g}, \tilde{f}, \tilde{u})$  and such that  $\mathcal{S}((\theta, g, f, u)) < \mathcal{S}((\tilde{\theta}, \tilde{g}, \tilde{f}, \tilde{u}))$ , that is in contradiction with our choice for  $(\theta, g, f, u)$ .

Thus we have proved that there exists an  $(\varepsilon, \psi)$ -approximate solution of (1.1) and (1.2) defined on the whole interval  $[\tau - \sigma, T]$ . ■

We are now prepared to prove Theorem 2.1.

**Proof of Theorem 2.1:** Let  $(\tau, \varphi) \in \mathcal{I} \times \mathcal{K}_0$  be fixed and we consider  $T \in (\tau, \tau + \rho]$  given as in Lemma 3.1. We introduce now the *solution operator*  $Q: L^1([\tau, T], X) \rightarrow C([\tau - \sigma, T], X)$  defined by

$$(3.11) \quad (Qf)(t) = \begin{cases} \varphi(t - \tau) & \text{if } t \in [\tau - \sigma, \tau], \\ \varphi(0) + \int_{\tau}^t f(s) ds & \text{if } t \in (\tau, T]. \end{cases}$$

We notice that  $u$  is a solution of (1.1) and (1.2) on  $[\tau - \sigma, T]$  if there exists  $f \in L^1([\tau, T], X)$  such that  $u = Qf$  and  $f(t) \in F(t, u(t))$  a.e. on  $[\tau, T]$ .

Let  $(\varepsilon_n)_n$  be a decreasing sequence of positive real numbers such that  $\sum_{n=1}^{\infty} \varepsilon_n < +\infty$  and  $\varepsilon_n \in (0, 1)$  for every  $n \in \mathbb{N}$ .

Starting with one measurable selection  $f_0(\cdot) \in F(\cdot, \varphi)$  in view of Lemma 3.1, we can define inductively the sequence  $((\theta^n, g^n, f^n, u^n))_{n \in \mathbb{N}}$  such that  $(\theta^n, g^n, f^n, u^n)$  is an  $(\varepsilon_n, f^n)$ -approximate solution on  $[\tau - \sigma, T]$  for every  $n \in \mathbb{N}$ .

Thus, for every  $n \in \mathbb{N}$  we have

$$(3.12) \quad u^n(t) = \begin{cases} \varphi(t - \tau) & \text{if } t \in [\tau - \sigma, \tau], \\ \varphi(0) + \int_{\tau}^t f^n(s) ds + \int_{\tau}^t g^n(s) ds & \text{if } t \in (\tau, T] \end{cases}$$

and

- (B<sub>1</sub>)  $u_{\theta^n(t)}^n \in \mathcal{K}_0 \cap B_{\sigma}(\varphi, r)$  for every  $t \in [\tau, T]$ ;
- (B<sub>2</sub>)  $0 \leq t - \theta^n(t)$  and  $\tilde{\omega}(t - \theta^n(t)) \leq \varepsilon$  for every  $t \in [\tau, T]$ ;
- (B<sub>3</sub>)  $\|g^n(t)\| \leq \varepsilon_n$  a.e. on  $[\tau, T]$ ;
- (B<sub>4</sub>)  $f^n(t) \in F(t, u_{\theta^n(t)}^n)$  a.e. on  $[\tau, T]$ ;
- (B<sub>5</sub>)  $\|f^n(t) - f^{n-1}(t)\| \leq d(f^{n-1}(t), F(t, u_{\theta^n(t)}^n)) + \varepsilon_n \mu(t)$  a.e. on  $[\tau, T]$ ;
- (B<sub>6</sub>)  $u_T^n \in \mathcal{K}_0 \cap B_{\sigma}(\varphi, r)$ .

We show that  $(u^n)_n$  converge uniformly to a function  $u: [\tau - \sigma, T] \rightarrow X$  that is a solution of (1.1) and (1.2).

For this, first we show that for every  $n \in \mathbb{N}$  we have

- (C<sub>1</sub>)  $\|f^n(t)\| \leq \chi(t)$  a.e. on  $[\tau, T]$ ;
- (C<sub>2</sub>)  $\|u_t^n - u_{\theta^n(t)}^n\|_{\sigma} \leq \varepsilon_n$  for every  $t \in [\tau, T]$ ;
- (C<sub>3</sub>)  $\|u^n(t) - (Qf^n)(t)\| \leq (T - \tau)\varepsilon_n$  for every  $t \in [\tau - \sigma, T]$ ;

- (C<sub>4</sub>)  $\|u_{\theta^{n+1}(t)}^{n+1} - u_{\theta^n(t)}^n\|_\sigma \leq 2\varepsilon_n + \|u^{n+1} - u^n\|_T$ , for every  $t \in [\tau, T]$ , where  $\|\cdot\|_T$  is norm in  $C([\tau - \sigma, T]; X)$ ;
- (C<sub>5</sub>)  $\|f^{n+1}(t) - f^n(t)\| \leq \mu(t)(\|u^{n+1} - u^n\|_T + 3\varepsilon_n)$  a.e. on  $[\tau, T]$ .

Indeed, (C<sub>1</sub>) follows from (H<sub>1</sub>) and (B<sub>4</sub>), (C<sub>2</sub>) follows from Remark 3.4, and (C<sub>3</sub>) follows from (3.11), (3.12) and (B<sub>3</sub>). For to show (C<sub>4</sub>) we observe that

$$\begin{aligned} \|u_t^{n+1} - u_t^n\|_\sigma &= \sup_{-\sigma \leq s \leq 0} \|u^{n+1}(t+s) - u^n(t+s)\| \\ &\leq \sup_{\tau - \sigma \leq \nu \leq T} \|u^{n+1}(\nu) - u^n(\nu)\| \\ &= \|u^{n+1} - u^n\|_T \end{aligned}$$

and thus by (C<sub>2</sub>) we obtain that

$$\begin{aligned} \|u_{\theta^{n+1}(t)}^{n+1} - u_{\theta^n(t)}^n\|_\sigma &\leq \|u_{\theta^{n+1}(t)}^{n+1} - u_t^{n+1}\|_\sigma + \|u_t^{n+1} - u_t^n\|_\sigma + \|u_t^n - u_{\theta^n(t)}^n\|_\sigma \\ &\leq \varepsilon_{n+1} + \|u_t^{n+1} - u_t^n\|_\sigma + \varepsilon_n \\ &\leq 2\varepsilon_n + \|u^{n+1} - u^n\|_T \end{aligned}$$

for every  $t \in [\tau, T]$ .

In finally, by (H<sub>2</sub>), (B<sub>5</sub>) and (C<sub>4</sub>) we have

$$\begin{aligned} \|f^{n+1}(t) - f^n(t)\| &\leq d\left(f^n(t), F(t, u_{\theta^{n+1}(t)}^{n+1})\right) + \varepsilon_{n+1} \mu(t) \\ &\leq d_{HP}\left(F(t, u_{\theta^n(t)}^n), F(t, u_{\theta^{n+1}(t)}^{n+1})\right) + \varepsilon_{n+1} \mu(t) \\ &\leq \mu(t) \left(\|u_{\theta^n(t)}^n - u_{\theta^{n+1}(t)}^{n+1}\| + \varepsilon_{n+1}\right) \\ &\leq \mu(t) \left(\|u^{n+1} - u^n\|_T + 3\varepsilon_n\right) \end{aligned}$$

a.e. on  $[\tau, T]$  and hence (C<sub>5</sub>) is also checked.

Further on, for every  $t \in [\tau, T]$ , by (3.6), (3.11), (C<sub>3</sub>) and (C<sub>5</sub>) we have

$$\begin{aligned} \|u^{n+1}(t) - u^n(t)\| &\leq \\ &\leq \|u^{n+1}(t) - (Qf^{n+1})(t)\| + \|(Qf^{n+1})(t) - (Qf^n)(t)\| + \|(Qf^n)(t) - u^n(t)\| \\ &\leq (T - \tau)(\varepsilon_{n+1} + \varepsilon_n) + \int_\tau^T \|f^{n+1}(s) - f^n(s)\| ds \\ &\leq 2(T - \tau)\varepsilon_n + \left(3\varepsilon_n + \|u^{n+1} - u^n\|_T\right) \int_\tau^T \mu(s) ds \\ &\leq \left(2(T - \tau) + \frac{3}{2}\right) \varepsilon_n + \frac{1}{2} \|u^{n+1} - u^n\|_T . \end{aligned}$$

Therefore, since  $\|u^{n+1}(t) - u^n(t)\| = 0$  for every  $t \in [\tau - \sigma, \tau]$  we obtain

$$\|u^{n+1}(t) - u^n(t)\| \leq \left(2(T-\tau) + \frac{3}{2}\right) \varepsilon_n + \frac{1}{2} \|u^{n+1} - u^n\|_T$$

for every  $t \in [\tau - \sigma, T]$  and so, we have

$$\|u^{n+1} - u^n\|_T \leq \left(2(T-\tau) + \frac{3}{2}\right) \varepsilon_n + \frac{1}{2} \|u^{n+1} - u^n\|_T.$$

Thus we have that

$$(3.13) \quad \|u^{n+1} - u^n\|_T \leq (4(T-\tau) + 3) \varepsilon_n$$

for every  $n \in \mathbb{N}^*$  with  $\sum_{n=1}^{\infty} \varepsilon_n < +\infty$  and thus we deduce that  $(u^n)_n$  converge uniformly to a function  $u: [\tau - \sigma, T] \rightarrow X$ .

From  $(C_5)$  and (3.13) we deduce that, for almost all  $t \in [\tau, T]$ , we have

$$\begin{aligned} \|f^{n+1}(t) - f^n(t)\| &\leq \mu(t) (\|u^{n+1} - u^n\|_T + 3\varepsilon_n) \\ &\leq \mu(t) (4(T-\tau) + 6) \varepsilon_n \end{aligned}$$

for every  $n \in \mathbb{N}^*$ . This imply that  $(f^n)_n$  converge pointwise almost everywhere to a measurable function  $f$ . For any fixed  $t \in [\tau - \sigma, T]$ , by  $(C_1)$  and Lebesgue's Theorem, we obtain that  $\lim_{n \rightarrow \infty} (Qf^n)(t) = (Qf)(t)$ . Consequently, by  $(C_3)$ , we conclude that  $u(t) = (Qf)(t)$  for every  $t \in [\tau - \sigma, T]$ . For every  $t \in [\tau, T]$  and every  $n \in \mathbb{N}^*$ , by  $(C_2)$ , we have

$$\|u_{\theta^n(t)}^n - u_t\|_{\sigma} \leq \|u_{\theta^n(t)}^n - u_t^n\|_{\sigma} + \|u_t^n - u_t\|_{\sigma} \leq \varepsilon_n + \|u^n - u\|_T$$

and thus  $u_{\theta^n(t)}^n \rightarrow u_t$  in  $\mathcal{C}_{\sigma}$  as  $n \rightarrow \infty$ .

From  $(B_1)$  and Remark 3.1 it follows that  $u_t \in \mathcal{K}_0 \cap B_{\sigma}(\varphi, r)$  for every  $t \in [\tau, T]$ .

Now, we observe that, a.e. on  $[\tau, T]$ , we have

$$\begin{aligned} d(f(t), F(t, u_t)) &\leq \|f(t) - f^n(t)\| + d(F(t, u_{\theta^n(t)}^n), F(t, u_t)) \\ &\leq \|f(t) - f^n(t)\| + \mu(t) \|u_{\theta^n(t)}^n - u_t\|_{\sigma} \end{aligned}$$

for every  $n \in \mathbb{N}^*$ . Therefore, by letting  $n \rightarrow \infty$ , we obtain that  $d(f(t), F(t, u_t)) = 0$  and thus, because the multifunction  $F$  has closed values,  $f(t) \in F(t, u_t)$  a.e on  $[\tau, T]$ .

Finally, from  $u_t \in \mathcal{K}_0 \cap B_\sigma(\varphi(0), r)$ , by Remark 3.1, we deduce that  $u(t) \in K \cap B(\varphi(0), r)$  for every  $t \in [\tau, T]$ .

We have proved that  $u: [\tau - \sigma, T] \rightarrow X$  is a solution of (1.1) and (1.2), and so,  $(\tau, \varphi)$  being arbitrarily fixed in  $\mathcal{I} \times \mathcal{K}_0$ , we have showed that  $K$  is a viable domain for (1.1). ■

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