

FRACTIONAL ORDER DIFFERENTIAL INCLUSIONS ON THE HALF-LINE

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Abstract. We are concerned with the existence of bounded solutions of a boundary value problem on an unbounded domain for fractional order differential inclusions involving the Caputo fractional derivative. Our results are based on the fixed point theorem of Bohnnenblust-Karlin combined with the diagonalization method.

1 Introduction

This paper deals with the existence of bounded solutions for boundary value problems (BVP for short) for fractional order differential inclusions of the form

$${}^c D^\alpha y(t) \in F(t, y(t)), \quad t \in J := [0, \infty), \quad (1.1)$$

$$y(0) = y_0, \quad y \text{ is bounded on } J, \quad (1.2)$$

where ${}^c D^\alpha$ is the Caputo fractional derivative of order $\alpha \in (1, 2]$, $F : J \times \mathbb{R} \rightarrow \mathcal{P}(\mathbb{R})$ is a multivalued map with compact, convex values ($\mathcal{P}(\mathbb{R})$ is the family of all nonempty subsets of \mathbb{R}), $y_0 \in \mathbb{R}$.

Fractional Differential equations have gained considerable importance due to their application in various sciences, such as physics, mechanics, chemistry, engineering, control, etc. (see [15, 17, 19, 18, 24, 27, 28]).

Recently, there has been a significant development in the study of ordinary and partial differential equations and inclusions involving fractional derivatives, see the monographs of Kilbas *et al.* [21], Lakshmikantham *et al.* [22], Miller and Ross [25], Podlubny [27], Samko *et al.* [29] and the papers by Agarwal *et al.* [1], Belarbi *et al.* [7, 8], Benchohra *et al.* [9, 10, 11, 12], Chang and Nieto [14], Diethelm *et al.* [15], and Ouahab [26].

Agarwal *et al.* [2] have considered a class of boundary value problems involving Riemann-Liouville fractional derivative on the half line. They used the diagonalization

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process combined with the nonlinear alternative of Leray- Schauder type. This paper continues this study by considering a boundary value problem with the Caputo fractional derivative. We use the classical fixed point theorem of Bohnnenblust-Karlin [13] combined with the diagonalization process widely used for integer order differential equations; see for instance [3, 4]. Our results extend to the multivalued case those considered recently by Arara *et al.* [5].

2 Preliminary facts

We now introduce notations, definitions, and preliminary facts that will be used in the remainder of this paper.

Let $T > 0$ and $J := [0, T]$. $C(J, \mathbb{R})$ is the Banach space of all continuous functions from J into \mathbb{R} with the usual norm

$$\|y\| = \sup\{|y(t)| : 0 \leq t \leq T\}.$$

$L^1(J, \mathbb{R})$ denote the Banach space of functions $y : J \rightarrow \mathbb{R}$ that are Lebesgue integrable with the norm

$$\|y\|_{L^1} = \int_0^T |y(t)| dt.$$

$AC^1(J, \mathbb{R})$ denote the space of differentiable functions whose first derivative y' is absolutely continuous.

2.1 Fractional derivatives

Definition 1. ([21, 27]). Given an interval $[a, b]$ of \mathbb{R} . The fractional (arbitrary) order integral of the function $h \in L^1([a, b], \mathbb{R})$ of order $\alpha \in \mathbb{R}_+$ is defined by

$$I_a^\alpha h(t) = \int_a^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} h(s) ds,$$

where Γ is the gamma function. When $a = 0$, we write $I^\alpha h(t) = [h * \varphi_\alpha](t)$, where $\varphi_\alpha(t) = \frac{t^{\alpha-1}}{\Gamma(\alpha)}$ for $t > 0$, and $\varphi_\alpha(t) = 0$ for $t \leq 0$, and $\varphi_\alpha \rightarrow \delta(t)$ as $\alpha \rightarrow 0$, where δ is the delta function.

Definition 2. ([21]). For a given function h on the interval $[a, b]$, the Caputo fractional-order derivative of h , is defined by

$$({}^c D_{a+}^\alpha h)(t) = \frac{1}{\Gamma(n-\alpha)} \int_a^t (t-s)^{n-\alpha-1} h^{(n)}(s) ds,$$

where $m = [\alpha] + 1$.

More details on fractional derivatives and their properties can be found in [21, 27]

Lemma 3. (Lemma 2.22 [21]). Let $\alpha > 0$, then the differential equation

$${}^c D^\alpha h(t) = 0$$

has solutions

$$h(t) = c_0 + c_1 t + c_2 t^2 + \dots + c_{m-1} t^{m-1}, c_i \in \mathbb{R}, \quad i = 0, 1, 2, \dots, m - 1, \quad m = [\alpha] + 1.$$

Lemma 4. (Lemma 2.22 [21]). Let $\alpha > 0$, then

$$I^\alpha {}^c D^\alpha h(t) = h(t) + c_0 + c_1 t + c_2 t^2 + \dots + c_{m-1} t^{m-1}, \tag{2.1}$$

for arbitrary $c_i \in \mathbb{R}, \quad i = 0, 1, 2, \dots, m - 1, \quad m = [\alpha] + 1.$

2.2 Set-valued maps

Let X and Y be Banach spaces. A set-valued map $G : X \rightarrow \mathcal{P}(Y)$ is said to be compact if $G(X) = \bigcup\{G(y); y \in X\}$ is compact. G has convex (closed, compact) values if $G(y)$ is convex(closed, compact) for every $y \in X$. G is bounded on bounded subsets of X if $G(B)$ is bounded in Y for every bounded subset B of X . A set-valued map G is upper semicontinuous (usc for short) at $z_0 \in X$ if for every open set O containing Gz_0 , there exists a neighborhood V of z_0 such that $G(V) \subset O$. G is usc on X if it is usc at every point of X if G is nonempty and compact-valued then G is usc if and only if G has a closed graph. The set of all bounded closed convex and nonempty subsets of X is denoted by $\mathcal{P}_{b,cl,c}(X)$. A set-valued map $G : J \rightarrow \mathcal{P}_{cl}(X)$ is measurable if for each $y \in X$, the function $t \mapsto dist(y, G(t))$ is measurable on J . If $X \subset Y$, G has a fixed point if there exists $y \in X$ such that $y \in Gy$. Also, $\|G(y)\|_{\mathcal{P}} = sup\{|x|; x \in G(y)\}$. A multivalued map $G : J \rightarrow P_{cl}(\mathbb{R})$ is said to be measurable if for every $y \in \mathbb{R}$, the function

$$t \mapsto d(y, G(t)) = \inf\{|y - z| : z \in G(t)\}$$

is measurable. For more details on multivalued maps see the books of Aubin and Frankowska [6], Deimling [16] and Hu and Papageorgiou [20].

Definition 5. A multivalued map $F : J \times \mathbb{R} \rightarrow \mathcal{P}(\mathbb{R})$ is said to be L^1 -Carathéodory if

- (i) $t \mapsto F(t, y)$ is measurable for each $x \in \mathbb{R}$;
- (ii) $x \mapsto F(t, y)$ is upper semicontinuous for almost all $t \in J$;
- (iii) for each $q > 0$, there exists $\varphi_q \in L^1(J, \mathbb{R}_+)$ such that

$$\|F(t, x)\|_{\mathcal{P}} = \sup\{|v| : v \in F(t, x)\} \leq \varphi_q(t) \quad \text{for all } |x| \leq q \text{ and for a.e. } t \in J.$$

The multivalued map F is said of Carathéodory if it satisfies (i) and (ii).
For each $y \in C(J, \mathbb{R})$, define the set of selections of F by

$$S_{F,y}^1 = \{v \in L^1(J, \mathbb{R}) : v(t) \in F(t, y(t)) \text{ a.e. } t \in J\}.$$

Definition 6. By a solution of BVP (1.1)-(1.2) we mean a function $y \in AC^1(J, \mathbb{R})$ such that

$${}^c D^\alpha y(t) = g(t), \quad t \in J, \quad 1 < \alpha \leq 2, \quad (2.2)$$

$$y(0) = y_0, \quad y \text{ bounded on } J, \quad (2.3)$$

where $g \in S_{F,y}^1$.

Remark 7. Note that for an L^1 -Carathéodory multifunction $F : J \times \mathbb{R} \rightarrow \mathcal{P}_{cl}(\mathbb{R})$ the set $S_{F,y}^1$ is not empty (see [23]).

Lemma 8. (Bohnenblust-Karlin)([13]). Let X be a Banach space and $K \in P_{cl,c}(X)$ and suppose that the operator $G : K \rightarrow P_{cl,c}(K)$ is upper semicontinuous and the set $G(K)$ is relatively compact in X . Then G has a fixed point in K .

3 Main result

We first address a boundary value problem on a bounded domain. Let $n \in \mathbb{N}$, and consider the boundary value problem

$${}^c D^\alpha y(t) \in F(t, y(t)), \quad t \in J_n := [0, n], \quad 1 < \alpha \leq 2, \quad (3.1)$$

$$y(0) = y_0, \quad y'(n) = 0. \quad (3.2)$$

Let $h : J_n \rightarrow \mathbb{R}$ be continuous, and consider the linear fractional order differential equation

$${}^c D^\alpha y(t) = h(t), \quad t \in J_n, \quad 1 < \alpha \leq 2. \quad (3.3)$$

We shall refer to (3.3)-(3.2) as (LP).

By a solution to (LP) we mean a function $y \in AC^1(J_n, \mathbb{R})$ that satisfies equation (3.3) on J_n and condition (3.2).

We need the following auxiliary result:

Lemma 9. A function y is a solution of the fractional integral equation

$$y(t) = y_0 + \int_0^n G_n(t, s)h(s)ds, \quad (3.4)$$

if and only if y is a solution of (LP), where $G(t, s)$ is the Green's function defined by

$$G_n(t, s) = \begin{cases} \frac{-t(n-s)^{\alpha-2}}{\Gamma(\alpha-1)} + \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)}, & 0 \leq s \leq t \leq n, \\ \frac{-t(n-s)^{\alpha-2}}{\Gamma(\alpha-1)}, & 0 \leq t \leq s < n. \end{cases} \quad (3.5)$$

Proof. Let $y \in C(J_n, \mathbb{R})$ be a solution to (LP). Using Lemma 4, we have that

$$y(t) = I^\alpha h(t) - c_0 - c_1 t = \int_0^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} h(s) ds - c_0 - c_1 t,$$

for arbitrary constants c_0 and c_1 . We have by derivation

$$y'(t) = \int_0^t \frac{(t-s)^{\alpha-2}}{\Gamma(\alpha-1)} h(s) ds - c_1.$$

Applying the boundary conditions (3.2), we find that

$$\begin{aligned} c_0 &= -y_0, \\ c_1 &= \int_0^n \frac{(n-s)^{\alpha-2}}{\Gamma(\alpha-1)} h(s) ds. \end{aligned}$$

Reciprocally, let $y \in C(J_n, \mathbb{R})$ satisfying (3.4), then

$$y(t) = y_0 + \int_0^t \left[\frac{-t(n-s)^{\alpha-2}}{\Gamma(\alpha-1)} + \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} \right] h(s) ds + \int_t^n \frac{-t(n-s)^{\alpha-2}}{\Gamma(\alpha-1)} h(s) ds.$$

Then $y(0) = y_0$ and

$$y'(t) = \int_0^n \frac{-(n-s)^{\alpha-2}}{\Gamma(\alpha-1)} h(s) ds + \int_0^t \frac{(t-s)^{\alpha-2}}{\Gamma(\alpha-1)} h(s) ds.$$

Thus, $y'(n) = 0$ and

$${}^c D^{\alpha-1} y(t) = {}^c D^\alpha y(t) = {}^c D^{\alpha-1} \int_0^t \frac{(t-s)^{\alpha-2}}{\Gamma(\alpha-1)} h(s) ds = {}^c D^{\alpha-1} I^{\alpha-1} h(t).$$

□

Remark 10. For each $n > 0$, the function $t \in J_n \mapsto \int_0^n |G_n(t, s)| ds$ is continuous on $[0, n]$, and hence is bounded. Let

$$\tilde{G}_n = \sup \left\{ \int_0^n |G_n(t, s)| ds, t \in J_n \right\}.$$

Definition 11. A function $y \in AC^1(J_n, \mathbb{R})$ is said to be a solution of (3.1)–(3.2) if there exists a function $v \in L^1(J_n, \mathbb{R})$ with $v(t) \in F(t, y(t))$, for a.e. $t \in J_n$, such that the differential equation ${}^c D^\alpha y(t) = v(t)$ on J_n and

$$y(0) = y_0, \quad y'(n) = 0$$

are satisfied.

Theorem 12. *Assume the following hypotheses hold:*

(\mathcal{H}_1) $F : J_n \times \mathbb{R} \rightarrow \mathcal{P}(\mathbb{R})$ is Carathéodory with compact convex values,

(\mathcal{H}_2) there exist $p \in C(J, \mathbb{R}^+)$ and $\psi : [0, \infty) \rightarrow (0, \infty)$ continuous and nondecreasing such that

$$\|F(t, u)\|_{\mathcal{P}} \leq p(t)\psi(|u|) \text{ for } t \in J_n \text{ and each } u \in \mathbb{R};$$

(\mathcal{H}_3) There exists a constant $r > 0$ such that

$$r \geq |y_0| + p_n^* \psi(r) \tilde{G}_n,$$

where

$$p_n^* = \sup\{p(s), s \in J_n\}.$$

Then BVP (3.1)–(3.2) has at least one solution on J_n with $|y(t)| \leq r$ for each $t \in J_n$.

Proof. Fix $n \in \mathbb{N}$ and consider the boundary value problem

$$D^\alpha y(t) \in F(t, y(t)), \quad t \in J_n, \quad 1 < \alpha \leq 2, \quad (3.6)$$

$$y(0) = y_0, \quad y'(n) = 0. \quad (3.7)$$

We begin by showing that (3.6)–(3.7) has a solution $y_n \in C(J_n, \mathbb{R})$ with

$$|y_n(t)| \leq r \text{ for each } t \in J_n.$$

Consider the operator $N : C(J_n, \mathbb{R}) \rightarrow 2^{C(J_n, \mathbb{R})}$ defined by

$$(Ny) = \left\{ h \in C(J, \mathbb{R}) : h(t) = y_0 + \int_0^n G_n(t, s)v(s)ds \right\}$$

where $v \in S_{F, y}^1$, and $G_n(t, s)$ is the Green's function given by (3.5). Clearly, from Lemma 8, the fixed points of N are solutions to (3.6)–(3.7). We shall show that N satisfies the assumptions of Bohnenblust-Karlin's fixed point theorem. The proof will be given in several steps.

Let

$$K = \{y \in C(J_n, \mathbb{R}), \|y\|_n \leq r\},$$

where r is the constant given by (\mathcal{H}_3). It is clear that K is a closed, convex subset of $C(J_n, \mathbb{R})$.

Step1: $N(y)$ is convex for each $y \in K$.

Indeed, if h_1, h_2 belong to $N(y)$, then there exist $v_1, v_2 \in S_{F,y}^1$ such that for each $t \in J_n$ we have

$$h_i(t) = y_0 + \int_0^n G_n(t, s)v_i(s)ds, \quad i = 1, 2.$$

Let $0 \leq d \leq 1$. Then, for each $t \in J$, we have

$$(dh_1 + (1 - d)h_2)(t) = \int_0^n G_n(t, s)(dv_1(s) + (1 - d)v_2(s))ds.$$

Since $S_{F,y}^1$ is convex (because F has convex values), we have

$$dh_1 + (1 - d)h_2 \in N(y).$$

Step 2: $N(K)$ is bounded.

This is clear since $N(K) \subset K$ and K is bounded.

Step 3: $N(K)$ is equicontinuous.

Let $\xi_1, \xi_2 \in J, \xi_1 < \xi_2, y \in K$ and $h \in N(y)$, then

$$\begin{aligned} |h(\xi_2) - h(\xi_1)| &\leq \int_0^n |G(\xi_2, s) - G(\xi_1, s)|v(s)|ds \\ &\leq p_n^*\psi(r) \int_0^n |G_n(\xi_2, s) - G_n(\xi_1, s)|ds. \end{aligned}$$

As $\xi_1 \rightarrow \xi_2$, the right-hand side of the above inequality tends to zero. As a consequence of Steps 1 to 3 together with the Arzelá-Ascoli theorem, we can conclude that $N : K \rightarrow \mathcal{P}(K)$ is compact.

Step 4: N has a closed graph.

Let $y_n \rightarrow y_*, h_n \in N(y_n)$ and $h_n \rightarrow h_*$. We need to show that $h_* \in N(y_*)$. $h_n \in N(y_n)$ means that there exists $v_n \in S_{F,y_n}^1$ such that, for each $t \in J_n$,

$$h_n(t) = y_0 + \int_0^n G_n(t, s)v_n(s)ds.$$

We must show that there exists $v_* \in S_{F,y_*}^1$ such that, for each $t \in J_n$,

$$h_*(t) = y_0 + \int_0^n G_n(t, s)v_*(s)ds.$$

We consider the continuous linear operator

$$\Gamma : L^1(J_n, \mathbb{R}) \rightarrow C(J_n, \mathbb{R}),$$

defined by

$$(\Gamma v)(t) = \int_0^n G_n(t, s)v(s)ds.$$

Since $h_n(t) - y_0 \in \Gamma(S_{F, y_n}^1)$, $|(h_n(t) - y_0) - (h_*(t) - y_0)| \rightarrow 0$ as $n \rightarrow \infty$ and $\Gamma \circ S_F^1$ has a closed graph, then

$$h_* - y_0 \in \Gamma(S_{F, y}^1).$$

So

$$h_* \in N(y_*).$$

Therefore, we deduce from Bohnenblust-Karlin fixed point theorem that N has a fixed point y_n in K which is a solution of BVP (3.6)–(3.7) with

$$|y_n(t)| \leq r \text{ for each } t \in J_n.$$

Diagonalization process

We now use the following diagonalization process. For $k \in \mathbb{N}$, let

$$u_k(t) = \begin{cases} y_k(t), & t \in [0, n_k], \\ y_k(n_k) & t \in [n_k, \infty). \end{cases} \quad (3.8)$$

Here $\{n_k\}_k \in \mathbb{N}^*$ is a sequence of numbers satisfying

$$0 < n_1 < n_2 < \dots < n_k < \dots \uparrow \infty.$$

Let $S = \{u_k\}_{k=1}^\infty$. Notice that

$$|u_k(t)| \leq r \text{ for } t \in [0, n_1], k \in \mathbb{N}.$$

Also for $k \in \mathbb{N}$ and $t \in [0, n_1]$ we have

$$u_{n_k}(t) = y_0 + \int_0^{n_1} G_{n_1}(t, s)v_{n_k}(s)ds,$$

where $v_{n_k} \in S_{F, u_{n_k}}^1$ and thus, for $k \in \mathbb{N}$ and $t, x \in [0, n_1]$ we have

$$u_{n_k}(t) - u_{n_k}(x) = \int_0^{n_1} [G_{n_1}(t, s) - G_{n_1}(x, s)]v_{n_k}(s)ds$$

and by (\mathcal{H}_2) , we have

$$|u_{n_k}(t) - u_{n_k}(x)| \leq p_1^* \psi(r) \int_0^{n_1} |G_{n_1}(t, s) - G_{n_1}(x, s)|ds.$$

The Arzelà-Ascoli Theorem guarantees that there is a subsequence N_1^* of \mathbb{N} and a function $z_1 \in C([0, n_1], \mathbb{R})$ with $u_{n_k} \rightarrow z_1$ in $C([0, n_1], \mathbb{R})$ as $k \rightarrow \infty$ through N_1^* . Let $N_1 = N_1^* \setminus \{1\}$. Notice that

$$|u_{n_k}(t)| \leq r \text{ for } t \in [0, n_2], k \in \mathbb{N}.$$

Also for $k \in \mathbb{N}$ and $t, x \in [0, n_2]$ we have

$$|u_{n_k}(t) - u_{n_k}(x)| \leq p_2^* \psi(r) \int_0^{n_2} |G_{n_2}(t, s) - G_{n_2}(x, s)| ds.$$

The Arzelà-Ascoli Theorem guarantees that there is a subsequence N_2^* of N_1 and a function $z_2 \in C([0, n_2], \mathbb{R})$ with $u_{n_k} \rightarrow z_2$ in $C([0, n_2], \mathbb{R})$ as $k \rightarrow \infty$ through N_2^* . Note that $z_1 = z_2$ on $[0, n_1]$ since $N_2^* \subseteq N_1$. Let $N_2 = N_2^* \setminus \{2\}$. Proceed inductively to obtain for $m \in \{3, 4, \dots\}$ a subsequence N_m^* of N_{m-1} and a function $z_m \in C([0, n_m], \mathbb{R})$ with $u_{n_k} \rightarrow z_m$ in $C([0, n_m], \mathbb{R})$ as $k \rightarrow \infty$ through N_m^* . Let $N_m = N_m^* \setminus \{m\}$.

Define a function y as follows. Fix $t \in (0, \infty)$ and let $m \in \mathbb{N}$ with $s \leq n_m$. Then define $y(t) = z_m(t)$. Then $y \in C([0, \infty), \mathbb{R})$, $y(0) = y_0$ and $|y(t)| \leq r$ for $t \in [0, \infty)$. Again fix $t \in [0, \infty)$ and let $m \in \mathbb{N}$ with $s \leq n_m$. Then for $n \in N_m$ we have

$$u_{n_k}(t) = y_0 + \int_0^{n_m} G_{n_m}(t, s)v_{n_k}(s)ds,$$

Let $n_k \rightarrow \infty$ through N_m to obtain

$$z_m(t) = y_0 + \int_0^{n_m} G_m(x, s)v_m(s)ds,$$

i.e

$$y(t) = y_0 + \int_0^{n_m} G_{n_m}(t, s)v(s)ds,$$

where $v_m \in S_{F, z_m}^1$.

We can use this method for each $x \in [0, n_m]$, and for each $m \in \mathbb{N}$. Thus

$$D^\alpha y(t) \in F(t, y(t)), \text{ for } t \in [0, n_m]$$

for each $m \in \mathbb{N}$ and $\alpha \in (1, 2]$. □

4 An example

Consider the boundary value problem

$${}^c D^\alpha y(t) \in F(t, y(t)), \text{ for } t \in J = [0, \infty), \quad 1 < \alpha \leq 2, \tag{4.1}$$

$$y(0) = 1, \quad y \text{ is bounded on } [0, \infty), \quad (4.2)$$

where ${}^c D^\alpha$ is the Caputo fractional derivative. Set

$$F(t, y) = \{v \in \mathbb{R} : f_1(t, y) \leq v \leq f_2(t, y)\},$$

where $f_1, f_2 : J \times \mathbb{R} \rightarrow \mathbb{R}$ are measurable in t . We assume that for each $t \in J$, $f_1(t, \cdot)$ is lower semi-continuous (i.e, the set $\{y \in \mathbb{R} : f_1(t, y) > \mu\}$ is open for each $\mu \in \mathbb{R}$), and assume that for each $t \in J$, $f_2(t, \cdot)$ is upper semi-continuous (i.e the set $\{y \in \mathbb{R} : f_2(t, y) < \mu\}$ is open for each $\mu \in \mathbb{R}$). Assume that there exists $p \in C(J, \mathbb{R}^+)$ and $\delta \in (0, 1)$ such that

$$\max(|f_1(t, y)|, |f_2(t, y)|) \leq p(t)|y|^\delta, \quad t \in J, \text{ and all } y \in \mathbb{R}.$$

It is clear that F is compact and convex valued, and it is upper semi-continuous (see [16]). Also conditions (\mathcal{H}_1) and (\mathcal{H}_2) are satisfied with

$$\psi(u) = u^\delta, \text{ for each } u \in [0, \infty).$$

From (3.5) we have for $s \leq t$

$$\int_0^t G_n(t, s) ds = \frac{t}{\Gamma(\alpha-1)(\alpha-1)} [(n-t)^{(\alpha-1)} - n^{(\alpha-1)}] + \frac{t^\alpha}{\alpha\Gamma(\alpha)}$$

and for $t \leq s$

$$\int_t^n G_n(t, s) ds = \frac{-t}{(\alpha-1)\Gamma(\alpha-1)} (n-t)^{\alpha-1}.$$

Also since

$$\lim_{c \rightarrow \infty} \frac{c}{1 + p_n^* \psi(c) \tilde{G}_n} = \lim_{c \rightarrow \infty} \frac{c}{\psi(c)} = \lim_{c \rightarrow \infty} \frac{c}{c^\delta} = \infty,$$

then there exists $r > 0$ such that

$$\frac{r}{1 + p_n^* \psi(r) \tilde{G}_n} \geq 1.$$

Hence (\mathcal{H}_3) is satisfied. Then by Theorem 12, BVP (4.1)-(4.2) has a bounded solution on $[0, \infty)$.

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Surveys in Mathematics and its Applications **5** (2010), 99 – 111

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