

# On a linear family of affine connections

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*Dedicated to the memory of Radu Rosca (1908-2005)*

**Abstract.** The aim of this paper is to study some geometrical objects in the deformation algebra associated to a linear family of affine connections. It is pointed out the parallelism between certain algebraic and geometric properties.

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**Key words:** associative deformation algebras, conformal metrics.

## 1 Preliminaries

Let  $M$  be a  $n$ -dimensional ( $n > 3$ ) differentiable manifold. One denotes by  $\mathcal{F}(M)$  the ring of real valued functions, defined on  $M$  and by  $\mathcal{T}_s^r(M)$  the  $\mathcal{F}(M)$ -module of tensor fields of type  $(r, s)$  on  $M$ . Particularly, one denotes  $\mathcal{T}_0^1(M)$ , respectively  $\mathcal{T}_1^0(M)$ , by  $\mathcal{X}(M)$ , respectively  $\Lambda^1(M)$ .

The differentiable manifolds, the differentiable mappings, the tensor fields and the linear connections are supposed to be of class  $C^\infty$ .

Let  $A \in \mathcal{T}_2^1(M)$ . If one defines the product of two vector fields  $X$  and  $Y$  by

$$(*) \quad X \circ Y = A(X, Y),$$

the  $\mathcal{F}(M)$ -module  $\mathcal{X}(M)$  becomes an  $\mathcal{F}(M)$ -algebra. This algebra is called the algebra associated to  $A$  and it is denoted by  $\mathcal{U}(M, A)$ . If  $A = \overline{\nabla} - \nabla$ , where  $\nabla$  and  $\overline{\nabla}$  are two affine connections on  $M$ , then  $\mathcal{U}(M, \overline{\nabla} - \nabla)$  is called the deformation algebra associated to the pair of connections  $(\nabla, \overline{\nabla})$ .

**Definition 1.1** *An element  $X \in \mathcal{U}(M, A)$  is called an almost principal vector field if there exist  $f \in \mathcal{F}(M)$  and a 1-form  $\omega \in \Lambda^1(M)$  such that*

$$A(Z, X) = fZ + \omega(Z)X, \forall Z \in \mathcal{X}(M).$$

- Remark 1.1**
- i) If  $f = 0$ , then  $X$  becomes a principal vector field;
  - ii) If  $\omega = 0$ , then  $X$  is an almost special vector field;
  - iii) If  $f = 0$  and  $\omega = 0$ , then  $X$  is a special vector field;
  - iv) If  $A(X, X) = 0$ , then  $X$  is a 2-nilpotent vector field.

## 2 Main result

Let  $(M, \overset{\circ}{g})$  be a conex,  $n$  - dimensional ( $n > 3$ ) Riemannian manifold. One denotes by  $\overset{\circ}{\nabla}$ , respectively  $\overset{1}{\nabla}$ , the Levi-Civita connection associated to  $\overset{\circ}{g}$ , respectively  $\overset{1}{g} = e^{2u} \overset{\circ}{g}$ , where  $u \in \mathcal{F}(M)$ . One gets the linear family of connections

$$(**) \quad \{\overset{\circ}{\nabla} + \lambda(\overset{1}{\nabla} - \overset{\circ}{\nabla}) | \lambda \in \mathbf{R}\}.$$

**Theorem 2.1** *Let  $\overset{\lambda}{\nabla}$  be an affine connection from the linear family (\*\*). We denote by  $\overset{\lambda}{R}$ , respectively  $\overset{\circ}{R}$ , the curvature tensor field of the linear connection  $\overset{\lambda}{\nabla}$ , respectively  $\overset{\circ}{\nabla}$ . Let  $T_p M$  be the tangent vector space in an arbitrary point  $p \in M$ . The following assertions are equivalent:*

- (i)  $\overset{\lambda}{\nabla} = \overset{\circ}{\nabla}$ ;
  - (ii)  $\overset{\lambda}{R} = \overset{\circ}{R}$ , if  $\overset{\circ}{R}_p: T_p M \times T_p M \times T_p M \mapsto T_p M$  is a surjective mapping,  $\forall p \in M$ ;
  - (iii)  $\overset{\lambda}{\nabla} \overset{\lambda}{R} = \overset{\circ}{\nabla} \overset{\circ}{R}$ , if  $\overset{\circ}{R}_p: T_p M \times T_p M \times T_p M \mapsto T_p M$  is a surjective mapping,  $\forall p \in M$ ;
  - (iv) The deformation algebra  $\mathcal{U}(M, \overset{\lambda}{\nabla} - \overset{\circ}{\nabla})$  is associative;
  - (v)  $\overset{\lambda}{\nabla}$  and  $\overset{\circ}{\nabla}$  have the same geodesics;
  - (vi) All the elements of the algebra  $\mathcal{U}(M, \overset{\lambda}{\nabla} - \overset{\circ}{\nabla})$  are almost principal vector fields;
  - (vii) All the elements of the algebra  $\mathcal{U}(M, \overset{\lambda}{\nabla} - \overset{\circ}{\nabla})$  are almost special vector fields;
  - (viii) All the elements of the algebra  $\mathcal{U}(M, \overset{\lambda}{\nabla} - \overset{\circ}{\nabla})$  are principal vector fields;
  - (ix) All the elements of the algebra  $\mathcal{U}(M, \overset{\lambda}{\nabla} - \overset{\circ}{\nabla})$  are special vector fields;
  - (x) All the elements of the algebra  $\mathcal{U}(M, \overset{\lambda}{\nabla} - \overset{\circ}{\nabla})$  are 2-nilpotent vector fields.
- Proof.* (i)  $\Rightarrow$  (ii)  $\Rightarrow$  (iii), (i)  $\Rightarrow$  (iv), (i)  $\Rightarrow$  (v), (i)  $\Rightarrow$  (vi), (i)  $\Rightarrow$  (vii), (i)  $\Rightarrow$  (viii), (i)  $\Rightarrow$  (ix), (i)  $\Rightarrow$  (x) are obvious.  
 (iii)  $\Rightarrow$  (i) From (iii) one gets

$$(\overset{\lambda}{\nabla}_X \overset{\lambda}{R})(Y, Z, V) = (\overset{\circ}{\nabla}_X \overset{\circ}{R})(Y, Z, V), \forall X, Y, Z, V \in \mathcal{X}(M).$$

Moreover

$$\begin{aligned} (\overset{\lambda}{\nabla}_X \overset{\circ}{R})(Y, Z, V) &= (\overset{\circ}{\nabla}_X \overset{\circ}{R})(Y, Z, V) + \lambda \{A(X, \overset{\circ}{R}(Y, Z)V) - \\ &- \overset{\circ}{R}(A(X, Y), Z)V - \overset{\circ}{R}(Y, A(X, Z))V - \overset{\circ}{R}(Y, Z)A(X, V)\}, \end{aligned}$$

where  $A = \overset{1}{\nabla} - \overset{\circ}{\nabla}$ . The last two formulae imply

$$(2.1) \quad \begin{aligned} (\overset{\lambda}{\nabla}_X \overset{\lambda}{R})(Y, Z, V) &= (\overset{\circ}{\nabla}_X \overset{\circ}{R})(Y, Z, V) + \lambda \{A(X, \overset{\circ}{R}(Y, Z)V) - \\ &- \overset{\circ}{R}(A(X, Y), Z)V - \overset{\circ}{R}(Y, A(X, Z))V - \overset{\circ}{R}(Y, Z)A(X, V)\}. \end{aligned}$$

Permuting circular  $X, Y, Z$  one gets another two analogous relations

$$(2.1') \quad (\overset{\lambda}{\nabla}_Y \overset{\lambda}{R})(Z, X, V) = (\overset{\circ}{\nabla}_Y \overset{\circ}{R})(Z, X, V) + \lambda\{A(Y, \overset{\circ}{R})(Z, X)V - \\ - \overset{\circ}{R}(A(Y, Z), X)V - \overset{\circ}{R}(Z, A(Y, X))V - \overset{\circ}{R}(Z, X)A(Y, V)\},$$

$$(2.1'') \quad (\overset{\lambda}{\nabla}_Z \overset{\lambda}{R})(X, Y, V) = (\overset{\circ}{\nabla}_Z \overset{\circ}{R})(X, Y, V) + \lambda\{A(Z, \overset{\circ}{R})(X, Y)V - \\ - \overset{\circ}{R}(A(Z, X), Y)V - \overset{\circ}{R}(X, A(Z, Y))V - \overset{\circ}{R}(X, Y)A(Z, V)\}.$$

The second Bianchi identities, the relations (2.1), (2.1') and (2.1'') lead to

$$(2.2) \quad \lambda\{A(X, \overset{\circ}{R})(Y, Z)V + A(Y, \overset{\circ}{R})(Z, X)V + A(Z, \overset{\circ}{R})(X, Y)V - \\ - \overset{\circ}{R}(Y, Z)A(X, V) - \overset{\circ}{R}(Z, X)A(Y, V) - \overset{\circ}{R}(X, Y)A(Z, V)\} = 0.$$

From (2.2) we obtain  $\lambda = 0$ , so (i) or

$$(2.2') \quad A(X, \overset{\circ}{R})(Y, Z)V + A(Y, \overset{\circ}{R})(Z, X)V + A(Z, \overset{\circ}{R})(X, Y)V = \\ = \overset{\circ}{R}(Y, Z)A(X, V) - \overset{\circ}{R}(Z, X)A(Y, V) - \overset{\circ}{R}(X, Y)A(Z, V).$$

Let  $\overset{\circ}{g}_{ij}, A_{ij}^k$ , respectively  $\overset{\circ}{R}_{jkl}^i$  be the components of  $\overset{\circ}{g}, A$ , respectively  $\overset{\circ}{R}$ , in a local system of coordinates  $(x^1, x^2, \dots, x^n)$ . In local coordinates (2.2') becomes

$$(2.2'') \quad A_{il}^s \overset{\circ}{R}_{sjk}^r + A_{jl}^s \overset{\circ}{R}_{s ki}^r + A_{kl}^s \overset{\circ}{R}_{sij}^r = \\ A_{js}^r \overset{\circ}{R}_{lki} + A_{ks}^r \overset{\circ}{R}_{lij} + A_{is}^r \overset{\circ}{R}_{ljk}.$$

From  $\overset{1}{g} = e^{2u} \overset{\circ}{g}$  and  $A = \overset{1}{\nabla} - \overset{\circ}{\nabla}$  one has

$$(2.3) \quad A_{jk}^i = \delta_j^i u_k + \delta_k^i u_j - \overset{\circ}{g}_{jk} u^i,$$

where  $u_i = \frac{\partial u}{\partial x^i}, u^i = \overset{\circ}{g}^{ik} u_k, \overset{\circ}{g}^{ik} \overset{\circ}{g}_{ij} = \delta_j^k$ . Relations (2.2') and (2.3) imply

$$(\delta_i^r \overset{\circ}{R}_{ljk}^s + \delta_j^r \overset{\circ}{R}_{lki}^s + \delta_k^r \overset{\circ}{R}_{lij}^s) u_s + (\overset{\circ}{g}_{il} \overset{\circ}{R}_{sjk}^r + \overset{\circ}{g}_{jl} \overset{\circ}{R}_{s ki}^r + \overset{\circ}{g}_{kl} \overset{\circ}{R}_{sij}^r) u^s = 0.$$

Considering  $r = j$  and summing, one gets

$$(2.4) \quad (n-2) \overset{\circ}{R}_{lki}^s u_s + (\overset{\circ}{R}_{lski} + \overset{\circ}{g}_{il} \overset{\circ}{R}_{sk} - \overset{\circ}{g}_{kl} \overset{\circ}{R}_{is}) u^s = 0,$$

where  $\overset{\circ}{R}_{ijkl} = \overset{\circ}{g}_{is} \overset{\circ}{R}_{sjkl}, \overset{\circ}{R}_{ij} = \overset{\circ}{R}_{ikj}^k$ . Multiplying (2.4) by  $\overset{\circ}{g}^{il}$  and summing, we obtain

$$(2.4') \quad (n-2) R_{sk} u^s = 0.$$

From (2.4') and (2.4) one has

$$(2.4'') \quad (n-3) \overset{\circ}{R}_{lki}^s u_s = 0.$$

Since  $n > 3$ , from (2.4'') we get

$$(2.5) \quad \omega(\overset{\circ}{R}(X, Y)Z) = 0, \forall X, Y, Z \in \mathcal{X}(M),$$

where  $\omega$  is the 1-form having the components  $u_1, u_2, \dots, u_n$ .  $\forall p \in M$ , the relation (2.5) implies

$$(2.5') \quad \omega_p(\overset{\circ}{R}_p(X_p, Y_p)Z_p) = 0, \forall X_p, Y_p, Z_p \in T_pM.$$

Since  $\overset{\circ}{R}_p: T_pM \times T_pM \times T_pM \mapsto T_pM$  is a surjective mapping,  $\forall p \in M$ , from (2.5') one has  $\omega_p(T_pM) = 0, \forall p \in M$ , i.e.  $\omega_p = 0, \forall p \in M$ , so  $\omega = 0$ . Therefore  $u_1 = u_2 = \dots = u_n = 0$  and  $u = \text{constant}$ . Hence  $\overset{1}{\nabla} = \overset{\circ}{\nabla}$ .

(iv)  $\Rightarrow$  (i) Since the algebra  $\mathcal{U}(M, \overset{\lambda}{\nabla} - \overset{\circ}{\nabla})$  is abelian, then this algebra is associative if and only if

$$(2.6) \quad \lambda[A(X, A(Y, Z)) - A(Y, A(X, Z))] = 0, \forall X, Y, Z \in \mathcal{X}(M).$$

From (2.6) we get  $\lambda = 0$ , so (i) or

$$(2.6') \quad A(X, A(Y, Z)) = A(Y, A(X, Z)), \forall X, Y, Z \in \mathcal{X}(M).$$

In local coordinates (2.6') becomes

$$(2.6'') \quad A_{sk}^i A_{jl}^s = A_{sl}^i A_{jk}^s.$$

Taking into account (2.6'') and (2.3) one has

$$(2.6''') \quad \delta_k^i u_l u_j - \delta_l^i u_k u_j - g_{il} u^i u_k + g_{jk} u^i u_l + (\delta_k^i g_{jl} - \delta_l^i g_{jk}) u_s u^s = 0.$$

Considering  $i = k$  and summing, one gets

$$(2.6^{iv}) \quad n u_j u_l + (n - 2) g_{jl} u_s u^s = 0.$$

Multiplying the previous relation by  $g^{jl}$ , we have  $u_s u^s = 0$  and also  $u_j u_l = 0$ . Therefore  $u_1 = u_2 = \dots = u_n = 0$  and hence  $\overset{\lambda}{\nabla} = \overset{\circ}{\nabla}$ .

(v)  $\Rightarrow$  (i) The symmetric linear connections  $\overset{\lambda}{\nabla}$  and  $\overset{\circ}{\nabla}$  have the same geodesics if and only if there exists a 1-form  $\overset{\lambda}{\omega} \in \Lambda^1(M)$  such that

$$(2.7) \quad \overset{\lambda}{\nabla}_X Y = \overset{\circ}{\nabla}_X Y + \overset{\lambda}{\omega}(X)Y + \overset{\lambda}{\omega}(Y)X, \forall X, Y \in \mathcal{X}(M).$$

Since  $\overset{1}{g} = e^{2u} \overset{\circ}{g}$ , the deformation tensor  $\overset{\lambda}{A} = \overset{\lambda}{\nabla} - \overset{\circ}{\nabla}$  is given by

$$(2.8) \quad \overset{\circ}{g}(\overset{\lambda}{A}(X, Y), Z) = \lambda\{X(u) \overset{\circ}{g}(Y, Z) + Y(u) \overset{\circ}{g}(X, Z) - Z(u) \overset{\circ}{g}(Y, X)\}.$$

The relations (2.7) and (2.8) lead to

$$(2.9) \quad \overset{\circ}{g}(Y, Z)[\overset{\lambda}{\omega}(X) - \lambda X(u)] + \overset{\circ}{g}(X, Z)[\overset{\lambda}{\omega}(Y) - \lambda Y(u)] - \overset{\circ}{g}(Y, X)Z(u) = 0.$$

For  $Y = X$ , from (2.9) one has

$$(2.10) \quad 2 \overset{\circ}{g}(X, Z)[\overset{\lambda}{\omega}(X) - \lambda X(u)] = Z(u) \overset{\circ}{g}(X, X), \forall X, Z \in \mathcal{X}(M).$$

From (2.10) we get

$$(2.10') \quad \begin{aligned} & 2 \overset{\circ}{g}_p(X_p, Z_p)[\overset{\lambda}{\omega}_p(X_p) - \lambda X_p(u)] = \\ & = Z_p(u) \overset{\circ}{g}_p(X_p, X_p), \forall X_p, Z_p \in T_p M \setminus \{0\}. \end{aligned}$$

Since  $n > 3$ ,  $\forall p \in M$  and  $Z_p \in T_p M \setminus \{0\}$  there exists a vector  $X_p \in T_p M \setminus \{0\}$  such that  $\overset{\circ}{g}_p(X_p, Z_p) = 0$ . From (2.10') one has  $Z_p(u) = 0$ ,  $\forall p \in M, \forall Z_p \in T_p M \setminus \{0\}$ . Therefore  $u = \text{constant}$  and from (2.8) we get  $\overset{\circ}{g}(\overset{\lambda}{A}(X, Y), Z) = 0, \forall X, Y, Z \in \mathcal{X}(M)$ . Hence  $\overset{\lambda}{\nabla} = \overset{\circ}{\nabla}$ .

vi)  $\Rightarrow$  v) All the elements of the deformation algebra  $\mathcal{U}(M, \overset{\lambda}{\nabla} - \overset{\circ}{\nabla})$  are almost special vector fields if and only if there exist two 1-forms  $\omega$  and  $\eta$  on  $M$  such that

$$(2.11) \quad \overset{\lambda}{\nabla}_X Y = \overset{\circ}{\nabla}_X Y + \omega(X)Y + \eta(Y)X, \forall X, Y \in \mathcal{X}(M).$$

The linear connections  $\overset{\lambda}{\nabla}$  and  $\overset{\circ}{\nabla}$  are symmetric, so from (2.11) one has  $\omega = \eta$ , i.e. (v).

vii)  $\Rightarrow$  i), viii)  $\Rightarrow$  i), ix)  $\Rightarrow$  i), x)  $\Rightarrow$  i) (it is used the fact that  $\mathcal{U}(M, \overset{\lambda}{\nabla} - \overset{\circ}{\nabla})$  is an abelian algebra).

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