

ON A CLASS OF QUASILINEAR ELLIPTIC SYSTEMS IN \mathbb{R}^N INVOLVING CRITICAL SOBOLEV EXPONENTS

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ABSTRACT. We study here a class of quasilinear elliptic systems involving the p -Laplacian operator. Under some suitable assumptions on the nonlinearities, we show the existence result by using a fixed point theorem.

1. INTRODUCTION AND PRELIMINARIES

This paper is concerned with the existence of nontrivial solution to the quasilinear elliptic system of the form

$$\begin{cases} -\Delta_p u = f(x) |u|^{p^*-2} u + \lambda \frac{\partial F}{\partial u}(x, u, v), & \text{in } \mathbb{R}^N, \\ -\Delta_q v = g(x) |v|^{q^*-2} v + \mu \frac{\partial F}{\partial v}(x, u, v), & \text{in } \mathbb{R}^N, \\ u(x), v(x) \rightarrow 0, & \text{as } |x| \rightarrow +\infty \end{cases} \quad (1.1)$$

where Δ_p is the so called p -Laplacian operator, i.e. $\Delta_p u = \operatorname{div}(|\nabla u|^{p-2} \nabla u)$. f , g and F are real-valued functions satisfying some assumptions; u and v are unknown real valued functions defined in \mathbb{R}^N and belonging to appropriate function spaces; λ and μ are positive parameters, which can be taken equal to 1, and the parameters p and q are real numbers satisfying $2 \leq p, q < N$. The real number $p^* = \frac{Np}{N-p}$ designates the critical Sobolev exponent of p .

In recent years, several authors use different methods to solve quasilinear equations or systems defined in bounded or unbounded domains. Djellit and Tas [6] investigated a system such as (1.1) by employing variational approach.

In this work, motivated by [A. Djellit, S. Tas. On some nonlinear elliptic systems. *Nonl. Anal.* 59 (2004), 695-706], we show an existence result by using a fixed point theorem due to Bohnenblust-Karlin.

This paper is divided into three sections, organized as follows: in Section 2, we give some notation and hypotheses; Section 3 is devoted to establish an existence theorem.

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2. NOTATION AND HYPOTHESES

We denote by $D^{1,m}(\mathbb{R}^N)$ the completion of $C_0^\infty(\mathbb{R}^N)$ in the norm

$$\|u\|_{1,m} \equiv \|\nabla u\|_m = \left(\int_{\mathbb{R}^N} |\nabla u|^m dx \right)^{\frac{1}{m}}; \quad 1 < m < N.$$

It is well known that $D^{1,m}(\mathbb{R}^N)$ is a uniformly convex Banach space and may be written as

$$D^{1,m}(\mathbb{R}^N) = \{u \in L^{m^*}(\mathbb{R}^N); \quad \nabla u \in (L^m(\mathbb{R}^N))^N\}.$$

Moreover, we have the following Sobolev constant defined by

$$S_m \equiv C^{-m}(N, m) = \inf \left\{ \frac{\|u\|_{1,m}^m}{\|u\|_{m^*}^m}, \quad u \in D^{1,m}(\mathbb{R}^N) \setminus \{0\} \right\}.$$

We denote Z by the product space $Z \equiv D^{1,p}(\mathbb{R}^N) \times D^{1,q}(\mathbb{R}^N)$ with the norm $\|(u, v)\|_Z = \|u\|_{1,p} + \|v\|_{1,q}$; Z^* is the dual space of Z equipped with the dual norm $\|\cdot\|_*$.

In addition, let T and N be two operators defined from Z into Z^* by

$$T(u, v)(w, z) = \int_{\mathbb{R}^N} |\nabla u|^{p-2} \nabla u \nabla w dx + \int_{\mathbb{R}^N} |\nabla v|^{q-2} \nabla v \nabla z dx,$$

and

$$\begin{aligned} N(u, v)(w, z) = & \int_{\mathbb{R}^N} [(f(x) |u|^{p^*-2} u + \lambda \frac{\partial F}{\partial u}(x, u, v))w \\ & + (g(x) |v|^{q^*-2} v + \mu \frac{\partial F}{\partial v}(x, u, v))z] dx, \quad \forall (u, v), (w, z) \in Z. \end{aligned}$$

Now, we recall the fixed point theorem due to Bohnenblust-Karlin (see [11]).

Theorem 2.1.([11]) Let Z be a Banach space, let $B \subset Z$ be a nonempty, closed, convex set and let $S : B \rightarrow 2^B$ be a set-valued mapping satisfying

- (a) for each $U \in Z$, the set SU is nonempty, closed and convex,
- (b) S is closed,
- (c) the set $S(B) = \bigcup_{U \in B} SU$ is relatively compact.

Then S has a fixed point in B i.e. there is $U \in B$ such that $U \in SU$.

Our aim is to find the condition of the above theorem. The fixed points of the set-valued mapping S are precisely the weak solutions of system (1.1). In other words, we state the existence of a pair $(u, v) \in Z$ such that $T(u, v)(w, z) = N(u, v)(w, z)$, $\forall (w, z) \in Z$, under the following assumptions.

- (H1) f and g are positive and bounded functions.
- (H2) $F \in C^1(\mathbb{R}^N, \mathbb{R}, \mathbb{R})$ and $F(x, 0, 0) = 0$.
- (H3) For all $U = (u, v) \in \mathbb{R}^2$ and for almost every $x \in \mathbb{R}^N$

$$\begin{aligned}
& \left| \frac{\partial F}{\partial u}(x, U) \right| \leq a_1(x) |U|^{p_1-1} + a_2(x) |U|^{p_2-1} \\
& \left| \frac{\partial F}{\partial v}(x, U) \right| \leq b_1(x) |U|^{q_1-1} + b_2(x) |U|^{q_2-1} \\
& \text{where } 1 < p_1, q_1 < \min(p, q), \quad \max(p, q) < p_2, q_2 < \min(p^*, q^*) \\
& a_i \in L^{\alpha_i}(\mathbb{R}^N) \cap L^{\beta_i}(\mathbb{R}^N), \quad b_i \in L^{\gamma_i}(\mathbb{R}^N) \cap L^{\delta_i}(\mathbb{R}^N), \quad i = 1, 2. \\
& \alpha_i = \frac{p^*}{p^* - p_i}, \quad \gamma_i = \frac{q^*}{q^* - q_i}, \quad \beta_i = \frac{p^* q^*}{p^* q^* - p^*(p_i - 1) - q^*}, \\
& \delta_i = \frac{p^* q^*}{p^* q^* - q^*(q_i - 1) - p^*}.
\end{aligned}$$

3. EXISTENCE OF SOLUTIONS

The goal of this section is to establish the following result.

Theorem 3.1. Under hypotheses $(H_1) - (H_3)$, the equation $T(u, v) = N(u, v)$ has a solution in Z .

First, two preliminary results. The first one concerns the properties of the operator T while the second one describes the property of the operator N .

Lemma 3.2. The operator T is monotone, hemicontinuous, coercive and satisfies the following property:

$$[(u_n, v_n) \rightharpoonup (u, v), T(u_n, v_n) \rightarrow T(u, v)] \Rightarrow (u_n, v_n) \rightarrow (u, v). \quad (3.1)$$

Proof. Let us denote by T_p the operator defined from $D^{1,p}(\mathbb{R}^N)$ into $(D^{1,p}(\mathbb{R}^N))^*$ by

$$T_p(u)w = \int_{\mathbb{R}^N} |\nabla u|^{p-2} \nabla u \cdot \nabla w dx, \quad \forall u, w \in D^{1,p}(\mathbb{R}^N)$$

and T_q the corresponding one with p replaced by q .

Observe that $T(u, v)(w, z) = T_p(u)w + T_q(v)z$, $\forall (u, v), (w, z) \in Z$. T_p, T_q are duality mappings on $D^{1,p}(\mathbb{R}^N)$ and $D^{1,q}(\mathbb{R}^N)$ corresponding to the Guage functions $\Phi_p(t) = t^{p-1}$ and $\Phi_q(t) = t^{q-1}$, respectively. Hence T_p, T_q are demicontinuous (see [3, p.175]).

So, for $(u_n, v_n) \rightarrow (u, v)$ in Z , we have $T_p(u_n) \rightharpoonup T_p(u)$ in $(D^{1,p}(\mathbb{R}^N))^*$ and $T_q(v_n) \rightharpoonup T_q(v)$ in $(D^{1,q}(\mathbb{R}^N))^*$. Since $D^{1,p}(\mathbb{R}^N)$ and $D^{1,q}(\mathbb{R}^N)$ are reflexive, and the dual space of any reflexive space is reflexive. we get $T(u_n, v_n) = T_p(u_n) + T_q(v_n) \rightharpoonup T_p(u) + T_q(v) = T(u, v)$ in Z^* , i.e. T is demicontinuous. So, it is hemicontinuous. We note according to [2] that $\forall \lambda, \mu \in \mathbb{R}^N$

$$|\lambda - \mu|^p \leq (|\lambda|^{p-2} \lambda - |\mu|^{p-2} \mu) \cdot (\lambda - \mu) \quad \text{if } p \geq 2.$$

Replacing λ and μ by $\nabla u, \nabla v$ respectively and integrating over \mathbb{R}^N , we obtain

$$\int_{\mathbb{R}^N} |\nabla u - \nabla v|^p \leq \int_{\mathbb{R}^N} (|\nabla u|^{p-2} \nabla u - |\nabla v|^{p-2} \nabla v) \cdot (\nabla u - \nabla v) \quad \text{if } p \geq 2. \quad (3.2)$$

By virtue of (3.2) we show that T_p (similarly T_q) is monotone, indeed,

$$\begin{aligned} (T_p u - T_p w)(u - w) &= T_p u(u - w) - T_p w(u - w) \\ &= \int_{\mathbb{R}^N} (|\nabla u|^{p-2} \nabla u \nabla(u - w)) dx \\ &\quad - \int_{\mathbb{R}^N} (|\nabla w|^{p-2} \nabla w \nabla(u - w)) dx \\ &= \int_{\mathbb{R}^N} (|\nabla u|^{p-2} \nabla u - |\nabla w|^{p-2} \nabla w) (\nabla u - \nabla w) dx \\ &\geq \int_{\mathbb{R}^N} |\nabla u - \nabla w|^p = \|u - w\|_{1,p}^p \geq 0. \end{aligned}$$

So, T is monotone. On the other hand, T is coercive since $T(u, v)(u, v) = \|u\|_{1,p}^p + \|v\|_{1,q}^q$. Now we show that T satisfies property (3.1).

Let us take a sequence $(u_n, v_n) \in Z$ such that $(u_n, v_n) \rightharpoonup (u, v)$ in Z and $T(u_n, v_n) \rightarrow T(u, v)$ in Z^* . Then $T(u_n, v_n)(u_n, v_n) \rightarrow T(u, v)(u, v)$. So $\|u_n\|_{1,p}^p + \|v_n\|_{1,q}^q \rightarrow \|u\|_{1,p}^p + \|v\|_{1,q}^q$. According to the uniform convexity of Z , $(u_n, v_n) \rightarrow (u, v)$ in Z . \square

Lemma 3.3. Under hypothesis $(H_1) - (H_3)$, the operator N is compact.

Proof. Let B_R be the ball of radius R , centered at the origin of \mathbb{R}^N . We put $B'_R = \mathbb{R}^N - B_R$ and we designate N_R the operator defined from $Z_R \equiv D^{1,p}(B_R) \times D^{1,q}(B_R)$ into Z_R^* by

$$\begin{aligned} N_R(u, v)(w, z) &= \int_{B_R} [(f(x) |u|^{p^*-2} u + \lambda \frac{\partial F}{\partial u}(x, u, v))w \\ &\quad + (g(x) |v|^{q^*-2} v + \mu \frac{\partial F}{\partial v}(x, u, v))z] dx. \end{aligned}$$

Let $\{(u_n, v_n)\}$ be a bounded sequence in Z . There is a subsequence denoted again as $\{(u_n, v_n)\}$, weakly convergent to (u, v) in Z . For $(w, z) \in Z$, we have

$$\begin{aligned} &|N(u_n, v_n)(w, z) - N(u, v)(w, z)| \\ &= |N_R(u_n, v_n)(w, z) - N_R(u, v)(w, z)| \\ &+ \left| \int_{B'_R} f(x) (|u_n|^{p^*-2} u_n - |u|^{p^*-2} u) w dx \right| \\ &+ \left| \int_{B'_R} g(x) (|v_n|^{q^*-2} v_n - |v|^{q^*-2} v) z dx \right| \\ &+ \left| \int_{B'_R} \lambda \left(\frac{\partial F}{\partial u}(x, u_n, v_n) - \frac{\partial F}{\partial u}(x, u, v) \right) w dx \right| \\ &+ \left| \int_{B'_R} \mu \left(\frac{\partial F}{\partial v}(x, u_n, v_n) - \frac{\partial F}{\partial v}(x, u, v) \right) z dx \right|. \end{aligned} \tag{3.3}$$

Since the restriction operator $(u, v) \rightarrow (u, v)|_{B_R}$ is continuous from $D^{1,p}(\mathbb{R}^N) \times D^{1,q}(\mathbb{R}^N)$ into $D^{1,p}(B_R) \times D^{1,q}(B_R)$, we have $(u_n, v_n) \rightharpoonup (u, v)$ in $D^{1,p}(B_R) \times D^{1,q}(B_R)$. We have also that the embeddings $D^{1,p}(B_R) \hookrightarrow L^p(B_R)$ and $D^{1,q}(B_R) \hookrightarrow L^q(B_R)$ are compact, so

$$\begin{aligned} u_n &\rightarrow u && \text{a.e. in } B_R, \\ v_n &\rightarrow v && \text{a.e. in } B_R. \end{aligned}$$

Hypothesis (H_3) gives

$$\begin{aligned} \left| \frac{\partial F}{\partial u}(x, u_n, v_n)w \right| &\leq [a_1(x)(|u_n|^{p_1-1} + |v_n|^{p_1-1}) \\ &\quad + a_2(x)(|u_n|^{p_2-1} + |v_n|^{p_2-1})] |w|, \end{aligned} \quad (3.4)$$

and

$$\begin{aligned} \left| \frac{\partial F}{\partial v}(x, u_n, v_n)z \right| &\leq [b_1(x)(|u_n|^{q_1-1} + |v_n|^{q_1-1}) \\ &\quad + b_2(x)(|u_n|^{q_2-1} + |v_n|^{q_2-1})] |z|. \end{aligned} \quad (3.5)$$

Using Holder's inequality and Sobolev's imbedding, and the fact that $a_i \in L^{\alpha_i}(\mathbb{R}^N) \cap L^{\beta_i}(\mathbb{R}^N)$, $b_i \in L^{\gamma_i}(\mathbb{R}^N) \cap L^{\delta_i}(\mathbb{R}^N)$, we get that the right hand side of inequalities (3.4), (3.5) belong to $L^1(B_R)$. Hence under hypotheses $(H_1) - (H_3)$ and by using Holder's inequality and Sobolev's imbedding, according to Dominated convergence theorem, we obtain, the first expression on the right hand side of the inequality (3.3) tends to 0 as $n \rightarrow +\infty$; Taking (H_1) and (H_3) into account, and the fact that for $i = 1, 2$,

$$\begin{aligned} \|a_i\|_{L^{\alpha_i}(B'_R)} + \|a_i\|_{L^{\beta_i}(B'_R)} &\rightarrow 0, \\ \|b_i\|_{L^{\gamma_i}(B'_R)} + \|b_i\|_{L^{\delta_i}(B'_R)} &\rightarrow 0, \end{aligned}$$

as $R \rightarrow +\infty$; we obtain, the other expressions tend also to 0 as R sufficiently large. So, the compactness of N follows. \square

Lemma 3.4. Suppose that (H_1) and (H_3) hold. There is a constant $k > 0$ such that $T(u, v) = N(\sigma, \rho)$ and $\|(\sigma, \rho)\|_Z \leq k$ implies $\|(u, v)\|_Z \leq k$.

Proof. Let (u, v) , $(\sigma, \rho) \in Z$ be such that $T(u, v) = N(\sigma, \rho)$, then

$$T(u, v)(w, z) = N(\sigma, \rho)(w, z), \quad \forall (w, z) \in Z.$$

In particular, we have $T(u, v)(u, 0) = N(\sigma, \rho)(u, 0)$ i.e.

$$\|u\|_{1,p}^p = \int_{\mathbb{R}^N} |\nabla u|^p dx = \int_{\mathbb{R}^N} (f(x) |\sigma|^{p^*-2} \sigma + \lambda \frac{\partial F}{\partial u}(x, \sigma, \rho)) u dx. \quad (3.6)$$

In view of (H_1) and (H_3) , by using Holder's inequality and Sobolev's imbedding we obtain

$$\begin{aligned} \int_{\mathbb{R}^N} f(x) |\sigma|^{p^*-2} \sigma u dx &\leq c' \int_{\mathbb{R}^N} |\sigma|^{p^*-1} |u| dx \\ &\leq c' \|u\|_{p^*} \|\sigma\|_{p^*}^{p^*-1} \leq c_1 \|u\|_{1,p} \|\sigma\|_{1,p}^{p^*-1}, \end{aligned} \quad (3.7)$$

and

$$\begin{aligned} \int_{\mathbb{R}^N} \lambda \frac{\partial F}{\partial u}(x, \sigma, \rho) u dx &\leq c_1 \|u\|_{1,p} (\|a_1\|_{\alpha_1} \|\sigma\|_{1,p}^{p_1-1} + \|a_1\|_{\beta_1} \|\rho\|_{1,q}^{p_1-1} \\ &\quad + \|a_2\|_{\alpha_2} \|\sigma\|_{1,p}^{p_2-1} + \|a_2\|_{\beta_2} \|\rho\|_{1,q}^{p_2-1}) \end{aligned} \quad (3.8)$$

So, by virtue of (3.6), (3.7) and (3.8) we get

$$\begin{aligned} \|u\|_{1,p}^{p-1} &\leq c_1 \lambda (\|\sigma\|_{1,p}^{p^*-1} + \|a_1\|_{\alpha_1} \|\sigma\|_{1,p}^{p_1-1} + \|a_1\|_{\beta_1} \|\rho\|_{1,q}^{p_1-1} \\ &\quad + \|a_2\|_{\alpha_2} \|\sigma\|_{1,p}^{p_2-1} + \|a_2\|_{\beta_2} \|\rho\|_{1,q}^{p_2-1}). \end{aligned} \quad (3.9)$$

In the same way, we have

$$\begin{aligned} \|v\|_{1,q}^{q-1} &\leq c_2 \mu(\|\rho\|_{1,q}^{q^*-1} + \|b_1\|_{\delta_1} \|\sigma\|_{1,p}^{q_1-1} + \|b_1\|_{\gamma_1} \|\rho\|_{1,q}^{q_1-1} \\ &\quad + \|b_2\|_{\delta_2} \|\sigma\|_{1,p}^{q_2-1} + \|b_2\|_{\gamma_2} \|\rho\|_{1,q}^{q_2-1}). \end{aligned} \tag{3.10}$$

If $\|(\sigma, \rho)\|_Z = \|\sigma\|_{1,p} + \|\rho\|_{1,q} \leq k$, we have $\|\sigma\|_{1,p} \leq k$ and $\|\rho\|_{1,q} \leq k$. So, in view of (3.9), (3.10) we get

$$\begin{aligned} \|u\|_{1,p}^{p-1} &\leq c\lambda(k^{p^*-1} + k^{p_1-1} + k^{p_2-1}), \\ \|v\|_{1,q}^{q-1} &\leq c\mu(k^{q^*-1} + k^{q_1-1} + k^{q_2-1}). \end{aligned}$$

Since $p_1 < p_2 < p^*$ and $q_1 < q_2 < q^*$, there is a $k > 0$ such that $c(k^{p^*-1} + k^{p_1-1} + k^{p_2-1}) \leq (\frac{k}{2})^{p-1}$ and $c(k^{q^*-1} + k^{q_1-1} + k^{q_2-1}) \leq (\frac{k}{2})^{q-1}$. So, $\|\sigma\|_{1,p} + \|\rho\|_{1,q} \leq k$ implies $\|u\|_{1,p} + \|v\|_{1,q} \leq k$. \square

We have on the following proposition, which is standard in the theory of monotone operators.

Proposition 3.5. Let X be a real normed space, $T : X \rightarrow X^*$ be a monotone, hemicontinuous operator and let $w \in X, f \in X^*$.

The following two assertions are equivalent

- (a) $Tw = f$
- (b) $\langle Tz - f, z - w \rangle \geq 0$ for all $z \in X$.

Now, we are ready to give the following proof.

Proof of Theorem 3.1. In view of lemma 3.4, let $B \subset Z$ be the closed ball of radius k centered at the origin. We define the operator S from B into 2^B by

$$(\sigma, \rho) \mapsto S(\sigma, \rho) = \{(u, v); T(u, v) = N(\sigma, \rho)\}.$$

By virtue of lemma 3.2, T is monotone, hemicontinuous and coercive, then according to Browder's Theorem (see[13,p.557]), $S(\sigma, \rho)$ is nonempty, convex, closed and bounded for every $(\sigma, \rho) \in B$. Furthermore, the operator S is closed, indeed, let $\{(\sigma_n, \rho_n)\} \subset B; (\sigma_n, \rho_n) \rightarrow (\sigma, \rho) \in Z$, and $\{(u_n, v_n)\} \subset Z$ such that $(u_n, v_n) \in S(\sigma_n, \rho_n)$ and $(u_n, v_n) \rightarrow (u, v)$ in Z .

Since N is continuous, it is demicontinuous. We have also that T is demicontinuous, so we can write

$$\begin{aligned} T(u_n, v_n) &\rightharpoonup T(u, v), \\ N(\sigma_n, \rho_n) &\rightharpoonup N(\sigma, \rho). \end{aligned}$$

Since $(u_n, v_n) \in S(\sigma_n, \rho_n)$, we have $T(u_n, v_n) = N(\sigma_n, \rho_n)$. Hence $T(u_n, v_n) \rightharpoonup N(\sigma, \rho)$. Since the weak limit is unique, we get

$$T(u, v) = N(\sigma, \rho).$$

On the other hand, B is closed, consequently $(\sigma, \rho) \in B$ and then $(u, v) \in S(\sigma, \rho)$. Now, let us show that $S(B) = \bigcup_{(\sigma, \rho) \in B} S(\sigma, \rho)$ is relatively compact.

Let $(u_n, v_n) \subset \bigcup_{(\sigma, \rho) \in B} S(\sigma, \rho)$ and $(\sigma_n, \rho_n) \subset B$ be such that

$$T(u_n, v_n) = N(\sigma_n, \rho_n). \tag{3.11}$$

In view of lemma 3.3, $N(B)$ is relatively compact. So there exists $H \in Z^*$ such that $N(\sigma_n, \rho_n) \rightarrow H$. Hence by (3.11) we have $T(u_n, v_n) \rightarrow H$. Consequently $T(u_n, v_n)$ is bounded. Since T is coercive, (u_n, v_n) is also bounded; otherwise, if

$\|(u_n, v_n)\| \rightarrow \infty$, we have $T(u_n, v_n) \rightarrow \infty$, which is a contradiction. Hence, we may choose a subsequence denoted again by $\{(u_n, v_n)\}$, weakly convergent to (u_0, v_0) in Z .

The monotonicity of T leads to $(T(u, v) - T(u_n, v_n))(u - u_n, v - v_n) \geq 0, \forall (u, v) \in Z$, and passing to the limit, we obtain

$$(T(u, v) - H)(u - u_0, v - v_0) \geq 0, \quad \forall (u, v) \in Z,$$

i.e. $\langle T(u, v) - H, (u, v) - (u_0, v_0) \rangle \geq 0, \forall (u, v) \in Z$. So by virtue of proposition 3.5, we have $T(u_0, v_0) = H$. Taking the condition (3.1) into account, we obtain the convergence of (u_n, v_n) to (u_0, v_0) . Finally, by Bohnenblust-Karlin fixed point theorem, S possesses a fixed point. i.e. there exist $(\sigma_0, \rho_0) \in B$ such that $T(\sigma_0, \rho_0) = N(\sigma_0, \rho_0)$. \square

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