

ON SOLUTIONS OF A SYSTEM OF HIGHER-ORDER NONLINEAR FRACTIONAL DIFFERENTIAL EQUATIONS

(COMMUNICATED BY DOUGLAS R. ANDERSON)

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ABSTRACT. A system of higher-order nonlinear fractional differential equations is studied in this article, and some sufficient conditions for existence and uniqueness of a solution for the system is established by the nonlinear alternative of Leray-Schauder and Banach contraction principle.

1. INTRODUCTION AND PRELIMINARIES

This article is concerned with the initial value problem for the following system of fractional order differential equations:

$${}^c D^\rho u(t) = f\left(t, v^{(n)}(t), {}^c D^\beta v(t)\right), \quad u^{(k)}(0) = \eta_k, \quad 0 < t \leq T, \quad (1.1)$$

$${}^c D^\sigma v(t) = g\left(t, u^{(n)}(t), {}^c D^\alpha u(t)\right), \quad v^{(k)}(0) = \xi_k, \quad 0 < t \leq T, \quad (1.2)$$

where ${}^c D$ denotes the Caputo fractional derivative, $f, g : [0, T] \times \mathbb{R}^2 \rightarrow \mathbb{R}$ are given functions, $\rho, \sigma \in (m-1, m), \alpha, \beta \in (n-1, n), m, n \in \mathbb{N}, \rho > \beta, \sigma > \alpha, k = 0, 1, 2, \dots, m-1, T > 0$, and η_k, ξ_k are suitable real constants. In this article, we consider the case that all of ρ, σ, β and α are non-integer valued.

Recently, fractional order differential equations and systems have been of great interest. For example, in 2010, Li[9] discussed the existence and uniqueness of mild solution for

$$\begin{aligned} \frac{d^q x(t)}{dt^q} &= -Ax(t) + f(t, x(t), Gx(t)), \quad t \in [0, T], \\ x(0) + g(x) &= x_0. \end{aligned} \quad (1.3)$$

Li and Guérékata[10] studied mild solutions of the fractional integrodifferential equations as follows

$$\frac{d^q x(t)}{dt^q} + Ax(t) = f(t, x(t)) + \int_0^t a(t-s)g(s, x(s))ds, \quad t \in [0, T], \quad x(0) = x_0. \quad (1.4)$$

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In 2011, Anguraj, Karthikeyan and Trujillo[1] investigated the existence and the uniqueness of the solution for the following fractional integrodifferential equation

$$\begin{aligned} \frac{d^q x(t)}{dt^q} &= f\left(t, x(t), \int_0^t k(t, s, x(s)) ds, \int_0^1 h(t, s, x(s)) ds\right), \quad t \in [0, 1], \\ x(0) &= \int_0^1 g(s)x(s) ds. \end{aligned} \quad (1.5)$$

Guo and Liu[4] studied the existence of unique solutions of initial value problems of the following system of fractional order differential equations with infinite delay

$$\begin{aligned} D^\alpha y_1(t) &= f_1[t, y_{1t}, y_{2t}], \quad t \in [0, b], \\ y_1(t) &= \phi_1(t), \quad t \in (-\infty, 0], \\ D^\alpha y_2(t) &= f_2[t, y_{1t}, y_{2t}], \quad t \in [0, b], \\ y_2(t) &= \phi_2(t), \quad t \in (-\infty, 0]. \end{aligned} \quad (1.6)$$

For detailed discussion on this topic, refer to the monographs of Kilbas et al.[5], and the papers by Ahmad and Alsaedi [2], Guo and Liu [3], Kosmatov [6], Lakshmikantham and Vatsala [7], Li and Deng [8], Su [11], Goodrich [12,13], Bonilla et al. [14], Bai and Fang [15], Kobayashi [16], Wang et al. [17] and the references therein.

Applying the nonlinear alternative of Leray-Schauder, we obtain a result of existence of a solution for system (1.1)-(1.2). The uniqueness of a solution for the system is established by Banach contraction principle.

The following notations, definitions, and preliminary facts will be used throughout this paper.

Let $X = \{u : u \in C([0, T])\}$ and $Y = \{v : v \in C([0, T])\}$ be normed spaces with the sup-norm $\|u\|_X$ and $\|v\|_Y$, respectively, where $C([0, T])$ denotes the space of all continuous functions defined on $[0, T]$. Then, $(X \times Y, \|\cdot\|_{X \times Y})$ is a normed space endowed with the sup-norm given by $\|(u, v)\|_{X \times Y} := \max\{\|u\|_X, \|v\|_Y\}$.

Definition 1.1. For a function $f \in C^m([0, T])$, $m \in \mathbb{N}$, where $C^m([0, T])$ denotes the space of all continuous functions with m th order derivative, the Caputo derivative of fractional order $\alpha \in (m-1, m)$ is defined by

$${}^c D^\alpha f(t) = \frac{1}{\Gamma(m-\alpha)} \int_0^t (t-s)^{m-\alpha-1} f^{(m)}(s) ds. \quad (1.7)$$

Definition 1.2. The Riemann-Liouville fractional integral of order α , inversion of D^α , is defined by

$$I^\alpha f(t) = \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} f(s) ds. \quad (1.8)$$

Lemma 1.3. [8] If $\alpha \in (m-1, m)$, $m \in \mathbb{N}$, $f \in C^m([0, T])$ and $g \in C^1([0, T])$, then

$$\begin{aligned} (1) \quad & {}^c D^\alpha I^\alpha g(t) = g(t); \\ (2) \quad & I^\alpha ({}^c D^\alpha) f(t) = f(t) - \sum_{k=0}^{m-1} \frac{t^k}{k!} f^{(k)}(0). \end{aligned}$$

Lemma 1.4. [6] If $m-1 < \alpha < \beta < m$ and $f \in C^m([0, T])$, then for all $k \in \{1, 2, \dots, m-1\}$ and for all $t \in [0, T]$, the following relations hold:

$${}^c D^{\beta-m+k} f^{m-k}(t) = {}^c D^\beta f(t), \quad (1.9)$$

$${}^c D^{\beta-\alpha} {}^c D^\alpha f(t) = {}^c D^\beta f(t). \quad (1.10)$$

Theorem 1.5. *(the nonlinear alternative of Leray-Schauder) Let X be a normed linear space, $S \subset X$ be a convex set, U be open in S with $0 \in U$, and $F : \bar{U} \rightarrow S$ be a continuous and compact mapping. Then either the mapping F has a fixed point in \bar{U} or there exist $n \in \partial U$ and $\lambda \in (0, 1)$ with $n = \lambda F n$.*

Now list the following hypotheses for convenience:

(H1) $f : [0, T] \times \mathbb{R}^2 \rightarrow \mathbb{R}$ are continuously differentiable function with $f(0, 0, 0) = 0$ and $f(t, 0, 0) \neq 0$ on a compact subinterval of $(0, T]$;

(H2) $g : [0, T] \times \mathbb{R}^2 \rightarrow \mathbb{R}$ are continuously differentiable function with $g(0, 0, 0) = 0$ and $g(t, 0, 0) \neq 0$ on a compact subinterval of $(0, T]$;

(H3) there exist nonnegative functions $a_1, a_2, a_3, b_1, b_2, b_3 \in C([0, T])$ such that

$$\begin{aligned} |f(t, x, y)| &\leq a_1(t) + a_2(t)|x| + a_3(t)|y|, \quad t \in [0, T], \\ |g(t, x, y)| &\leq b_1(t) + b_2(t)|x| + b_3(t)|y|, \quad t \in [0, T]; \end{aligned} \quad (1.11)$$

(H4) there exist nonnegative functions $l_1, l_2, l_3, l_4 \in C([0, T])$ such that

$$\begin{aligned} |f(t, x_1, y_1) - f(t, x_2, y_2)| &\leq l_1(t)|x_1 - x_2| + l_2(t)|y_1 - y_2|, \quad t \in [0, T], \\ |g(t, x_1, y_1) - g(t, x_2, y_2)| &\leq l_3(t)|x_1 - x_2| + l_4(t)|y_1 - y_2|, \quad t \in [0, T]. \end{aligned} \quad (1.12)$$

2. EXISTENCE AND UNIQUENESS OF A SOLUTION

In this section, the theorems of existence and uniqueness of a solution for system (1.1)-(1.2) will be given.

Lemma 2.1. *Let (H1)-(H2) hold and $n-1 < \alpha, \beta < n \leq m-1 < \rho, \sigma < m$. Then, a function $u \in C^m([0, T])$ is a solution of the initial value problem (1.1) if and only if*

$$u(t) = \sum_{k=0}^{n-1} \frac{t^k}{k!} \eta_k + \int_0^t \frac{(t-s)^{n-1}}{\Gamma(n)} w_1(s) ds, \quad 0 < t \leq 1, \quad (2.1)$$

where $w_1(t) = u^{(n)}(t) \in C^{m-n}([0, T])$ with $u^{(n+i)}(t) = w_1^{(i)}(t)$, $0 \leq i \leq m-n-1$ is a solution of the integral equation

$$w_1(t) = \sum_{i=0}^{m-n-1} \frac{t^i}{i!} \eta_{n+i} + \int_0^t \frac{(t-s)^{\rho-n-1}}{\Gamma(\rho-n)} f\left(s, w_2(s), \int_0^s \frac{(s-\tau)^{n-\beta-1}}{\Gamma(n-\beta)} w_2(\tau) d\tau\right) ds, \quad (2.2)$$

and a function $v \in C^m([0, T])$ is a solution of the initial value problem (1.2) if and only if

$$v(t) = \sum_{k=0}^{n-1} \frac{t^k}{k!} \xi_k + \int_0^t \frac{(t-s)^{n-1}}{\Gamma(n)} w_2(s) ds, \quad 0 < t \leq 1, \quad (2.3)$$

where $w_2(t) = v^{(n)}(t) \in C^{m-n}([0, T])$ with $v^{(n+i)}(t) = w_2^{(i)}(t)$ is a solution of the integral equation

$$w_2(t) = \sum_{i=0}^{m-n-1} \frac{t^i}{i!} \xi_{n+i} + \int_0^t \frac{(t-s)^{\sigma-n-1}}{\Gamma(\sigma-n)} g\left(s, w_1(s), \int_0^s \frac{(s-\tau)^{n-\alpha-1}}{\Gamma(n-\alpha)} w_1(\tau) d\tau\right) ds. \quad (2.4)$$

Proof. Since the two parts of the Lemma is similar, we only give the proof of the first part briefly. Lemma 1.4 ensures that

$${}^c D^{\rho-n} u^{(n)}(t) = {}^c D^{\rho} u(t) = f\left(t, v^{(n)}(t), {}^c D^{\beta} v(t)\right). \quad (2.5)$$

By Definition 1.1, we obtain

$${}^c D^{\rho-n} u^{(n)}(t) = f\left(t, v^{(n)}(t), \int_0^t \frac{(t-s)^{n-\beta-1}}{\Gamma(n-\beta)} v^{(n)}(s) ds\right). \quad (2.6)$$

It follows from Definition 1.2, Lemma 1.3 (2) and the substitutions $u^{(n)}(t) = w_1(t)$, $v^{(n)}(t) = w_2(t)$ that

$$\begin{aligned} w_1(t) &= u^{(n)}(t) = \sum_{i=0}^{m-n-1} \frac{t^i}{i!} u^{(n+i)}(0) + I^{\rho-n} ({}^c D^{\rho-n} u^{(n)}(t)) \\ &= \sum_{i=0}^{m-n-1} \frac{t^i}{i!} w_1^{(i)}(0) \\ &\quad + \int_0^t \frac{(t-s)^{\rho-n-1}}{\Gamma(\rho-n)} f\left(s, v^{(n)}(s), \int_0^s \frac{(s-\tau)^{n-\beta-1}}{\Gamma(n-\beta)} v^{(n)}(\tau) d\tau\right) ds \quad (2.7) \\ &= \sum_{i=0}^{m-n-1} \frac{t^i}{i!} \eta_{n+i} \\ &\quad + \int_0^t \frac{(t-s)^{\rho-n-1}}{\Gamma(\rho-n)} f\left(s, w_2(s), \int_0^s \frac{(s-\tau)^{n-\beta-1}}{\Gamma(n-\beta)} w_2(\tau) d\tau\right) ds. \end{aligned}$$

Conversely, suppose that $w_1 \in C^{m-n}([0, T])$ is a solution of (2.2). Then,

$$\begin{aligned} u^{(n)}(t) &= w_1(t) = \sum_{i=0}^{m-n-1} \frac{t^i}{i!} \eta_{n+i} \\ &\quad + \int_0^t \frac{(t-s)^{\rho-n-1}}{\Gamma(\rho-n)} f\left(s, w_2(s), \int_0^s \frac{(s-\tau)^{n-\beta-1}}{\Gamma(n-\beta)} w_2(\tau) d\tau\right) ds \quad (2.8) \\ &= \sum_{i=0}^{m-n-1} \frac{t^i}{i!} \eta_{n+i} + I^{\rho-n} f\left(t, v^{(n)}(t), {}^c D^{\beta} v(t)\right). \end{aligned}$$

Since $\rho - n \in (m - n - 1, m - n)$, by Lemma 1.3 (1) and Lemma 1.4, we have

$$\begin{aligned} {}^c D^{\rho} u(t) &= {}^c D^{\rho-n} u^{(n)}(t) \\ &= {}^c D^{\rho-n} \left(\sum_{i=0}^{m-n-1} \frac{t^i}{i!} \eta_{n+i} \right) + {}^c D^{\rho-n} I^{\rho-n} f\left(t, v^{(n)}(t), {}^c D^{\beta} v(t)\right) \quad (2.9) \\ &= f\left(t, v^{(n)}(t), {}^c D^{\beta} v(t)\right), \quad 0 < t \leq 1. \end{aligned}$$

Differentiating (2.2), we get

$$\begin{aligned} w_1^{(k)} &= \sum_{i=0}^{m-n-k-1} \frac{t^i}{i!} \eta_{n+i+k} + \prod_{j=1}^k (\rho - n - j) \int_0^t \frac{(t-s)^{\rho-n-1-k}}{\Gamma(\rho-n)} \\ &\quad f\left(s, w_2(s), \int_0^s \frac{(s-\tau)^{n-\beta-1}}{\Gamma(n-\beta)} w_2(\tau) d\tau\right) ds \quad (2.10) \end{aligned}$$

for each $k = 0, 1, \dots, m - n - 1$. As $\rho - n - 1 - k \in (-1, m - n - 1)$, the second term in (2.10) goes to zero as $t \rightarrow 0$. Thus, we have

$$u^{(n+k)}(0) = w_1^{(k)}(0) = \eta_{n+k}, \quad k = 0, 1, \dots, m - n - 1, \quad (2.11)$$

which means that $u^{(k)}(0) = \eta_k, k = 0, 1, \dots, m - 1$. Clearly, $w_1^{(m-n)} = u^{(m)} \in C([0, T])$. Therefore, u is a solution of (1.1). \square

For the sake of simplicity, Lemma 2.1 can be rewritten as

Lemma 2.2. *Let $f, g : [0, T] \times \mathbb{R} \rightarrow \mathbb{R}$ be continuous functions. Then $(u, v) \in X \times Y$ is a solution of (1.1)-(1.2) if and only if $(u, v) \in X \times Y$ is a solution of (2.1)-(2.4).*

Theorem 2.3. *Assume (H1)-(H3) hold, and*

$$\begin{aligned} B_1 &= \sup_{t \in [0, T]} \int_0^t \frac{(t-s)^{\rho-n-1}}{\Gamma(\rho-n)} \left(a_2(s) + \frac{s^{n-\beta}}{\Gamma(n-\beta+1)} a_3(s) \right) ds < 1, \\ B_2 &= \sup_{t \in [0, T]} \int_0^t \frac{(t-s)^{\sigma-n-1}}{\Gamma(\sigma-n)} \left(b_2(s) + \frac{s^{n-\alpha}}{\Gamma(n-\alpha+1)} b_3(s) \right) ds < 1, \\ 0 < C_1 &= \sup_{t \in [0, T]} \left(|\eta(t)| + \int_0^t \frac{(t-s)^{\rho-n-1}}{\Gamma(\rho-n)} a_1(s) ds \right) < +\infty, \\ 0 < C_2 &= \sup_{t \in [0, T]} \left(|\xi(t)| + \int_0^t \frac{(t-s)^{\sigma-n-1}}{\Gamma(\sigma-n)} b_1(s) ds \right) < +\infty, \end{aligned} \quad (2.12)$$

where

$$\eta(t) = \sum_{i=0}^{m-n-1} \frac{t^i}{i!} \eta_{n+i}, \quad \xi(t) = \sum_{i=0}^{m-n-1} \frac{t^i}{i!} \xi_{n+i}. \quad (2.13)$$

Then the system of integral equations (2.1)-(2.4) has a solution.

Proof. Define a mapping $F : X \times Y \rightarrow X \times Y$ and a ball U in the normed space $X \times Y$ by

$$F(w_1, w_2)(t) = (F_1 w_2(t), F_2 w_1(t)), \quad (2.13)$$

and

$$U = \{(w_1(t), w_2(t)) : (w_1(t), w_2(t)) \in X \times Y, \|(w_1(t), w_2(t))\|_{X \times Y} < R, t \in [0, T]\}, \quad (2.14)$$

where

$$\begin{aligned} F_1 w_2(t) &= \eta(t) + \int_0^t \frac{(t-s)^{\rho-n-1}}{\Gamma(\rho-n)} f\left(s, w_2(s), \int_0^s \frac{(s-\tau)^{n-\beta-1}}{\Gamma(n-\beta)} w_2(\tau) d\tau\right) ds, \\ F_2 w_1(t) &= \xi(t) + \int_0^t \frac{(t-s)^{\sigma-n-1}}{\Gamma(\sigma-n)} g\left(s, w_1(s), \int_0^s \frac{(s-\tau)^{n-\alpha-1}}{\Gamma(n-\alpha)} w_1(\tau) d\tau\right) ds, \end{aligned} \quad (2.15)$$

and

$$R = \frac{C}{1-B}, \quad B = \max\{B_1, B_2\}, \quad C = \max\{C_1, C_2\}. \quad (2.16)$$

Clearly, by (H1) and (H2), F is well defined and continuous. Let $(w_1, w_2) \in \bar{U}$. Then $\|(w_1, w_2)\|_{X \times Y} \leq R$, and

$$\begin{aligned}
& \|F_1 w_2\|_X \\
&= \sup_{t \in [0, T]} \left| \eta(t) + \int_0^t \frac{(t-s)^{\rho-n-1}}{\Gamma(\rho-n)} f\left(s, w_2(s), \int_0^s \frac{(s-\tau)^{n-\beta-1}}{\Gamma(n-\beta)} w_2(\tau) d\tau\right) ds \right| \\
&\leq \sup_{t \in [0, T]} \left(|\eta(t)| + \int_0^t \frac{(t-s)^{\rho-n-1}}{\Gamma(\rho-n)} \left| f\left(s, w_2(s), \int_0^s \frac{(s-\tau)^{n-\beta-1}}{\Gamma(n-\beta)} w_2(\tau) d\tau\right) \right| ds \right) \\
&\leq \sup_{t \in [0, T]} \left(|\eta(t)| + \int_0^t \frac{(t-s)^{\rho-n-1}}{\Gamma(\rho-n)} \left(a_1(s) + a_2(s) |w_2(s)| \right. \right. \\
&\quad \left. \left. + a_3(s) \int_0^s \frac{(s-\tau)^{n-\beta-1}}{\Gamma(n-\beta)} |w_2(\tau)| d\tau \right) ds \right) \\
&\leq \sup_{t \in [0, T]} \left(|\eta(t)| + \int_0^t \frac{(t-s)^{\rho-n-1}}{\Gamma(\rho-n)} a_1(s) ds \right) \\
&\quad + \sup_{t \in [0, T]} \left(\int_0^t \frac{(t-s)^{\rho-n-1}}{\Gamma(\rho-n)} \left(a_2(s) + a_3(s) \int_0^s \frac{(s-\tau)^{n-\beta-1}}{\Gamma(n-\beta)} d\tau \right) ds \right) \|w_2\|_Y \\
&\leq \sup_{t \in [0, T]} \left(|\eta(t)| + \int_0^t \frac{(t-s)^{\rho-n-1}}{\Gamma(\rho-n)} a_1(s) ds \right) \\
&\quad + \sup_{t \in [0, T]} \int_0^t \frac{(t-s)^{\rho-n-1}}{\Gamma(\rho-n)} \left(a_2(s) + \frac{s^{n-\beta}}{\Gamma(n-\beta+1)} a_3(s) \right) ds \|w_2\|_Y \\
&= C_1 + B_1 \|w_2\|_Y \leq C + BR = R.
\end{aligned} \tag{2.17}$$

Similarly, we have

$$\|F_2 w_1\|_Y \leq C_2 + B_2 \|w_1\|_X \leq C + BR = R. \tag{2.18}$$

Therefore, $\|F(w_1, w_2)\|_{X \times Y} \leq R$, which implies that $F(w_1, w_2) \in \bar{U}$. In order to show that F is completely continuous (continuous and compact), put

$$\begin{aligned}
M_f &= \max_{t \in [0, T]} \left| f\left(t, w_2(t), \int_0^t \frac{(t-\tau)^{n-\beta-1}}{\Gamma(n-\beta)} w_2(\tau) d\tau\right) \right|, \\
M_g &= \max_{t \in [0, T]} \left| g\left(t, w_1(t), \int_0^t \frac{(t-\tau)^{n-\alpha-1}}{\Gamma(n-\alpha)} w_1(\tau) d\tau\right) \right|.
\end{aligned} \tag{2.19}$$

For $(w_1, w_2) \in U$ and $t_1, t_2 \in [0, T]$ with $t_1 < t_2$, we obtain

$$\begin{aligned}
& |F_1 w_2(t_2) - F_1 w_2(t_1)| \\
&= \left| \eta(t_2) - \eta(t_1) + \int_0^{t_2} \frac{(t_2-s)^{\rho-n-1}}{\Gamma(\rho-n)} f\left(s, w_2(s), \int_0^s \frac{(s-\tau)^{n-\beta-1}}{\Gamma(n-\beta)} w_2(\tau) d\tau\right) \right. \\
&\quad \left. - \int_0^{t_1} \frac{(t_1-s)^{\rho-n-1}}{\Gamma(\rho-n)} f\left(s, w_2(s), \int_0^s \frac{(s-\tau)^{n-\beta-1}}{\Gamma(n-\beta)} w_2(\tau) d\tau\right) ds \right| \\
&\leq |\eta(t_2) - \eta(t_1)| + M_f \left| \int_0^{t_2} \frac{(t_2-s)^{\rho-n-1}}{\Gamma(\rho-n)} ds - \int_0^{t_1} \frac{(t_1-s)^{\rho-n-1}}{\Gamma(\rho-n)} ds \right| \\
&\leq |\eta(t_2) - \eta(t_1)| + \frac{M_f}{\Gamma(\rho-n+1)} |t_2^{\rho-n} - t_1^{\rho-n}|,
\end{aligned} \tag{2.20}$$

and, in a similar manner,

$$|F_2 w_1(t_2) - F_2 w_1(t_1)| \leq |\xi(t_2) - \xi(t_1)| + \frac{M_g}{\Gamma(\sigma - n + 1)} |t_2^{\sigma-n} - t_1^{\sigma-n}|. \quad (2.21)$$

It follows from the uniform continuity of functions t^k , $t^{\rho-n}$ and $t^{\sigma-n}$ on $[0, T]$ that FU is an equicontinuous set. Moreover, it is uniformly bounded as $FU \subset U$. Hence, F is a completely continuous mapping.

Now to consider the following eigenvalue problem

$$(w_1, w_2) = \lambda F(w_1, w_2) = (\lambda F_1 w_2, \lambda F_2 w_1), \quad \lambda \in (0, 1). \quad (2.22)$$

Assume that (w_1, w_2) is a solution of (2.22) for $\lambda \in (0, 1)$. Then,

$$\begin{aligned} & \|w_1\|_X \\ &= \sup_{t \in [0, T]} |\lambda F_1 w_2(t)| \\ &= \lambda \sup_{t \in [0, T]} \left| \eta(t) + \int_0^t \frac{(t-s)^{\rho-n-1}}{\Gamma(\rho-n)} f\left(s, w_2(s), \int_0^s \frac{(s-\tau)^{n-\beta-1}}{\Gamma(n-\beta)} w_2(\tau) d\tau\right) ds \right| \\ &\leq \lambda \sup_{t \in [0, T]} \left(|\eta(t)| + \int_0^t \frac{(t-s)^{\rho-n-1}}{\Gamma(\rho-n)} \left| f\left(s, w_2(s), \int_0^s \frac{(s-\tau)^{n-\beta-1}}{\Gamma(n-\beta)} w_2(\tau) d\tau\right) \right| ds \right) \\ &\leq \lambda(C + B\|w_2\|_Y), \end{aligned} \quad (2.23)$$

and, similarly,

$$\|w_2\|_Y = \sup_{t \in [0, T]} |\lambda F_2 w_1(t)| \leq \lambda(C + B\|w_1\|_X). \quad (2.24)$$

(2.23) and (2.24) guarantee that $(w_1, w_2) \notin \partial U$. Therefore, by Theorem 1.5, there exists a fixed point (w_{10}, w_{20}) in \bar{U} such that $\|(w_{10}, w_{20})\|_{X \times Y} \leq R$, which completes the proof. \square

It follows from Lemma 2.1 and Theorem 2.3 that the solution (u_0, v_0) of (1.1)-(1.2) is given by

$$\begin{aligned} u_0(t) &= \sum_{k=0}^{n-1} \frac{t^k}{k!} \eta_k + \int_0^t \frac{(t-s)^{n-1}}{\Gamma(n)} w_{10}(s) ds, \\ v_0(t) &= \sum_{k=0}^{n-1} \frac{t^k}{k!} \xi_k + \int_0^t \frac{(t-s)^{n-1}}{\Gamma(n)} w_{20}(s) ds, \end{aligned} \quad (2.25)$$

where

$$\begin{aligned} w_{10}(t) &= \sum_{i=0}^{m-n-1} \frac{t^i}{i!} \eta_{n+i} \\ &\quad + \int_0^t \frac{(t-s)^{\rho-n-1}}{\Gamma(\rho-n)} f\left(s, w_{20}(s), \int_0^s \frac{(s-\tau)^{n-\beta-1}}{\Gamma(n-\beta)} w_{20}(\tau) d\tau\right) ds, \\ w_{20}(t) &= \sum_{i=0}^{m-n-1} \frac{t^i}{i!} \xi_{n+i} \\ &\quad + \int_0^t \frac{(t-s)^{\sigma-n-1}}{\Gamma(\sigma-n)} g\left(s, w_{10}(s), \int_0^s \frac{(s-\tau)^{n-\alpha-1}}{\Gamma(n-\alpha)} w_{10}(\tau) d\tau\right) ds. \end{aligned} \quad (2.26)$$

Theorem 2.4. *Assume (H1), (H2) and (H4) hold, and*

$$\begin{aligned}
D_1 &= \sup_{t \in [0, T]} \int_0^t \frac{(t-s)^{\rho-n-1}}{\Gamma(\rho-n)} \left(l_1(s) + \frac{s^{n-\beta}}{\Gamma(n-\beta+1)} l_2(s) \right) ds < 1, \\
D_2 &= \sup_{t \in [0, T]} \int_0^t \frac{(t-s)^{\sigma-n-1}}{\Gamma(\sigma-n)} \left(l_3(s) + \frac{s^{n-\alpha}}{\Gamma(n-\alpha+1)} l_4(s) \right) ds < 1, \\
0 &< \sup_{t \in [0, T]} \left(\int_0^t \frac{(t-s)^{\rho-n-1}}{\Gamma(\rho-n)} |f(s, 0, 0)| ds \right) < +\infty, \\
0 &< \sup_{t \in [0, T]} \left(\int_0^t \frac{(t-s)^{\sigma-n-1}}{\Gamma(\sigma-n)} |g(s, 0, 0)| ds \right) < +\infty
\end{aligned} \tag{2.27}$$

Then the system of integral equations (2.1)-(2.4) has a unique solution.

Proof. Define the mapping F and the ball U as those in the proof of Theorem 2.3, where

$$R = \frac{1}{1-D_1} \sup_{t \in [0, T]} \left(\int_0^t \frac{(t-s)^{\rho-n-1}}{\Gamma(\rho-n)} |f(s, 0, 0)| ds \right). \tag{2.28}$$

Then F is well defined and continuous. For $(w_1, w_2) \in \bar{U}$, we obtain

$$\begin{aligned}
\|F_1 w_2\|_X &\leq \|F_1 w_2 - F_1 0\|_X + \|F_1 0\|_X \\
&\leq \sup_{t \in [0, T]} \int_0^t \frac{(t-s)^{\rho-n-1}}{\Gamma(\rho-n)} \left(l_1(s) + \frac{s^{n-\beta}}{\Gamma(n-\beta+1)} l_2(s) \right) ds \|w_2\|_Y \\
&\quad + \sup_{t \in [0, T]} \left(\int_0^t \frac{(t-s)^{\rho-n-1}}{\Gamma(\rho-n)} |f(s, 0, 0)| ds \right) \\
&\leq D_1 R + (1-D_1) R \leq R.
\end{aligned} \tag{2.29}$$

Similarly, $\|F_2 w_1\|_Y \leq R$. Therefore, $F\bar{U} \subset \bar{U}$.

For $(w_1, w_2), (w'_1, w'_2) \in \bar{U}$, we have

$$\begin{aligned}
&\|F_1 w_2 - F_1 w'_2\|_X \\
&\leq \sup_{t \in [0, T]} |F_1 w_2(t) - F_1 w'_2(t)| \\
&\leq \sup_{t \in [0, T]} \int_0^t \frac{(t-s)^{\rho-n-1}}{\Gamma(\rho-n)} \left(l_1(s) + \frac{s^{n-\beta}}{\Gamma(n-\beta+1)} l_2(s) \right) ds \|w_2 - w'_2\|_Y \\
&= D_1 \|w_2 - w'_2\|_Y,
\end{aligned} \tag{2.30}$$

and, similarly,

$$\|F_2 w_1 - F_2 w'_1\|_X \leq D_2 \|w_1 - w'_1\|_X. \tag{2.31}$$

Noting that $D_1 < 1, D_2 < 1$, F is a contractive mapping. It follows from Banach contraction principle that F has a unique fixed point $(w'_{10}, w'_{20}) \in \bar{U}$, which is a solution of integral equations (2.1)-(2.4). This completes the proof. \square

3. EXAMPLE

Consider the following coupled system of fractional differential equations:

$$\begin{aligned}
 {}^cD^{11/5}u(t) &= \frac{t}{2} + \frac{t}{3}v''(t) + \frac{t^{4/5}}{4} {}^cD^{9/5}v(t), \quad 0 < t \leq 1, \\
 u(0) &= 0, \quad u'(0) = 1, \quad u''(0) = 2, \\
 {}^cD^{11/4}v(t) &= t + \frac{1}{2}u''(t) + \frac{t^{-3/4}}{3} {}^cD^{5/4}u(t), \quad 0 < t \leq 1, \\
 v(0) &= 3, \quad v'(0) = 4, \quad v''(0) = 5.
 \end{aligned}
 \tag{3.1}$$

Here $T = 1, n = 2, m = 3, \rho = 11/5, \sigma = 11/4, \beta = 9/5, \alpha = 5/4, \eta_1 = 0, \eta_2 = 1, \eta_3 = 2, \xi_1 = 3, \xi_2 = 4,$ and $\xi_3 = 5$. Obviously, the hypotheses (H1)-(H3) are satisfied with $a_1(t) = t/2, a_2(t) = t/3, a_3(t) = t^{4/5}/4, b_1(t) = t, b_2(t) = 1/2, b_3(t) = t^{-3/4}/3$. In this case

$$\begin{aligned}
 B_1 &= \frac{1}{\Gamma(1/5)} \sup_{t \in [0,1]} \int_0^t (t-s)^{-4/5} \left(\frac{s}{3} + \frac{s}{4\Gamma(6/5)} \right) ds \\
 &= \frac{1}{\Gamma(1/5)} \left(\frac{1}{3} + \frac{1}{4\Gamma(6/5)} \right) \frac{15}{4} < 1, \\
 B_2 &= \frac{1}{\Gamma(3/4)} \sup_{t \in [0,1]} \int_0^t (t-s)^{-1/4} \left(\frac{1}{2} + \frac{1}{3\Gamma(7/4)} \right) ds \\
 &= \frac{1}{\Gamma(3/4)} \left(\frac{1}{2} + \frac{1}{3\Gamma(7/4)} \right) \frac{4}{3} < 1, \\
 0 < C_1 &= \sup_{t \in [0,1]} \left(2 + \frac{1}{\Gamma(1/5)} \int_0^t (t-s)^{-4/5} \cdot \frac{s}{2} ds \right) \\
 &= 2 + \frac{1}{\Gamma(1/5)} \cdot \frac{15}{8} < +\infty, \\
 0 < C_2 &= \sup_{t \in [0,1]} \left(5 + \frac{1}{\Gamma(3/4)} \int_0^t (t-s)^{-1/4} \cdot s ds \right) \\
 &= 5 + \frac{1}{\Gamma(3/4)} \cdot \frac{-8}{3} < +\infty.
 \end{aligned}
 \tag{3.2}$$

Thus, all the conditions of Theorem 2.3 are satisfied, and there exists a solution of system (3.1).

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