

ON RICCI H-PSEUDOSYMMETRIC H-HYPERSURFACES OF SOME
ANTI-KÄHLER MANIFOLDS

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A b s t r a c t. We adopt the notion of the pseudosymmetry and Ricci pseudosymmetry to the case of the anti-Kähler manifolds and then we extend the results of the paper [1] to the h-hypersurfaces of the anti-Kähler manifolds of the constant totally real sectional curvatures.

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1. *The object of the paper*

Let (M, g) be a semi-Riemannian manifold of dimension ≥ 3 . The manifold (M, g) is locally symmetric if $\nabla R = 0$, on M , where ∇ is its Levi-Civita connection and R the curvature tensor. The proper generalization of locally symmetric manifolds form semi-symmetric manifolds. They are characterized by the condition

$$R \cdot R = 0,$$

which holds on M , where R acts as a derivation. Some of the investigations of such manifolds gave rise to the next generalization, namely to the pseudosymmetric manifolds, i.e., manifolds satisfying on some set $\mathcal{U} \subset M$ the

condition

$$R \cdot R = \mathcal{L} Q(g, R), \quad (1.1)$$

where \mathcal{L} is a function on U and Q is a special operator (see section 2).

A manifold (M, g) , $\dim M \geq 3$, is said to be Ricci pseudosymmetric, resp. Ricci semi-symmetric, if

$$R \cdot \rho = \mathcal{L} Q(g, \rho), \quad \text{resp. } R \cdot \rho = 0, \quad (1.2)$$

holds on the appropriate set $\mathcal{U} \subset M$, and ρ is the Ricci tensor.

For a survey of results on different aspects of pseudosymmetric manifolds, we refer to [3]; see also [2], [10], [11], [14]. Among other problems there were studied the extrinsic characterizations of Ricci pseudosymmetric hypersurfaces of semi-Riemannian spaces of constant curvature in terms of the shape operator. Namely, in [1] (see Theorems 3.1 and 3.2) the following result is proved

Let M be a hypersurface of a semi-Riemannian space of constant curvature and dimension $n \geq 3$. Then M is Ricci pseudosymmetric if and only if at every point $p \in M$, the second fundamental form h satisfies one of the following conditions

$$h^2 = \alpha h + \beta q, \quad \alpha, \beta \in R, \quad (1.3)$$

or

$$h^3 = \text{tr } h h^2 + \lambda h, \quad \lambda \in R.$$

In particular, for semi-Euclidean space, the previous result imply

A hypersurface M of semi-Euclidean space of dimension $n \geq 3$ is Ricci pseudosymmetric if and only if for every point $p \in M$ the tensor $R \cdot \rho$ vanishes at p , or (1.3) holds.

In section 4 of the present paper, we adopt the notion of pseudosymmetry and Ricci pseudosymmetry to the complex structure of the anti-Kähler manifolds and then we extend the above theorems for the h-hypersurface of anti-Kähler manifold of constant totally real sectional curvature. To do this, we use two formulas proved in section 3, valid for h-hypersurface of the anti-Kähler manifold of constant totally real sectional curvature. In section 2, we explain notations used in the paper.

2. Preliminaries

Let \widetilde{M} be a connected differentiable manifold endowed with pseudo-Riemannian metric G and a $(1,1)$ tensor field F such that, with respect to the local coordinates, holds

$$F_B^A F_C^B = -\delta_C^A, \quad F_A^E F_B^D G_{ED} = -G_{AB}, \quad \widetilde{\nabla}_D F_B^A = 0. \quad (2.1)$$

Here $\widetilde{\nabla}$ is the Levi-Civita connection of (\widetilde{M}, G) and $A, B, C, D \in \{1, 2, \dots, 2m\}$, $2m = \dim \widetilde{M}$. The manifold (\widetilde{M}, G, F) is said to be anti-Kähler manifold [12]. In some papers (\widetilde{M}, G, F) is named B-manifold ([6],[7],[13]) and in some others - the Kähler manifold with the Norden metric ([8],[9]).

The manifold (\widetilde{M}, G, F) is orientable and even-dimensional. The metric G of such a manifold is indefinite and the signature is (m, m) . Also, $\text{tr } F = 0$.

We denote by

$$\begin{aligned} \widetilde{R}_{ABCD} & \quad - \text{the Riemannian curvature tensor,} \\ \widetilde{\rho}_{AB} = \widetilde{R}^C_{ABC} & \quad - \text{the Ricci tensor,} \\ \widetilde{\rho}_{AB}^* = F_A^D \widetilde{\rho}_{DB} & \quad - \text{the second Ricci tensor,} \\ \widetilde{\kappa} = G^{AB} \widetilde{\rho}_{AB} & \quad - \text{the scalar curvature,} \\ \widetilde{\kappa}^* = G^{AB} \widetilde{\rho}_{AB}^* & \quad - \text{the second scalar curvature.} \end{aligned}$$

Since $\widetilde{\nabla} F = 0$, the curvature tensor and the Ricci tensors satisfy

$$\left. \begin{aligned} F_A^L F_B^M \widetilde{R}_{LMCD} &= -\widetilde{R}_{ABCD}, \\ F_A^L F_B^M \widetilde{\rho}_{LM} &= -\widetilde{\rho}_{AB}, \\ F_A^L F_B^M \widetilde{\rho}_{LM}^* &= -\widetilde{\rho}_{AB}^*. \end{aligned} \right\} \quad (2.2)$$

The manifold (\widetilde{M}, G, F) is of pointwise constant totally real sectional curvature if at $p \in M$, ([6], [7]):

$$\begin{aligned} \widetilde{R}_{ABCD} = & \\ & \frac{\widetilde{\kappa}(p)}{4m(m-1)} (G_{AD}G_{BC} - G_{AC}G_{BD} - F_A^L G_{LD} F_B^M G_{MC} + F_A^L G_{LC} F_B^M G_{MD}) \\ & - \frac{\widetilde{\kappa}^*(p)}{4m(m-1)} (G_{AD} F_B^L G_{LC} + G_{BC} F_A^L G_{LD} - G_{AC} F_B^L G_{LD} - G_{BD} F_A^L G_{LC}). \end{aligned} \quad (2.3)$$

If $m \geq 3$, both functions $\tilde{\kappa}$ and $\tilde{\kappa}^*$ are constants.

Now, we consider a differentiable submanifold M of \tilde{M} , $\dim M = 2n$, $n = m - 1$. Suppose that M is expressed in each neighbourhood \tilde{U} of \tilde{M} by the equations

$$x^A = x^A(u^a),$$

where x^A are the local coordinates of \tilde{M} in \tilde{U} and u^a are the local coordinates in $U = \tilde{U} \cap M$. Lowercase Latin indices $a, b, c, \dots, i, j, k, \dots$ run over the range $\{1, 2, \dots, 2n\}$. M is said to be a h-hypersurface (holomorphic hypersurface) of \tilde{M} if the restriction g of G on M has the maximal rank and the complex structure F leaves invariant the tangent space of M at each point $p \in M$. F induces on M the complex structure f such that (M, g, f) itself is an anti-Kähler manifold [4]. Similarly to (2.1) and (2.2), we have

$$\left. \begin{aligned} f_i^a f_a^j &= -\delta_i^j, & f_i^a f_j^b g_{ab} &= -g_{ij}, & \nabla_i f_j^k &= 0, \\ f_i^a f_j^b R_{ablm} &= -R_{ijlm}, & \rho_{ij}^* &= f_i^a \rho_{aj}, \\ f_i^a f_j^b \rho_{ab} &= -\rho_{ij}, & f_i^a f_j^b \rho_{ab}^* &= -\rho_{ij}^*, \end{aligned} \right\} \quad (2.4)$$

where ∇ is the Levi-Civita connection with respect to the metric g , and R_{ijlm} , ρ_{ij} and ρ_{ij}^* denote the local components of the Riemannian curvature tensor, Ricci tensor and the second Ricci tensor, respectively. We denote by κ and κ^* the scalar curvature and the second scalar curvature of (M, g, f) .

Because F leaves invariant the tangent space of M , it leaves invariant the normal space, too. There exist locally vector fields $N_{1|}$ and $N_{2|}$ normal to M , such that ([4]):

$$\begin{aligned} G_{AB} N_{1|}^A N_{1|}^B &= -G_{AB} N_{2|}^A N_{2|}^B = 1, & G_{AB} N_{1|}^A N_{2|}^B &= 0, \\ F_B^A N_{1|}^B &= -N_{2|}^A, & F_B^A N_{2|}^B &= N_{1|}^A. \end{aligned}$$

Denoting by h and k the second fundamental forms corresponding to $N_{1|}$ and $N_{2|}$ respectively, we have

$$h_{ij} = f_i^a k_{aj}, \quad k_{ij} = -f_i^a h_{aj}. \quad (2.5)$$

Also, we shall use

$$h_{ij}^2 = h_i^a h_{aj}, \quad h_{ij}^3 = h_i^a h_{aj}^2.$$

It is easy to see that the following conditions are satisfied

$$\left. \begin{aligned} f_i^a f_j^b h_{ab} &= -h_{ij}, & f_i^a f_j^b k_{ab} &= -k_{ij}, \\ f_i^a h_{aj} &= f_j^a h_{ai}, & f_i^a k_{aj} &= f_j^a k_{ia}, \\ h_{ij}^2 &= h_{ji}^2, & f_i^a f_j^b h_{ab}^2 &= -h_{ij}^2, & f_i^a h_{aj}^2 &= f_j^a h_{ia}^2, \\ h_{ij}^3 &= h_{ji}^3, & f_i^a f_j^b h_{ab}^3 &= -h_{ij}^3, & f_i^a h_{aj}^3 &= f_j^a h_{ia}^3. \end{aligned} \right\} \quad (2.6)$$

Let at $p \in M$, A and D be two symmetric $(0, 2)$ tensors and B the curvature like tensor, satisfying

$$f_i^a f_j^b A_{ab} = -A_{ij}, \quad f_i^a f_j^b D_{ab} = -D_{ij}, \quad (2.7)$$

$$f_i^a f_j^b B_{ablm} = -B_{ijlm} \quad (2.8)$$

Let T be a $(0, 4)$ tensor. We define the tensors $B \cdot A$, $B \cdot T$, $Q(A, D)$, $Q(A, B)$ by the formulas

$$(B \cdot A)_{rsij} = A_{aj} B_{irs}^a + A_{ia} B_{jrs}^a, \quad (2.9)$$

$$(B \cdot T)_{rsijlm} = T_{ajlm} B_{irs}^a + T_{ialm} B_{jrs}^a + T_{ijam} B_{lrs}^a + T_{ijla} B_{mrs}^a, \quad (2.10)$$

$$\begin{aligned} Q(A, D)_{rsij} &= A_{ri} D_{sj} + A_{rj} D_{si} - A_{si} D_{rj} - A_{sj} D_{ri} \\ &\quad - f_r^a f_s^b (A_{ai} D_{bj} + A_{aj} D_{bi} - A_{bi} D_{aj} - A_{bj} D_{ai}), \end{aligned} \quad (2.11)$$

$$\begin{aligned} Q(A, B)_{rsijlm} &= A_{ri} B_{sjlm} + A_{rj} B_{islm} + A_{rl} B_{ijsm} + A_{rm} B_{ijls} \\ &\quad - A_{si} B_{rjlm} - A_{sj} B_{irml} - A_{sl} B_{ijrm} - A_{sm} B_{ijlr} \\ &\quad - f_r^a f_s^b (A_{ai} B_{bjlm} + A_{aj} B_{iblm} + A_{al} B_{ijbm} + A_{am} B_{ijlb} \\ &\quad - A_{bi} B_{ajlm} - A_{bj} B_{ialm} - A_{bl} B_{ijam} - A_{bm} B_{ijla}). \end{aligned} \quad (2.12)$$

Remark. The operator Q of a semi-Riemannian manifold (M, g) is defined in the following way (e.g. see [1],[2],[3]):

$$Q(A, D)_{rsij} = A_{ri} D_{sj} + A_{rj} D_{si} - A_{si} D_{rj} - A_{sj} D_{ri},$$

$$\begin{aligned} Q(A, B)_{rsijlm} &= A_{ri} B_{sjlm} + A_{rj} B_{islm} + A_{rl} B_{ijsm} + A_{rm} B_{ijls} \\ &\quad - A_{si} B_{rjlm} - A_{sj} B_{irml} - A_{sl} B_{ijrm} - A_{sm} B_{ijlr}. \end{aligned}$$

Thus, (2.11) and (2.12) are the same operators, but adopted to the complex structure of the manifold.

We note that

$$\left. \begin{aligned} Q(A, D) &= -Q(D, A) \quad \text{and therefore} \quad Q(A, A) = 0, \\ Q(fA, fD) &= -Q(A, D) \quad \text{and therefore} \quad Q(fA, D) = Q(A, fD), \\ Q(A, fA) &= 0, \quad Q(fD, B) = Q(D, fB). \end{aligned} \right\} \quad (2.13)$$

For the latter use, we present

Lemma 2.1 ([4]) *Let as a point $p \in M$, A and D be two symmetric $(0, 2)$ tensors satisfying (2.7). If*

$$Q(A, D) = 0, \quad (2.14)$$

then

$$D = \delta A + \bar{\delta} fA, \quad \delta, \bar{\delta} \in R. \quad (2.15)$$

P r o o f. Let X be a vector such that

$$X^a X^b A_{ab} = \omega \neq 0, \quad X^a \bar{X}^b A_{ab} = \bar{\omega} \neq 0,$$

where $\bar{X}^i = f_a^i X^a$. We put

$$\eta = X^a X^b D_{ab}, \quad \bar{\eta} = X^a \bar{X}^b D_{ab}.$$

Transvecting (2.14) with $X^i X^r$, and symmetrizing the resulting equality, we get

$$\omega D_{sj} - \eta A_{sj} - \bar{\omega} f_s^a D_{aj} + \bar{\eta} f_s^a A_{aj} = 0,$$

from which it follows that

$$\omega f_i^a D_{aj} - \eta f_i^a A_{aj} + \bar{\omega} D_{ij} - \bar{\eta} A_{ij} = 0.$$

These two relations imply

$$D_{ij} = \frac{\omega \eta + \bar{\omega} \bar{\eta}}{\omega^2 + \bar{\omega}^2} A_{ij} - \frac{\omega \bar{\eta} - \bar{\omega} \eta}{\omega^2 + \bar{\omega}^2} f_i^a A_{aj}.$$

But this is just the relation (2.15). □

3. *H-hypersurface of an anti-Kähler manifold of constant totally real sectional curvatures*

The Gauss equation for an h-hypersurface (M, g, f) reads

$$\tilde{R}_{ABCD} \frac{\partial x^A}{\partial u^i} \frac{\partial x^B}{\partial u^j} \frac{\partial x^C}{\partial u^l} \frac{\partial x^D}{\partial u^m} = R_{ijlm} - (h_{im}h_{jl} - h_{il}h_{jm}) + (k_{im}k_{jl} - k_{il}k_{jm}).$$

Now, we suppose that the ambient manifold (\tilde{M}, G, F) is a manifold of constant totally real sectional curvatures. Then, substituting (2.3) into above Gauss equation, and taking into account that $m = n + 1$, we get

$$R_{ijlm} = K G_{ijlm} + \overset{*}{K} f_i^a G_{ajlm} + E_{ijlm} \quad (3.1)$$

where

$$G_{ijlm} = g_{im}g_{jl} - g_{il}g_{jm} - f_{im}f_{jl} + f_{il}f_{jm}, \quad (3.2)$$

$$E_{ijlm} = h_{im}h_{jl} - h_{il}h_{jm} - k_{im}k_{jl} + k_{il}k_{jm} \quad (3.3)$$

$$K = \frac{\tilde{\kappa}}{4n(n+1)}, \quad \overset{*}{K} = -\frac{\tilde{\kappa}^*}{4n(n+1)}, \quad (3.4)$$

and $f_{ij} = f_i^a g_{aj}$.

The relation (3.1) yields

$$\left. \begin{aligned} \rho_{im} &= 2(n-1)(K g_{im} + \overset{*}{K} f_{im}) + \text{tr } h h_{im} + \text{tr } k f_i^a h_{am} - 2h_{im}^2, \\ \overset{*}{\rho}_{im} &= 2(n-1)(K f_{im} - \overset{*}{K} g_{im}) + \text{tr } h f_i^a h_{am} - \text{tr } k h_{im} - 2f_i^a h_{am}^2, \end{aligned} \right\} \quad (3.5)$$

and therefore

$$\left. \begin{aligned} \kappa &= 4n(n-1)K + (\text{tr } h)^2 - (\text{tr } k)^2 - 2\text{tr } (h^2), \\ \overset{*}{\kappa} &= -4n(n-1) \overset{*}{K} - 2\text{tr } h \text{tr } k - 2\text{tr } (fh^2). \end{aligned} \right\} \quad (3.6)$$

We note that, because of $k_{ij} = -f_i^a h_{aj}$, we have $\text{tr } k = -\text{tr } (fh)$. In view of (3.1), we have

$$R \cdot R = K G \cdot R + \overset{*}{K} (fG) \cdot R + E \cdot R.$$

Using (2.12), we can easy to see that

$$G \cdot R = Q(g, R), \quad (fG) \cdot R = Q(fg, R).$$

Therefore

$$R \cdot R = K Q(g, R) + \overset{*}{K} Q(fg, R) + E \cdot R. \quad (3.7)$$

On the other hand

$$E \cdot R = K (E \cdot G) + \overset{*}{K} (E \cdot fG) + E \cdot E.$$

But

$$\begin{aligned} (E \cdot G)_{rsijlm} &= \\ &= G_{ajlm} E_{irs}^a + G_{ialm} E_{jrs}^a + G_{ijam} E_{lrs}^a + G_{ijla} E_{mrs}^a \\ &= g_{jl} (E_{mirs} + E_{imrs}) - g_{jm} (E_{lirs} + E_{ilrs}) \\ &\quad + g_{im} (E_{ljrs} + E_{jlrs}) - g_{il} (E_{mjrs} + E_{jmrs}) \\ &\quad - f_{im} (f_l^a E_{ajrs} + f_j^a E_{alrs}) + f_{il} (f_m^a E_{ajrs} + f_j^a E_{amrs}) \\ &\quad - f_{jl} (f_m^a E_{airs} + f_i^a E_{amrs}) + f_{jm} (f_l^a E_{airs} + f_i^a E_{alrs}) = 0, \end{aligned}$$

because of

$$E_{mirs} = -E_{imrs} \quad \text{and} \quad f_m^a E_{airs} = -f_i^a E_{amrs}.$$

Similary we have $E \cdot fG = 0$, and therefore (3.7) reduces to

$$R \cdot R = K Q(g, R) + \overset{*}{K} Q(fg, R) + E \cdot E.$$

Finally

$$\begin{aligned} (E \cdot E)_{rsijlm} &= \\ &= - \left[h_{ri}^2 E_{sjlm} + h_{rj}^2 E_{islm} + h_{rl}^2 E_{ijsm} + h_{rm}^2 E_{ijls} \right. \\ &\quad - h_{si}^2 E_{rjlm} - h_{sj}^2 E_{irlm} - h_{sl}^2 E_{ijrm} - h_{sm}^2 E_{ijlr} \\ &\quad - f_r^a f_s^b (h_{ai}^2 E_{bjlm} + h_{aj}^2 E_{iblm} + h_{al}^2 E_{ijbm} + h_{am}^2 E_{ijlb} \\ &\quad \left. - h_{bi}^2 E_{ajlm} - h_{bj}^2 E_{ialm} - h_{bl}^2 E_{ijam} - h_{bm}^2 E_{ijla}) \right] \\ &= -Q(h^2, E)_{rsijlm}. \end{aligned}$$

Thus, we can state

Proposition 3.1. *The relation*

$$(R \cdot R)_{rsijlm} = K Q(g, R)_{rsijlm} + \overset{*}{K} Q(fg, R)_{rsijlm} - Q(h^2, E)_{rsijlm} \quad (3.8)$$

holds good for any h -hypersurface of an anti-Kähler manifold of constant totally real sectional curvatures.

Transvecting (3.8) with g^{jl} we get

$$R \cdot \rho = KQ(g, \rho) + \overset{*}{K}(fg, \rho) + Q(h, \text{tr } h h^2 + \text{tr } k fh^2 - 2h^3). \quad (3.9)$$

Thus, we have

Proposition 3.2. *The relation (3.9) holds good for any h -hypersurface of an anti-Kähler manifold of constant totally real sectional curvatures.*

4. H -pseudosymmetry

In the case of anti-Kähler manifolds, we adopt the conditions (1.1) and (1.2) to the complex structure of the manifold introducing the following

Definition. *The anti-Kähler manifold (M, g, f) is said to be h -pseudosymmetric if the condition*

$$R \cdot R = \mathcal{L}_1 Q(g, R) + \mathcal{L}_2 Q(fg, R) \quad (4.1)$$

is satisfied on some set $U \subset M$, where \mathcal{L}_1 and \mathcal{L}_2 are some scalar function on U .

The manifold (M, g, f) is said to be Ricci h -pseudosymmetric if the condition

$$R \cdot \rho = \mathcal{L}_1 Q(g, \rho) + \mathcal{L}_2 Q(fg, \rho) \quad (4.2)$$

is satisfied on U .

Now, we consider h -hypersurface (M, g, f) of the anti-Kähler manifold of constant totally real sectional curvatures. Then, according to the Proposition 3.2, the relation (3.9) holds good. Thus, if (M, g, f) is also Ricci h -pseudosymmetric, then we have

$$(\mathcal{L}_1 - K)Q(g, \rho) + (\mathcal{L}_2 - \overset{*}{K})Q(fg, \rho) = Q(h, \text{tr } h h^2 + \text{tr } k fh^2 - 2h^3). \quad (4.3)$$

We shall examine two cases.

Case (1). If

$$\mathcal{L}_1 = K \quad \text{and} \quad \mathcal{L}_2 = \overset{*}{K}, \quad (4.4)$$

then (4.3) reduces to

$$Q(h, \operatorname{tr} h h^2 + \operatorname{tr} k f h^2 - 2h^3) = 0$$

and, in view of Lemma 2.1, we have

$$h^3 = \frac{1}{2} \operatorname{tr} h h^2 + \frac{1}{2} \operatorname{tr} k f h^2 + \delta h + \bar{\delta} f h . \quad (4.5)$$

Conversely, if (4.5) holds, then

$$\begin{aligned} Q(h, \operatorname{tr} h h^2 + \operatorname{tr} k f h^2 - 2h^3) &= \\ &= -2\delta Q(h, h) - 2\bar{\delta} Q(h, f h) = 0 , \end{aligned}$$

and (3.9) reduces to

$$R \cdot \rho = KQ(g, \rho) + \overset{*}{K}Q(fg, \rho) ,$$

i.e., (4.4) holds.

Thus, we can state

Theorem 4.1. *Let (M, g, f) be h -hypersurface of the anti-Kähler manifold (M, G, F) of constant totally real sectional curvatures. Then (4.5) is the necessary and the sufficient condition for (M, g, f) to be Ricci h -pseudosymmetric on the appropriate set $U \subset M$ such that (4.4) holds.*

Remark. According to (3.4), (4.4) turns into

$$\mathcal{L}_1 = \frac{\tilde{\kappa}}{4n(n+1)} , \quad \mathcal{L}_2 = -\frac{\tilde{\kappa}^*}{4n(n+1)} ,$$

where $\tilde{\kappa}$ and $\tilde{\kappa}^*$ are the first and the second scalar curvatures of \tilde{M} and $\dim M = 2n$.

Corollary. *Let (M, g, f) be h -hypersurface of the flat anti-Kähler manifold. Then (4.5) is the necessary and the sufficient condition for (M, g, f) to be Ricci semisymmetric.*

Case (2) If

$$\lambda_1 = \mathcal{L}_1 - \frac{\tilde{\kappa}}{4n(n+1)} \neq 0 \quad \text{and} \quad \lambda_2 = \mathcal{L}_2 + \frac{\tilde{\kappa}^*}{4n(n+1)} \neq 0 ,$$

then (4.3) gives

$$\lambda_1 Q(g, \rho) + \lambda_2 Q(fg, \rho) = Q(h, \operatorname{tr} h h^2 + \operatorname{tr} k fh^2 - 2h^3), \quad (4.6)$$

from which it follows that

$$\lambda_1 Q(fg, \rho) - \lambda_2 Q(g, \rho) = -Q(h, \operatorname{tr} k h^2 - \operatorname{tr} h fh^2 + 2fh^3). \quad (4.7)$$

In the local coordinates, the left hand side of (4.6) is the following

$$\begin{aligned} & \lambda_1 (g_{ri} \rho_{sj} + g_{rj} \rho_{si} - g_{si} \rho_{rj} - g_{sj} \rho_{ri} - f_{ri} \overset{*}{\rho}_{sj} - f_{rj} \overset{*}{\rho}_{si} + f_{si} \overset{*}{\rho}_{rj} + f_{sj} \overset{*}{\rho}_{ri}) \\ & + \lambda_2 (f_{ri} \rho_{sj} + f_{rj} \rho_{si} - f_{si} \rho_{rj} - f_{sj} \rho_{ri} + g_{ri} \overset{*}{\rho}_{sj} + g_{rj} \overset{*}{\rho}_{si} - g_{si} \overset{*}{\rho}_{rj} - g_{sj} \overset{*}{\rho}_{ri}), \end{aligned}$$

from which, by transvection with g^{ri} we get

$$\lambda_1 (2n\rho - \kappa g + \overset{*}{\kappa} fg) + \lambda_2 (2n \overset{*}{\rho} - \kappa fg - \overset{*}{\kappa} g).$$

In the similar way, we obtain from

$$Q(h, \operatorname{tr} h h^2 + \operatorname{tr} k fh^2 - 2h^3)$$

the following expression

$$\begin{aligned} & - \left[\operatorname{tr} h \operatorname{tr} h^2 + \operatorname{tr} k \operatorname{tr}(fh^2) - 2\operatorname{tr} h^3 \right] h + \left[\operatorname{tr} h \operatorname{tr}(fh^2) - \operatorname{tr} k \operatorname{tr} h^2 - 2\operatorname{tr}(fh^3) \right] fh \\ & + \left[(\operatorname{tr} h)^2 - (\operatorname{tr} k)^2 \right] h^2 + 2\operatorname{tr} h \operatorname{tr} k fh^2 - 2\operatorname{tr} h h^3 - 2\operatorname{tr} k fh^3. \end{aligned}$$

Thus, as a consequence of (4.6), we have

$$\begin{aligned} & \lambda_1 Q(2n\rho - \kappa g + \overset{*}{\kappa} fg, h) + \lambda_2 Q(2n \overset{*}{\rho} - \kappa fg - \overset{*}{\kappa} g, h) \\ & = - \left[(\operatorname{tr} h)^2 - (\operatorname{tr} k)^2 \right] Q(h, h^2) - 2\operatorname{tr} h \operatorname{tr} k Q(h, fh^2) \\ & \quad + 2\operatorname{tr} h Q(h, h^3) + 2\operatorname{tr} k Q(h, fh^3). \end{aligned} \quad (4.8)$$

But, the right hand side of (4.8) can be written in the form

$$\begin{aligned} & \left[-(\operatorname{tr} h)^2 + (\operatorname{tr} k)^2 \right] Q(h, h^2) - 2\operatorname{tr} h \operatorname{tr} k Q(h, fh^2) \\ & \quad + 2\operatorname{tr} h Q(h, h^3) + 2\operatorname{tr} k Q(h, fh^3) \\ & = -\operatorname{tr} h \left[\operatorname{tr} h Q(h, h^2) + \operatorname{tr} k Q(h, fh^2) - 2Q(h, h^3) \right] \\ & \quad + \operatorname{tr} k \left[\operatorname{tr} k Q(h, h^2) - \operatorname{tr} h Q(h, fh^2) + 2Q(h, fh^3) \right] \\ & = -\operatorname{tr} h Q(h, \operatorname{tr} h h^2 + \operatorname{tr} k fh^2 - 2h^3) + \operatorname{tr} k Q(h, \operatorname{tr} k h^2 - \operatorname{tr} h fh^2 + 2fh^3) \\ & = -\operatorname{tr} h \left[\lambda_1 Q(g, \rho) + \lambda_2 Q(fg, \rho) \right] + \operatorname{tr} k \left[-\lambda_1 Q(fg, \rho) + \lambda_2 Q(g, \rho) \right], \end{aligned}$$

because of (4.6) and (4.7). Thus, (4.8) is of the form

$$\begin{aligned} & \lambda_1 Q(2n\rho - \kappa g + \overset{*}{\kappa}fg, h) + \lambda_2 Q(2n \overset{*}{\rho} - \kappa fg - \overset{*}{\kappa}g, h) \\ &= -\lambda_1 [\operatorname{tr} h Q(g, \rho) + \operatorname{tr} k Q(fg, \rho)] + \lambda_2 [\operatorname{tr} k Q(g, \rho) - \operatorname{tr} h Q(fg, \rho)] . \end{aligned} \quad (4.9)$$

On the other hand, using (3.5), we have

$$\begin{aligned} & Q(2n\rho - \kappa g + \overset{*}{\kappa}fg, h) \\ &= [4n(n-1)K - \kappa] Q(g, h) + \left[4n(n-1) \overset{*}{K} + \overset{*}{\kappa} \right] Q(fg, h) + 4nQ(h, h^2) . \end{aligned}$$

Similarly

$$\begin{aligned} & Q(2n \overset{*}{\rho} - \kappa fg - \overset{*}{\kappa}g, h) \\ &= [4n(n-1)K - \kappa] Q(fg, h) - \left[4n(n-1) \overset{*}{K} + \overset{*}{\kappa} \right] Q(g, h) + 4nQ(h, fh^2) , \end{aligned}$$

such that (4.9) becomes

$$\begin{aligned} & \lambda_1 \{ [4n(n-1)K - \kappa] Q(g, h) + [4n(n-1) \overset{*}{K} + \overset{*}{\kappa}] Q(fg, h) \\ & \quad + 4nQ(h, h^2) + \operatorname{tr} h Q(g, \rho) + \operatorname{tr} k Q(fg, \rho) \} \\ & + \lambda_2 \{ [4n(n-1)K - \kappa] Q(fg, h) - [4n(n-1) \overset{*}{K} + \overset{*}{\kappa}] Q(g, h) \\ & \quad + 4nQ(h, fh^2) - \operatorname{tr} k Q(g, \rho) + \operatorname{tr} h Q(fg, \rho) \} = 0 . \end{aligned} \quad (4.10)$$

If we set

$$\begin{aligned} P = & [4n(n-1)K - \kappa] Q(g, h) + [4n(n-1) \overset{*}{K} + \overset{*}{\kappa}] Q(fg, h) \\ & + 4nQ(h, h^2) + \operatorname{tr} h Q(g, \rho) + \operatorname{tr} k Q(fg, \rho) , \end{aligned}$$

then

$$\begin{aligned} fP = & [4n(n-1)K - \kappa] Q(fg, h) - [4n(n-1) \overset{*}{K} - \overset{*}{\kappa}] Q(g, h) \\ & + 4nQ(fh, h^2) + \operatorname{tr} h Q(fg, \rho) - \operatorname{tr} k Q(g, \rho) . \end{aligned}$$

But

$$Q(h, fh^2) = Q(fh, h^2) .$$

This means that (4.10) can be expressed in the form

$$\lambda_1 P + \lambda_2 fP = 0 .$$

This relation, together with

$$-\lambda_2 P + \lambda_1 fP = 0 ,$$

yields

$$(\lambda_1^2 + \lambda_2^2)P = 0 ,$$

and $P = 0$ if at last one of the conditions $\lambda_1 \neq 0$ and $\lambda_2 \neq 0$ is satisfied.

Thus we have

$$\begin{aligned} & [4n(n-1)K - \kappa]Q(g, h) + [4n(n-1) \overset{*}{K} + \overset{*}{\kappa}]Q(fg, h) \\ & + 4nQ(h, h^2) + \text{tr} h Q(g, \rho) + \text{tr} k Q(fg, \rho) = 0 , \end{aligned}$$

or

$$\begin{aligned} & [4n(n-1)K - \kappa + (\text{tr} h)^2 - (\text{tr} k)^2]Q(g, h) \\ & + [4n(n-1) \overset{*}{K} + \overset{*}{\kappa} + 2\text{tr} h \text{tr} k]Q(fg, h) \\ & - 2\text{tr} h Q(g, h^2) - 2\text{tr} k Q(g, fh^2) + 4nQ(h, h^2) = 0 , \end{aligned} \quad (4.11)$$

because of

$$\begin{aligned} Q(g, \rho) &= \text{tr} h Q(g, h) + \text{tr} k Q(g, fh) - 2Q(g, h^2) , \\ Q(fg, \rho) &= \text{tr} h Q(fg, h) + \text{tr} k Q(g, h) - 2Q(g, fh^2) . \end{aligned}$$

Finally, according to (3.6),

$$\begin{aligned} 4n(n-1)K - \kappa + (\text{tr} h)^2 - (\text{tr} k)^2 &= 2\text{tr}(h^2), \\ 4n(n-1) \overset{*}{K} + \overset{*}{\kappa} + 2\text{tr} h \text{tr} k &= -2\text{tr}(fh^2) , \end{aligned}$$

and (4.11) becomes

$$\begin{aligned} & \text{tr} h^2 Q(g, h) - \text{tr}(fh^2)Q(fg, h) \\ & - \text{tr} h Q(g, h^2) - \text{tr} k Q(g, fh^2) + 2nQ(h, h^2) = 0 . \end{aligned} \quad (4.12)$$

On the other hand,

$$\begin{aligned} & Q\left(h - \frac{\text{tr} h}{2n}g + \frac{\text{tr}(fh)}{2n}fg, h^2 - \frac{\text{tr} h^2}{2n}g + \frac{\text{tr}(fh^2)}{2n}fg\right) \\ &= Q\left(h, h^2\right) + Q\left(g, \frac{\text{tr} h^2}{2n}h\right) - Q\left(g, \frac{\text{tr}(fh^2)}{2n}fh\right) \\ & \quad - Q\left(g, \frac{\text{tr} h}{2n}h^2\right) + Q\left(g, \frac{\text{tr} fh}{2n}fh^2\right) . \end{aligned}$$

This, in view of (4.12), means that

$$Q\left(h - \frac{\operatorname{tr} h}{2n}g + \frac{\operatorname{tr}(fh)}{2n}fg, h^2 - \frac{\operatorname{tr} h^2}{2n}g + \frac{\operatorname{tr}(fh^2)}{2n}fg\right) = 0$$

from which, applying Lemma 2.1, we get

$$\begin{aligned} h^2 - \frac{\operatorname{tr} h^2}{2n}g + \frac{\operatorname{tr}(fh^2)}{2n}fg &= \delta\left(h - \frac{\operatorname{tr} h}{2n}g + \frac{\operatorname{tr}(fh)}{2n}fg\right) \\ &\quad + \bar{\delta}\left(fh - \frac{\operatorname{tr} h}{2n}fg - \frac{\operatorname{tr}(fh)}{2n}g\right), \end{aligned}$$

or

$$h^2 = \delta h + \bar{\delta}fh + \mu g + \bar{\mu}fg, \quad (4.13)$$

where

$$\begin{aligned} \mu &= \frac{\operatorname{tr} h^2}{2n} - \delta \frac{\operatorname{tr} h}{2n} - \bar{\delta} \frac{\operatorname{tr}(fh)}{2n}, \\ \bar{\mu} &= -\frac{\operatorname{tr}(fh^2)}{2n} + \delta \frac{\operatorname{tr}(fh)}{2n} - \bar{\delta} \frac{\operatorname{tr} h}{2n}. \end{aligned}$$

Conversely, if (4.13) holds, then

$$\begin{aligned} Q(h^2, E) &= Q(\delta h + \bar{\delta}fh + \mu g + \bar{\mu}fg, E) \\ &= \delta Q(h, E) + \bar{\delta}Q(fh, E) + \mu Q(g, E) + \bar{\mu}Q(fg, E). \end{aligned}$$

But

$$Q(h, E) = Q(fh, E) = 0,$$

and therefore

$$Q(h^2, E) = \mu Q(g, E) + \bar{\mu}Q(fg, E). \quad (4.14)$$

On the other hand, in view of $Q(g, G) = Q(fg, G) = 0$, we have

$$\mu Q(g, KG + \overset{*}{K}fG) = 0, \quad \bar{\mu}Q(fg, KG + \overset{*}{K}fG) = 0,$$

that is, the relation (4.14) is equivalent to

$$Q(h^2, E) = \mu Q(g, KG + \overset{*}{K}fG + E) + \bar{\mu}Q(fg, KG + \overset{*}{K}fG + E).$$

In the other words

$$Q(h^2, E) = \mu Q(g, R) + \bar{\mu} Q(fg, R) . \quad (4.15)$$

According to the Proposition 3.1, for any h-hypersurface of the anti-Kähler manifold of constant totally real sectional curvatures, the relation (3.8) holds, which, in view of (4.15) becomes

$$R \cdot R = (K - \mu)Q(G, R) + (\overset{*}{K} - \bar{\mu})Q(fg, R) .$$

This means that if (4.15) holds, then (M, g, f) is h-pseudosymmetric. But h-pseudosymmetric manifold is Ricci h-pseudosymmetric, too. Thus, we can state

Theorem 4.2. *Let (M, g, f) , $\dim M = 2n$, be a h-hypersurface of the anti-Kähler manifold (\widetilde{M}, G, F) of constant totally real sectional curvatures. Let $\widetilde{\kappa}$ and $\overset{*}{\kappa}$ be the first and the second scalar curvatures of (\widetilde{M}, G, F) . Then (4.13) is the necessary and the sufficient condition for (M, g, f) to be, on the appropriate set $U \subset M$, Ricci h-pseudosymmetric such that at least one of the relations*

$$\mathcal{L}_1 \neq \frac{\widetilde{\kappa}}{4n(n+1)} , \quad \mathcal{L}_2 \neq \frac{\overset{*}{\kappa}}{4n(n+1)}$$

is satisfied.

5. Remark. H-pseudosymmetry is also considered in [5]. In that paper it is proved that every anti-Kähler manifold satisfying the Roter type equation

$$\begin{aligned} R(X, Y, Z, W) = & N_1 \Gamma(X, Y, Z, W) + N_2 \Gamma(fX, Y, Z, W) \\ & + N_3 G(X, Y, Z, W) + N_4 G(fX, Y, Z, W) , \end{aligned}$$

on some set $U \subset M$, is h-pseudosymmetric, where

$$\begin{aligned} \Gamma(X, Y, Z, W) = & \rho(X, W)\rho(Y, Z) - \rho(X, Z)\rho(Y, W) \\ & - \overset{*}{\rho}(X, W) \overset{*}{\rho}(Y, Z) + \overset{*}{\rho}(X, Z) \overset{*}{\rho}(Y, W) , \end{aligned}$$

and N_1, \dots, N_4 are some scalar functions on U .

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