

Research Article

Oscillation Behavior of Third-Order Neutral Emden-Fowler Delay Dynamic Equations on Time Scales

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We will establish some oscillation criteria for the third-order Emden-Fowler neutral delay dynamic equations $(r(t)(x(t) - a(t)x(\tau(t)))^{\Delta\Delta})^{\Delta} + p(t)x^{\gamma}(\delta(t)) = 0$ on a time scale \mathbb{T} , where $\gamma > 0$ is a quotient of odd positive integers with r , a , and p real-valued positive rd-continuous functions defined on \mathbb{T} . To the best of our knowledge nothing is known regarding the qualitative behavior of these equations on time scales, so this paper initiates the study. Some examples are considered to illustrate the main results.

1. Introduction

The study of dynamic equations on time-scales, which goes back to its founder Hilger [1], is an area of mathematics that has recently received a lot of attention. It has been created in order to unify the study of differential and difference equations. Many results concerning differential equations carry over quite easily to corresponding results for difference equations, while other results seem to be completely different from their continuous counterparts. The study of dynamic equations on time-scales reveals such discrepancies, and helps avoid proving results twice—once for differential equations and once again for difference equations.

Several authors have expounded on various aspects of this new theory; see the survey paper by Agarwal et al. [2], Bohner and Guseinov [3], and references cited therein. A book

on the subject of time-scales, by Bohner and Peterson [4], summarizes and organizes much of the time-scale calculus; see also the book by Bohner and Peterson [5] for advances in dynamic equations on time-scales.

In the recent years, there has been increasing interest in obtaining sufficient conditions for the oscillation and nonoscillation of solutions of various equations on time-scales; we refer the reader to the papers [6–38]. To the best of our knowledge, it seems to have few oscillation results for the oscillation of third-order dynamic equations; see, for example, [14–16, 21, 35]. However, the paper which deals with the third-order delay dynamic equation is due to Hassan [21].

Hassan [21] considered the third-order nonlinear delay dynamic equations

$$\left(c(t)\left((a(t)x^\Delta(t))^\Delta\right)^\gamma\right)^\Delta + f(t, x(\tau(t))) = 0, \quad t \in \mathbb{T}, \quad (1.1)$$

where $\tau(\sigma(t)) = \sigma(\tau(t))$ is required, and the author established some oscillation criteria for (1.1) which extended the results given in [16].

To the best of our knowledge, there are no results regarding the oscillation of the solutions of the following third-order nonlinear neutral delay dynamic equations on time-scales up to now:

$$\left(r(t)(x(t) - a(t)x(\tau(t)))^{\Delta\Delta}\right)^\Delta + p(t)x^\gamma(\delta(t)) = 0, \quad t \in \mathbb{T}. \quad (1.2)$$

We assume that $\gamma > 0$ is a quotient of odd positive integers, r , a and p are positive real-valued rd-continuous functions defined on \mathbb{T} such that $r^\Delta(t) \geq 0$, $0 < a(t) \leq a_0 < 1$, $\lim_{t \rightarrow \infty} a(t) = a < 1$, the delay functions $\tau : \mathbb{T} \rightarrow \mathbb{T}$, $\delta : \mathbb{T} \rightarrow \mathbb{T}$ are rd-continuous functions such that $\tau(t) \leq t$, $\delta(t) \leq t$, and $\lim_{t \rightarrow \infty} \tau(t) = \lim_{t \rightarrow \infty} \delta(t) = \infty$.

As we are interested in oscillatory behavior, we assume throughout this paper that the given time-scale \mathbb{T} is unbounded above. We assume $t_0 \in \mathbb{T}$ and it is convenient to assume $t_0 > 0$. We define the time-scale interval of the form $[t_0, \infty)_{\mathbb{T}}$ by $[t_0, \infty)_{\mathbb{T}} = [t_0, \infty) \cap \mathbb{T}$.

For the oscillation of neutral delay dynamic equations on time-scales, Mathsen et al. [26] considered the first-order neutral delay dynamic equations on time-scales

$$[y(t) - r(t)y(\tau(t))]^\Delta + p(t)y(\delta(t)) = 0, \quad t \in \mathbb{T}, \quad (1.3)$$

and established some new oscillation criteria of (1.3) which as a special case involve some well-known oscillation results for first-order neutral delay differential equations.

Agarwal et al. [7], Şahiner [28], Saker [31], Saker et al. [33], Wu et al. [34] studied the second-order nonlinear neutral delay dynamic equations on time-scales

$$\left(r(t)((y(t) + p(t)y(\tau(t)))^\Delta)^\gamma\right)^\Delta + f(t, y(\delta(t))) = 0, \quad t \in \mathbb{T}, \quad (1.4)$$

by means of Riccati transformation technique, the authors established some oscillation criteria of (1.4).

Saker [32] investigated the second-order neutral Emden-Fowler delay dynamic equations on time-scales

$$\left[a(t)(y(t) + r(t)y(\tau(t)))^\Delta \right]^\Delta + p(t)y^\gamma(\delta(t)) = 0, \quad t \in \mathbb{T}, \tag{1.5}$$

and established some new oscillation for (1.5).

Our purpose in this paper is motivated by the question posed in [26]: What can be said about higher-order neutral dynamic equations on time-scales and the various generalizations? We refer the reader to the articles [23, 24] and we will consider the particular case when the order is 3, that is, (1.2). Set $t_{-1} := \min_{t \in [t_0, \infty)_{\mathbb{T}}} \{\tau(t), \delta(t)\}$. By a solution of (1.2), we mean a nontrivial real-valued function $x \in C_{rd}([t_{-1}, \infty)_{\mathbb{T}}, \mathbb{R})$ satisfying $x - ax \circ \tau \in C_{rd}^2([t_0, \infty)_{\mathbb{T}}, \mathbb{R})$ and $r(x - ax \circ \tau)^{\Delta\Delta} \in C_{rd}^1([t_0, \infty)_{\mathbb{T}}, \mathbb{R})$, and satisfying (1.2) for all $t \in [t_0, \infty)_{\mathbb{T}}$.

The paper is organized as follows. In Section 2, we apply a simple consequence of Keller’s chain rule, devoted to the proof of the sufficient conditions which guarantee that every solution of (1.2) oscillates or converges to zero. In Section 3, some examples are considered to illustrate the main results.

2. Main Results

In this section we give some new oscillation criteria for (1.2). In order to prove our main results, we will use the formula

$$((x(t))^\gamma)^\Delta = \gamma \int_0^1 [hx^\sigma(t) + (1 - h)x(t)]^{\gamma-1} x^\Delta(t) dh, \tag{2.1}$$

where x is delta differentiable and eventually positive or eventually negative, which is a simple consequence of Keller’s chain rule (see Bohner and Peterson [4, Theorem 1.90]).

Before stating our main results, we begin with the following lemmas which are crucial in the proofs of the main results.

For the sake of convenience, we denote: $z(t) = x(t) - a(t)x(\tau(t))$, for $t \in [t_0, \infty)_{\mathbb{T}}$. Also, we assume that

(H) there exists $\{c_k\}_{k \in \mathbb{N}_0} \subset \mathbb{T}$ such that $\lim_{k \rightarrow \infty} c_k = \infty$ and $\tau(c_{k+1}) = c_k$.

Lemma 2.1. *Assume that (H) holds. Further, assume that x is an eventually positive solution of (1.2). If*

$$\int_{t_0}^\infty \frac{\Delta t}{r(t)} = \infty, \tag{2.2}$$

then there are only the following three cases for $t \geq t_1$ sufficiently large:

- (i) $z(t) > 0$, $z^\Delta(t) > 0$, $z^{\Delta\Delta}(t) > 0$, $z^{\Delta\Delta\Delta}(t) < 0$,
 - (ii) $z(t) < 0$, $z^\Delta(t) > 0$, $z^{\Delta\Delta}(t) > 0$, $z^{\Delta\Delta\Delta}(t) < 0$, $\lim_{t \rightarrow \infty} x(t) = 0$,
- or
- (iii) $z(t) > 0$, $z^\Delta(t) < 0$, $z^{\Delta\Delta}(t) > 0$, $z^{\Delta\Delta\Delta}(t) < 0$, $\lim_{t \rightarrow \infty} z(t) = l \geq 0$, $\lim_{t \rightarrow \infty} x(t) = l/(1 - a) \geq 0$.

Proof. Let x be an eventually positive solution of (1.2). Then there exists $t_1 \geq t_0$ such that $x(t) > 0$, $x(\tau(t)) > 0$, and $x(\delta(t)) > 0$ for all $t \geq t_1$. From (1.2) we have

$$\left(r(t)z^{\Delta\Delta}(t)\right)^\Delta = -p(t)x^\gamma(\delta(t)) < 0, \quad t \geq t_1. \quad (2.3)$$

Hence $r(t)z^{\Delta\Delta}(t)$ is strictly decreasing on $[t_1, \infty)_{\mathbb{T}}$. We claim that $z^{\Delta\Delta}(t) > 0$ eventually. Assume not, then there exists $t_2 \geq t_1$ such that

$$r(t)z^{\Delta\Delta}(t) < 0, \quad t \geq t_2. \quad (2.4)$$

Then we can choose a negative c and $t_3 \geq t_2$ such that

$$r(t)z^{\Delta\Delta}(t) \leq c < 0, \quad t \geq t_3. \quad (2.5)$$

Dividing by $r(t)$ and integrating from t_3 to t , we have

$$z^\Delta(t) \leq z^\Delta(t_3) + c \int_{t_3}^t \frac{\Delta s}{r(s)}. \quad (2.6)$$

Letting $t \rightarrow \infty$, then $z^\Delta(t) \rightarrow -\infty$ by (2.2). Thus, there is a $t_4 \geq t_3$ such that for $t \geq t_4$,

$$z^\Delta(t) \leq z^\Delta(t_4) < 0. \quad (2.7)$$

Integrating the previous inequality from t_4 to t , we obtain

$$z(t) - z(t_4) \leq z^\Delta(t_4)(t - t_4). \quad (2.8)$$

Therefore, there exist $d > 0$ and $t_5 \geq t_4$ such that

$$x(t) \leq -d + a(t)x(\tau(t)) \leq -d + a_0x(\tau(t)), \quad t \geq t_5. \quad (2.9)$$

We can choose some positive integer k_0 such that $c_k \geq t_5$, for $k \geq k_0$. Thus, we obtain

$$\begin{aligned} x(c_k) &\leq -d + a_0x(\tau(c_k)) = -d + a_0x(c_{k-1}) \leq -d - a_0d + a_0^2x(\tau(c_{k-1})) \\ &= -d - a_0d + a_0^2x(c_{k-2}) \leq \dots \leq -d - a_0d - \dots - a_0^{k-k_0-1}d + a_0^{k-k_0}x(\tau(c_{k_0+1})) \\ &= -d - a_0d - \dots - a_0^{k-k_0-1}d + a_0^{k-k_0}x(c_{k_0}). \end{aligned} \quad (2.10)$$

The above inequality implies that $x(c_k) < 0$ for sufficiently large k , which contradicts the fact that $x(t) > 0$ eventually. Hence we get

$$z^{\Delta\Delta}(t) > 0. \quad (2.11)$$

It follows from this that either $z^\Delta(t) > 0$ or $z^\Delta(t) < 0$. Since $r^\Delta(t) \geq 0$,

$$\left(r(t)z^{\Delta\Delta}(t)\right)^\Delta = r^\Delta(t)z^{\Delta\Delta}(t) + r^\sigma(t)z^{\Delta\Delta\Delta}(t) < 0, \quad (2.12)$$

which yields

$$z^{\Delta\Delta\Delta}(t) < 0. \quad (2.13)$$

If $z^\Delta(t) > 0$, then there are two possible cases:

- (1) $z(t) > 0$, eventually; or
- (2) $z(t) < 0$, eventually.

If there exists a $t_6 \geq t_1$ such that case (2) holds, then $\lim_{t \rightarrow \infty} z(t)$ exists, and $\lim_{t \rightarrow \infty} z(t) = b \leq 0$. We claim that $\lim_{t \rightarrow \infty} z(t) = 0$. Otherwise, $\lim_{t \rightarrow \infty} z(t) = b < 0$. We can choose some positive integer k_0 such that $c_k \geq t_6$, for $k \geq k_0$. Thus, we obtain

$$\begin{aligned} x(c_k) &\leq a_0 x(\tau(c_k)) = a_0 x(c_{k-1}) \leq a_0^2 x(\tau(c_{k-1})) \\ &= a_0^2 x(c_{k-2}) \leq \cdots \leq a_0^{k-k_0} x(\tau(c_{k_0+1})) = a_0^{k-k_0} x(c_{k_0}), \end{aligned} \quad (2.14)$$

which implies that $\lim_{k \rightarrow \infty} x(c_k) = 0$, and from the definition of $z(t)$, we have $\lim_{k \rightarrow \infty} z(c_k) = 0$, which contradicts $\lim_{t \rightarrow \infty} z(t) < 0$. Now, we assert that x is bounded. If it is not true, there exists $\{s_k\}_{k \in \mathbb{N}} \subset [t_6, \infty)_{\mathbb{T}}$ with $s_k \rightarrow \infty$ as $k \rightarrow \infty$ such that

$$x(s_k) = \sup_{t_0 \leq s \leq s_k} x(s), \quad \lim_{k \rightarrow \infty} x(s_k) = \infty. \quad (2.15)$$

From $\tau(t) \leq t$

$$z(s_k) = x(s_k) - a(s_k)x(\tau(s_k)) \geq (1 - a_0)x(s_k), \quad (2.16)$$

which implies that $\lim_{k \rightarrow \infty} z(s_k) = \infty$, it contradicts that $\lim_{t \rightarrow \infty} z(t) = 0$. Therefore, we can assume that

$$\limsup_{t \rightarrow \infty} x(t) = x_1, \quad \liminf_{t \rightarrow \infty} x(t) = x_2. \quad (2.17)$$

By $0 \leq a < 1$, we get

$$x_1 - ax_1 \leq 0 \leq x_2 - ax_2, \quad (2.18)$$

which implies that $x_1 \leq x_2$, so $x_1 = x_2$, hence, $\lim_{t \rightarrow \infty} x(t) = 0$.

Assume that $z^\Delta(t) < 0$. We claim that $z(t) \geq 0$ eventually. Otherwise, we have $\lim_{t \rightarrow \infty} z(t) < 0$ or $\lim_{t \rightarrow \infty} z(t) = -\infty$. By (H), there exists $t_7 \geq t_1$, we can choose some positive integer k_0 such that $c_k \geq t_7$ for $k \geq k_0$, and we obtain

$$\begin{aligned} x(c_k) &\leq a_0 x(\tau(c_k)) = a_0 x(c_{k-1}) \leq a_0^2 x(\tau(c_{k-1})) \\ &= a_0^2 x(c_{k-2}) \leq \cdots \leq a_0^{k-k_0} x(\tau(c_{k_0+1})) = a_0^{k-k_0} x(c_{k_0}), \end{aligned} \quad (2.19)$$

which implies that $\lim_{k \rightarrow \infty} x(c_k) = 0$, and from the definition of z , we have $\lim_{k \rightarrow \infty} z(c_k) = 0$, which contradicts $\lim_{t \rightarrow \infty} z(t) < 0$ or $\lim_{t \rightarrow \infty} z(t) = -\infty$. Now, we have that $\lim_{t \rightarrow \infty} z(t) = l \geq 0$, here l is finite. We assert that x is bounded. If it is not true, there exists $\{s_k\}_{k \in \mathbb{N}} \subset [t_6, \infty)_{\mathbb{T}}$ with $s_k \rightarrow \infty$ as $k \rightarrow \infty$ such that

$$x(s_k) = \sup_{t_0 \leq s \leq s_k} x(s), \quad \lim_{k \rightarrow \infty} x(s_k) = \infty. \quad (2.20)$$

From $\tau(t) \leq t$

$$z(s_k) = x(s_k) - a(s_k)x(\tau(s_k)) \geq (1 - a_0)x(s_k), \quad (2.21)$$

which implies that $\lim_{k \rightarrow \infty} z(s_k) = \infty$, it contradicts that $\lim_{t \rightarrow \infty} z(t) = l \geq 0$. Therefore, we can assume that

$$\limsup_{t \rightarrow \infty} x(t) = x_{1*}, \quad \liminf_{t \rightarrow \infty} x(t) = x_{2*}. \quad (2.22)$$

By $0 \leq a < 1$, we get

$$x_{1*} - ax_{1*} \leq l \leq x_{2*} - ax_{2*}, \quad (2.23)$$

which implies that $x_{1*} \leq x_{2*}$, so $x_{1*} = x_{2*}$, hence, $\lim_{t \rightarrow \infty} x(t) = l/(1 - a) \geq 0$. This completes the proof. \square

In [4, Section 1.6] the Taylor monomials $\{h_n(t, s)\}_{n=0}^{\infty}$ are defined recursively by

$$h_0(t, s) = 1, \quad h_{n+1}(t, s) = \int_s^t h_n(\tau, s) \Delta\tau, \quad t, s \in \mathbb{T}, \quad n \geq 1. \quad (2.24)$$

It follows from [4, Section 1.6] that $h_1(t, s) = t - s$ for any time-scale, but simple formulas in general do not hold for $n \geq 2$.

Lemma 2.2 (see [15, Lemma 4]). *Assume that z satisfies case (i) of Lemma 2.1. Then*

$$\liminf_{t \rightarrow \infty} \frac{tz(t)}{h_2(t, t_0)z^\Delta(t)} \geq 1. \tag{2.25}$$

Lemma 2.3. *Assume that x is a solution of (1.2) satisfying case (i) of Lemma 2.1. If*

$$\int_{t_0}^{\infty} p(t)(h_2(\delta(t), t_0))^{\gamma} \Delta t = \infty, \tag{2.26}$$

then z satisfies eventually

$$z^\Delta(t) \geq tz^{\Delta\Delta}(t), \quad \frac{z^\Delta(t)}{t} \text{ is nonincreasing.} \tag{2.27}$$

Proof. Let x be a solution of (1.2) such that case (i) of Lemma 2.1 holds for $t \geq t_1$. Define

$$Z(t) = z^\Delta(t) - tz^{\Delta\Delta}(t). \tag{2.28}$$

Thus

$$Z^\Delta(t) = -\sigma(t)z^{\Delta\Delta\Delta}(t) > 0. \tag{2.29}$$

We claim that $Z(t) > 0$ eventually. Otherwise, there exists $t_2 \geq t_1$ such that $Z(t) < 0$ for $t \geq t_2$. Therefore,

$$\left(\frac{z^\Delta(t)}{t}\right)^\Delta = -\frac{Z(t)}{t\sigma(t)} > 0, \quad t \geq t_2, \tag{2.30}$$

which implies that $z^\Delta(t)/t$ is strictly increasing on $[t_2, \infty)_{\mathbb{T}}$. Pick $t_3 \geq t_2$ such that $\delta(t) \geq \delta(t_3) \geq t_2$, for $t \geq t_3$. Then we have

$$\frac{z^\Delta(\delta(t))}{\delta(t)} \geq \frac{z^\Delta(\delta(t_3))}{\delta(t_3)} = P > 0, \tag{2.31}$$

then $z^\Delta(\delta(t)) \geq P\delta(t)$ for $t \geq t_3$. By Lemma 2.2, for any $0 < k < 1$, there exists $t_4 \geq t_3$ such that

$$\frac{z(t)}{z^\Delta(t)} \geq k \frac{h_2(t, t_0)}{t}, \quad t \geq t_4. \tag{2.32}$$

Hence there exists $t_5 \geq t_4$ so that

$$z(\delta(t)) \geq k \frac{h_2(\delta(t), t_0)}{\delta(t)} z^\Delta(\delta(t)) \geq Pk \frac{h_2(\delta(t), t_0)}{\delta(t)} \delta(t) = Pkh_2(\delta(t), t_0), \quad t \geq t_5. \tag{2.33}$$

By the definition of z , we have that

$$x(t) \geq z(t). \quad (2.34)$$

From (1.2), we obtain

$$\left(r(t)z^{\Delta\Delta}(t)\right)^{\Delta} + p(t)z^{\gamma}(\delta(t)) \leq 0. \quad (2.35)$$

Integrating both sides of (2.35) from t_5 to t , we get

$$r(t)z^{\Delta\Delta}(t) - r(t_5)z^{\Delta\Delta}(t_5) + (Pk)^{\gamma} \int_{t_5}^t p(s)(h_2(\delta(s), t_0))^{\gamma} \Delta s \leq 0, \quad (2.36)$$

which yields that

$$r(t_5)z^{\Delta\Delta}(t_5) \geq (Pk)^{\gamma} \int_{t_5}^t p(s)(h_2(\delta(s), t_0))^{\gamma} \Delta s, \quad (2.37)$$

which contradicts (2.26). Hence $Z(t) > 0$ and $z^{\Delta}(t)/t$ is nonincreasing. The proof is complete. \square

Lemma 2.4. *Assume that (H) holds and x is a solution of (1.2) which satisfies case (iii) of Lemma 2.1. If*

$$\int_{t_0}^{\infty} p(s)R^{\sigma}(s)\Delta s = \infty, \quad (2.38)$$

where $R(t) := \int_{t_0}^t (\sigma(u)/r(u))\Delta u$ for $t \in [t_0, \infty)_{\mathbb{T}}$, then $\lim_{t \rightarrow \infty} x(t) = 0$.

Proof. Let x be a solution of (1.2) such that case (iii) of Lemma 2.1 holds for $t \geq t_1$. Then $\lim_{t \rightarrow \infty} z(t) = l \geq 0$, $\lim_{t \rightarrow \infty} x(t) = l/(1-a) \geq 0$. Next we claim that $l = 0$. Otherwise, there exists $t_2 \geq t_1$ such that $z(\delta(t)) \geq l > 0$ for all $t \geq t_2$. By the definition of z , we have that (2.35) holds. Integrating both sides of (2.35) from t to ∞ , we get

$$z^{\Delta\Delta}(t) \geq \frac{1}{r(t)} \int_t^{\infty} p(s)z^{\gamma}(\delta(s))\Delta s. \quad (2.39)$$

Integrating again from t to ∞ , we have

$$-z^{\Delta}(t) \geq \int_t^{\infty} \frac{1}{r(u)} \int_u^{\infty} p(s)z^{\gamma}(\delta(s))\Delta s \Delta u. \quad (2.40)$$

Integrating again from t_2 to ∞ , we obtain

$$z(t_1) \geq \int_{t_2}^{\infty} \int_v^{\infty} \frac{1}{r(u)} \int_u^{\infty} p(s) z^\gamma(\delta(s)) \Delta s \Delta u \Delta v \geq l^\gamma \int_{t_2}^{\infty} \int_v^{\infty} \frac{1}{r(u)} \int_u^{\infty} p(s) \Delta s \Delta u \Delta v, \quad (2.41)$$

which contradicts (2.38), since by [23, Lemma 1] and [3, Remark 4.7], we get

$$\begin{aligned} & \int_{t_0}^{\infty} \int_v^{\infty} \frac{1}{r(u)} \int_u^{\infty} p(s) \Delta s \Delta u \Delta v \\ &= \int_{t_0}^{\infty} \int_v^{\infty} \int_u^{\infty} \frac{1}{r(u)} p(s) \Delta s \Delta u \Delta v \\ &= \int_{t_0}^{\infty} \int_v^{\infty} \int_v^{\sigma(s)} \frac{1}{r(u)} p(s) \Delta u \Delta s \Delta v = \int_{t_0}^{\infty} \int_{t_0}^{\sigma(s)} \int_v^{\sigma(s)} \frac{1}{r(u)} p(s) \Delta u \Delta v \Delta s \\ &= \int_{t_0}^{\infty} p(s) \int_{t_0}^{\sigma(s)} \int_v^{\sigma(s)} \frac{1}{r(u)} \Delta u \Delta v \Delta s = \int_{t_0}^{\infty} p(s) \int_{t_0}^{\sigma(s)} \int_{t_0}^{\sigma(u)} \frac{1}{r(u)} \Delta v \Delta u \Delta s \\ &= \int_{t_0}^{\infty} p(s) \int_{t_0}^{\sigma(s)} \frac{1}{r(u)} \int_{t_0}^{\sigma(u)} \Delta v \Delta u \Delta s \\ &= \int_{t_0}^{\infty} p(s) \int_{t_0}^{\sigma(s)} \frac{\sigma(u) - t_0}{r(u)} \Delta u \Delta s = \int_{t_0}^{\infty} p(s) \int_{t_0}^{\sigma(s)} \frac{\sigma(u)}{r(u)} \Delta u \Delta s = \int_{t_0}^{\infty} p(s) R^\sigma(s) \Delta s. \end{aligned} \quad (2.42)$$

Hence $\lim_{t \rightarrow \infty} x(t) = 0$ and completes the proof. \square

Theorem 2.5. Assume that (H), (2.2), (2.26), and (2.38) hold, $\gamma \geq 1$. Furthermore, assume that there exists a positive function $\eta \in C_{rd}^1([t_0, \infty)_{\mathbb{T}}, \mathbb{R})$ such that for some $0 < k < 1$ and for all constants $M > 0$

$$\limsup_{t \rightarrow \infty} \int_{t_0}^t \left(\eta(s) p(s) \zeta(s) - \frac{r(s) (\eta^\Delta(s))^2}{4k\gamma M^{\gamma-1} \eta(s)} \right) \Delta s = \infty, \quad (2.43)$$

where $\zeta(t) := (h_2(\delta(t), t_0)/t)^\gamma$. Then every solution x of (1.2) oscillates or $\lim_{t \rightarrow \infty} x(t) = 0$.

Proof. Suppose that (1.2) has a nonoscillatory solution x . We may assume without loss of generality that $x(t) > 0$, $x(\tau(t)) > 0$, and $x(\delta(t)) > 0$ for all $t \in [t_1, \infty)_{\mathbb{T}}$, $t_1 \in [t_0, \infty)_{\mathbb{T}}$. Then by Lemma 2.1, z satisfies three cases. Assume that z satisfies case (i). Define the function ω by

$$\omega(t) = \eta(t) \frac{r(t) z^{\Delta\Delta}(t)}{(z^\Delta(t))^\gamma}, \quad t \in [t_1, \infty)_{\mathbb{T}}. \quad (2.44)$$

Then $\omega(t) > 0$. Using the product rule, we have

$$\omega^\Delta(t) = \left(r(t) z^{\Delta\Delta}(t) \right)^\sigma \left[\frac{\eta(t)}{(z^\Delta(t))^\gamma} \right]^\Delta + \left(r(t) z^{\Delta\Delta}(t) \right)^\Delta \frac{\eta(t)}{(z^\Delta(t))^\gamma}. \quad (2.45)$$

By the quotient rule, we get

$$\omega^\Delta(t) = \left(r(t)z^{\Delta\Delta}(t)\right)^\sigma \frac{\eta^\Delta(t)(z^\Delta(t))^\gamma - \eta(t)\left((z^\Delta(t))^\gamma\right)^\Delta}{(z^\Delta(t))^\gamma(z^{\Delta\sigma}(t))^\gamma} + \left(r(t)z^{\Delta\Delta}(t)\right)^\Delta \frac{\eta(t)}{(z^\Delta(t))^\gamma}. \quad (2.46)$$

By the definition of z and (1.2), we obtain (2.35). From (2.35) and (2.44), we have

$$\omega^\Delta(t) \leq \frac{\eta^\Delta(t)}{\eta^\sigma(t)} \omega^\sigma(t) - \eta(t)p(t) \frac{z^\gamma(\delta(t))}{(z^\Delta(t))^\gamma} - \eta(t) \frac{(r(t)z^{\Delta\Delta}(t))^\sigma \left((z^\Delta(t))^\gamma\right)^\Delta}{(z^\Delta(t))^\gamma(z^{\Delta\sigma}(t))^\gamma}, \quad (2.47)$$

from (2.25) and (2.27), for any $0 < k < 1$, we obtain

$$\frac{z^\gamma(\delta(t))}{(z^\Delta(t))^\gamma} = \frac{z^\gamma(\delta(t))}{(z^\Delta(\delta(t)))^\gamma} \frac{(z^\Delta(\delta(t)))^\gamma}{(z^\Delta(t))^\gamma} \geq \left(k^{1/\gamma} \frac{h_2(\delta(t), t_0)}{\delta(t)}\right)^\gamma \left(\frac{\delta(t)}{t}\right)^\gamma = k \left(\frac{h_2(\delta(t), t_0)}{t}\right)^\gamma, \quad (2.48)$$

hence by (2.48), we have

$$\omega^\Delta(t) \leq \frac{\eta^\Delta(t)}{\eta^\sigma(t)} \omega^\sigma(t) - k\eta(t)p(t)\zeta(t) - \eta(t) \frac{(r(t)z^{\Delta\Delta}(t))^\sigma \left((z^\Delta(t))^\gamma\right)^\Delta}{(z^\Delta(t))^\gamma(z^{\Delta\sigma}(t))^\gamma}. \quad (2.49)$$

In view of $\gamma \geq 1$, from (2.1) and (i) of Lemma 2.1, we have

$$\begin{aligned} \left((z^\Delta(t))^\gamma\right)^\Delta &= \gamma \int_0^1 \left[hz^{\Delta\sigma}(t) + (1-h)z^\Delta(t)\right]^{\gamma-1} z^{\Delta\Delta}(t) dh \\ &\geq \gamma \left(z^\Delta(t)\right)^{\gamma-1} z^{\Delta\Delta}(t) \geq \gamma M^{\gamma-1} z^{\Delta\Delta}(t), \end{aligned} \quad (2.50)$$

where $M = z^\Delta(t_1)$. By (2.49), we have

$$\omega^\Delta(t) \leq \frac{\eta^\Delta(t)}{\eta^\sigma(t)} \omega^\sigma(t) - k\eta(t)p(t)\zeta(t) - \gamma M^{\gamma-1} \eta(t) \frac{\left[(r(t)z^{\Delta\Delta}(t))^\sigma\right]^2}{(z^\Delta(t))^\gamma(z^{\Delta\sigma}(t))^\gamma} \frac{z^{\Delta\Delta}(t)}{r^\sigma(t)z^{\Delta\Delta\sigma}(t)}, \quad (2.51)$$

from (i), we have $z^\Delta(t) \leq z^{\Delta\sigma}(t)$, by $(r(t)z^{\Delta\Delta}(t))^\Delta < 0$, we have

$$z^{\Delta\Delta}(t) \geq \frac{r^\sigma(t)}{r(t)} z^{\Delta\Delta\sigma}(t), \quad (2.52)$$

so we get

$$\omega^\Delta(t) \leq \frac{\eta^\Delta(t)}{\eta^\sigma(t)} \omega^\sigma(t) - k\eta(t)p(t)\zeta(t) - \gamma M^{\gamma-1} \eta(t) \frac{\left[(r(t)z^{\Delta\Delta}(t))^\sigma \right]^2}{r(t)((z^{\Delta\sigma}(t))^\gamma)^2}, \tag{2.53}$$

by (2.44), we have

$$\omega^\Delta(t) \leq \frac{\eta^\Delta(t)}{\eta^\sigma(t)} \omega^\sigma(t) - k\eta(t)p(t)\zeta(t) - \gamma M^{\gamma-1} \frac{\eta(t)}{r(t)(\eta^\sigma(t))^2} (\omega^\sigma(t))^2. \tag{2.54}$$

Therefore, we obtain

$$\omega^\Delta(t) \leq -k\eta(t)p(t)\zeta(t) + \frac{r(t)(\eta^\Delta(t))^2}{4\gamma M^{\gamma-1}\eta(t)}. \tag{2.55}$$

Integrating inequality (2.55) from t_1 to t , we obtain

$$-\omega(t_1) \leq \omega(t) - \omega(t_1) \leq -\int_{t_1}^t \left(k\eta(s)p(s)\zeta(s) - \frac{r(s)(\eta^\Delta(s))^2}{4\gamma M^{\gamma-1}\eta(s)} \right) \Delta s, \tag{2.56}$$

which yields

$$\int_{t_1}^t \left(k\eta(s)p(s)\zeta(s) - \frac{r(s)(\eta^\Delta(s))^2}{4\gamma M^{\gamma-1}\eta(s)} \right) \Delta s \leq \omega(t_1) \tag{2.57}$$

for all large t , which contradicts (2.43). If (ii) holds, from Lemma 2.1, then $\lim_{t \rightarrow \infty} x(t) = 0$. If case (iii) holds, by Lemma 2.4, then $\lim_{t \rightarrow \infty} x(t) = 0$. The proof is complete. \square

Remark 2.6. From Theorem 2.5, we can obtain different conditions for oscillation of all solutions of (1.2) with different choices of η .

For example, let $\eta(t) = t$. Now Theorem 2.5 yields the following result.

Corollary 2.7. *Assume that (H), (2.2), (2.26), and (2.38) hold, $\gamma \geq 1$. If*

$$\limsup_{t \rightarrow \infty} \int_{t_0}^t \left(sp(s) \left(\frac{h_2(\delta(s), t_0)}{s} \right)^\gamma - \frac{r(s)}{4k\gamma M^{\gamma-1}s} \right) \Delta s = \infty \tag{2.58}$$

holds for some $0 < k < 1$ and for all constants $M > 0$, then every solution x of (1.2) is either oscillatory or $\lim_{t \rightarrow \infty} x(t) = 0$.

For example, let $\eta(t) = 1$. From Theorem 2.5, we have the following result which can be considered as the extension of the Leighton-Wintner Theorem.

Corollary 2.8. Assume that (H), (2.2), (2.26), and (2.38) hold, and $\gamma \geq 1$. If

$$\limsup_{t \rightarrow \infty} \int_{t_0}^t p(s) \left(\frac{h_2(\delta(s), t_0)}{s} \right)^\gamma \Delta s = \infty, \quad (2.59)$$

then every solution x of (1.2) is either oscillatory or $\lim_{t \rightarrow \infty} x(t) = 0$.

In the following theorem, we present a new Kamenev-type oscillation criteria for (1.2).

Theorem 2.9. Assume that (H), (2.2), (2.26), and (2.38) hold, $\gamma \geq 1$. Let ζ and η be as defined in Theorem 2.5. If for some $0 < k < 1$ and for all constants $M > 0$

$$\limsup_{t \rightarrow \infty} \frac{1}{t^m} \int_{t_0}^t \left((t-s)^m \eta(s) p(s) \zeta(s) - \frac{r(s) B^2(t, s) (\eta^\sigma(s))^2}{4k\gamma M^{\gamma-1} \eta(s) (t-s)^m} \right) \Delta s = \infty, \quad (2.60)$$

where $m > 1$, and

$$B(t, s) = (t-s)^m \frac{\eta^\Delta(s)}{\eta^\sigma(s)} - m(t-\sigma(s))^{m-1}, \quad t \geq \sigma(s) \geq t_0, \quad (2.61)$$

then every solution x of (1.2) oscillates or $\lim_{t \rightarrow \infty} x(t) = 0$.

Proof. Suppose that (1.2) has a nonoscillatory solution x . We may assume without loss of generality that $x(t) > 0$, $x(\tau(t)) > 0$, and $x(\delta(t)) > 0$ for all $t \in [t_1, \infty)_{\mathbb{T}}$, $t_1 \in [t_0, \infty)_{\mathbb{T}}$. Then by Lemma 2.1, z satisfies three cases. Assume that z satisfies case (i). We proceed as in the proof of Theorem 2.5 to get (2.54) for all $t \geq t_1$ sufficiently large. Multiplying (2.54) by $(t-s)^m$ and integrating from t_1 to t , we have

$$\begin{aligned} \int_{t_1}^t (t-s)^m k \eta(s) p(s) \zeta(s) \Delta s &\leq - \int_{t_1}^t (t-s)^m \omega^\Delta(s) \Delta s + \int_{t_1}^t (t-s)^m \frac{\eta^\Delta(s)}{\eta^\sigma(s)} \omega^\sigma(s) \Delta s \\ &\quad - \int_{t_1}^t \frac{(t-s)^m \gamma M^{\gamma-1} \eta(s)}{r(s) (\eta^\sigma(s))^2} (\omega^\sigma(s))^2 \Delta s. \end{aligned} \quad (2.62)$$

Integration by parts, we obtain

$$- \int_{t_1}^t (t-s)^m \omega^\Delta(s) \Delta s = -(t-s)^m \omega(s) \Big|_{t_1}^t + \int_{t_1}^t ((t-s)^m)^\Delta \omega^\sigma(s) \Delta s. \quad (2.63)$$

Next, we show that if $t \geq \sigma(s)$ and $m \geq 1$, then

$$((t-s)^m)^\Delta \leq -m(t-\sigma(s))^{m-1}. \quad (2.64)$$

If $\mu(s) = 0$, it is easy to see that (2.64) is an equality. If $\mu(s) > 0$, then we get

$$((t-s)^m)^{\Delta_s} = \frac{1}{\mu(s)} [(t-\sigma(s))^m - (t-s)^m] = -\frac{1}{\sigma(s)-s} [(t-s)^m - (t-\sigma(s))^m]. \quad (2.65)$$

Using the inequality

$$x^m - y^m \geq my^{m-1}(x-y), \quad x \geq y > 0, \quad m \geq 1, \quad (2.66)$$

we obtain for $t \geq \sigma(s)$

$$[(t-s)^m - (t-\sigma(s))^m] \geq m(t-\sigma(s))^{m-1}(\sigma(s)-s), \quad (2.67)$$

and from this we see that (2.64) holds. From (2.62)–(2.64), we get

$$\begin{aligned} & \int_{t_1}^t (t-s)^m k \eta(s) p(s) \zeta(s) \Delta s \\ & \leq (t-t_1)^m \omega(t_1) + \int_{t_1}^t \left[(t-s)^m \frac{\eta^{\Delta}(s)}{\eta^{\sigma}(s)} - m(t-\sigma(s))^{m-1} \right] \omega^{\sigma}(s) \Delta s \\ & \quad - \int_{t_1}^t \frac{(t-s)^m \gamma M^{\gamma-1} \eta(s)}{r(s) (\eta^{\sigma}(s))^2} (\omega^{\sigma}(s))^2 \Delta s. \end{aligned} \quad (2.68)$$

Thus

$$\int_{t_1}^t \left((t-s)^m \eta(s) p(s) \zeta(s) - \frac{r(s) B^2(t,s) (\eta^{\sigma}(s))^2}{4k \gamma M^{\gamma-1} \eta(s) (t-s)^m} \right) \Delta s \leq \frac{1}{k} \omega(t_1) (t-t_1)^m, \quad (2.69)$$

which implies that

$$\frac{1}{t^m} \int_{t_1}^t \left((t-s)^m \eta(s) p(s) \zeta(s) - \frac{r(s) B^2(t,s) (\eta^{\sigma}(s))^2}{4k \gamma M^{\gamma-1} \eta(s) (t-s)^m} \right) \Delta s \leq \frac{1}{k} \omega(t_1) \left(\frac{t-t_1}{t} \right)^m. \quad (2.70)$$

This easily leads to a contradiction of (2.60). If (ii) holds, from Lemma 2.1, then $\lim_{t \rightarrow \infty} x(t) = 0$. If (iii) holds, by Lemma 2.4, then $\lim_{t \rightarrow \infty} x(t) = 0$. The proof is complete. \square

In the following theorem, we present a new Philos-type oscillation criteria for (1.2).

Theorem 2.10. *Assume that (H), (2.2), (2.26), and (2.38) hold, $\gamma \geq 1$. Let ζ and η be as defined in Theorem 2.5. Furthermore, assume that there exist functions $H, h \in C_{rd}(\mathbb{D}, \mathbb{R})$, where $\mathbb{D} \equiv \{(t, s) : t \geq s \geq t_0\}$ such that*

$$H(t, t) = 0, \quad t \geq t_0, \quad H(t, s) > 0, \quad t > s \geq t_0, \quad (2.71)$$

and H has a nonpositive continuous Δ -partial derivation $H^{\Delta_s}(t, s)$ with respect to the second variable and satisfies

$$H^{\Delta_s}(t, s) + H(t, s) \frac{\eta^{\Delta}(s)}{\eta^{\sigma}(s)} = -\frac{h(t, s)}{\eta^{\sigma}(s)} \sqrt{H(t, s)}. \quad (2.72)$$

If for some $0 < k < 1$ and for all constants $M > 0$

$$\limsup_{t \rightarrow \infty} \frac{1}{H(t, t_0)} \int_{t_0}^t K(t, s) \Delta s = \infty, \quad (2.73)$$

where

$$K(t, s) = H(t, s) \eta(s) p(s) \zeta(s) - \frac{r(s)(h_-(t, s))^2}{4k\gamma M^{\gamma-1} \eta(s)}, \quad (2.74)$$

where $h_-(t, s) = \max\{0, -h(t, s)\}$, then every solution x of (1.2) oscillates or $\lim_{t \rightarrow \infty} x(t) = 0$.

Proof. Suppose that (1.2) has a nonoscillatory solution x . We may assume without loss of generality that $x(t) > 0$, $x(\tau(t)) > 0$, and $x(\delta(t)) > 0$ for all $t \in [t_1, \infty)_{\mathbb{T}}$, $t_1 \in [t_0, \infty)_{\mathbb{T}}$. Then by Lemma 2.1, z satisfies three cases. Assume that z satisfies case (i). We proceed as in the proof of Theorem 2.5 to get (2.54) for all $t \geq t_1$ sufficiently large. Multiplying both sides of (2.54), with t replaced by s , by $H(t, s)$, integrating with respect to s from t_1 to t , we have

$$\begin{aligned} & \int_{t_1}^t kH(t, s) \eta(s) p(s) \zeta(s) \Delta s \\ & \leq - \int_{t_1}^t H(t, s) \omega^{\Delta}(s) \Delta s + \int_{t_1}^t H(t, s) \frac{\eta^{\Delta}(s)}{\eta^{\sigma}(s)} \omega^{\sigma}(s) \Delta s - \int_{t_1}^t H(t, s) \frac{\gamma M^{\gamma-1} \eta(s)}{r(s)(\eta^{\sigma}(s))^2} (\omega^{\sigma}(s))^2 \Delta s. \end{aligned} \quad (2.75)$$

Integrating by parts and using (2.71) and (2.72), we obtain

$$\begin{aligned} & \int_{t_1}^t kH(t, s) \eta(s) p(s) \zeta(s) \Delta s \\ & \leq H(t, t_1) \omega(t_1) + \int_{t_1}^t H^{\Delta_s}(t, s) \omega^{\sigma}(s) \Delta s + \int_{t_1}^t H(t, s) \frac{\eta^{\Delta}(s)}{\eta^{\sigma}(s)} \omega^{\sigma}(s) \Delta s \\ & \quad - \int_{t_1}^t H(t, s) \frac{\gamma M^{\gamma-1} \eta(s)}{r(s)(\eta^{\sigma}(s))^2} (\omega^{\sigma}(s))^2 \Delta s \\ & \leq H(t, t_1) \omega(t_1) + \int_{t_1}^t \left[-\frac{h(t, s)}{\eta^{\sigma}(s)} \sqrt{H(t, s)} \omega^{\sigma}(s) - H(t, s) \frac{\gamma M^{\gamma-1} \eta(s)}{r(s)(\eta^{\sigma}(s))^2} (\omega^{\sigma}(s))^2 \right] \Delta s \\ & \leq H(t, t_1) \omega(t_1) + \int_{t_1}^t \left[\frac{h_-(t, s)}{\eta^{\sigma}(s)} \sqrt{H(t, s)} \omega^{\sigma}(s) - H(t, s) \frac{\gamma M^{\gamma-1} \eta(s)}{r(s)(\eta^{\sigma}(s))^2} (\omega^{\sigma}(s))^2 \right] \Delta s \\ & \leq H(t, t_1) \omega(t_1) + \int_{t_1}^t \frac{r(s)(h_-(t, s))^2}{4\gamma M^{\gamma-1} \eta(s)} \Delta s. \end{aligned} \quad (2.76)$$

Therefore, we get

$$\int_{t_1}^t \left(H(t, s)\eta(s)p(s)\zeta(s) - \frac{r(s)(h_-(t, s))^2}{4k\gamma M^{\gamma-1}\eta(s)} \right) \Delta s \leq \frac{1}{k} H(t, t_1)\omega(t_1). \tag{2.77}$$

This easily leads to a contradiction of (2.73). If case (ii) holds, from Lemma 2.1, then $\lim_{t \rightarrow \infty} x(t) = 0$. If case (iii) holds, by Lemma 2.4, then $\lim_{t \rightarrow \infty} x(t) = 0$. The proof is complete. \square

The following result can be considered as the extension of the Atkinson’s theorem [39].

Theorem 2.11. *Assume that (H), (2.2), (2.26), and (2.38) hold, $\gamma > 1$. If*

$$\limsup_{t \rightarrow \infty} \int_{t_0}^t \frac{p(s)}{r(s)} \sigma(s) \left(\frac{h_2(\delta(s), t_0)}{\sigma(s)} \right)^\gamma \Delta s = \infty, \tag{2.78}$$

then every solution x of (1.2) is either oscillatory or $\lim_{t \rightarrow \infty} x(t) = 0$.

Proof. Suppose that (1.2) has a nonoscillatory solution x . We may assume without loss of generality that $x(t) > 0, x(\tau(t)) > 0$ and $x(\delta(t)) > 0$ for all $t \in [t_1, \infty)_{\mathbb{T}}, t_1 \in [t_0, \infty)_{\mathbb{T}}$. Then by Lemma 2.1, z satisfies three cases. Assume that z satisfies case (i). Define the function ω

$$\omega(t) = t \frac{r(t)z^{\Delta\Delta}(t)}{(z^\Delta(t))^\gamma}, \quad t \in [t_1, \infty)_{\mathbb{T}}. \tag{2.79}$$

Using the product rule, (2.25) and (2.27), for any $0 < k < 1$, we have that

$$\frac{z^\gamma(\delta(t))}{(z^{\Delta\sigma}(t))^\gamma} = \frac{z^\gamma(\delta(t))}{(z^\Delta(\delta(t)))^\gamma} \frac{(z^\Delta(\delta(t)))^\gamma}{(z^{\Delta\sigma}(t))^\gamma} \geq \left(k^{1/\gamma} \frac{h_2(\delta(t), t_0)}{\delta(t)} \right)^\gamma \left(\frac{\delta(t)}{\sigma(t)} \right)^\gamma = k \left(\frac{h_2(\delta(t), t_0)}{\sigma(t)} \right)^\gamma. \tag{2.80}$$

By (1.2), we have that (2.35) holds, then from (2.80), we calculate

$$\begin{aligned} \omega^\Delta(t) &= \left\{ r(t)z^{\Delta\Delta}(t) + \sigma(t)(r(t)z^{\Delta\Delta}(t))^\Delta \right\} (z^{\Delta\sigma}(t))^{-\gamma} + tr(t)z^{\Delta\Delta}(t) \left((z^\Delta(t))^{-\gamma} \right)^\Delta \\ &\leq r(t)z^{\Delta\Delta}(t) (z^{\Delta\sigma}(t))^{-\gamma} - \sigma(t)p(t) \left(\frac{z(\delta(t))}{z^{\Delta\sigma}(t)} \right)^\gamma + tr(t)z^{\Delta\Delta}(t) \left((z^\Delta(t))^{-\gamma} \right)^\Delta \\ &\leq r(t) \frac{\left((z^\Delta(t))^{1-\gamma} \right)^\Delta}{1-\gamma} - k\sigma(t)p(t) \left(\frac{h_2(\delta(t), t_0)}{\sigma(t)} \right)^\gamma, \end{aligned} \tag{2.81}$$

where the last inequality is true because $((z^\Delta(t))^{-\gamma})^\Delta \leq 0$ due to (2.1) and because

$$\begin{aligned} \left((z^\Delta(t))^{1-\gamma} \right)^\Delta &= (1-\gamma) \int_0^1 \left[h z^{\Delta\sigma}(t) + (1-h) z^\Delta(t) \right]^{-\gamma} z^{\Delta\Delta}(t) dh \\ &\leq (1-\gamma) \int_0^1 \left[h z^{\Delta\sigma}(t) + (1-h) z^{\Delta\sigma}(t) \right]^{-\gamma} z^{\Delta\Delta}(t) dh \\ &= (1-\gamma) \left(z^{\Delta\sigma}(t) \right)^{-\gamma} z^{\Delta\Delta}(t). \end{aligned} \quad (2.82)$$

Upon integration we arrive at

$$\begin{aligned} \int_{t_1}^t k\sigma(s) \frac{p(s)}{r(s)} \left(\frac{h_2(\delta(s), t_0)}{\sigma(s)} \right)^\gamma \Delta s &\leq \int_{t_1}^t \frac{\left((z^\Delta(s))^{1-\gamma} \right)^\Delta}{1-\gamma} \Delta s - \int_{t_1}^t \frac{\omega^\Delta(s)}{r(s)} \Delta s \\ &= \frac{(z^\Delta(t))^{1-\gamma}}{1-\gamma} - \frac{(z^\Delta(t_1))^{1-\gamma}}{1-\gamma} - \int_{t_1}^t \frac{\omega^\Delta(s)}{r(s)} \Delta s \\ &\leq \frac{(z^\Delta(t_1))^{1-\gamma}}{\gamma-1} + \frac{\omega(t_1)}{r(t_1)} - \frac{\omega(t)}{r(t)} + \int_{t_1}^t \omega^\sigma(s) \left(\frac{1}{r(s)} \right)^\Delta \Delta s \\ &\leq \frac{(z^\Delta(t_1))^{1-\gamma}}{\gamma-1} + \frac{\omega(t_1)}{r(t_1)} \end{aligned} \quad (2.83)$$

from $r^\Delta(t) \geq 0$. This contradicts (2.78). If case (ii) holds, from Lemma 2.1, then $\lim_{t \rightarrow \infty} x(t) = 0$. If case (iii) holds, by Lemma 2.4, then $\lim_{t \rightarrow \infty} x(t) = 0$. The proof is complete. \square

Theorem 2.12. Assume that (H), (2.2), (2.26), and (2.38) hold, $\gamma \leq 1$. Furthermore, assume that there exists a positive function $\eta \in C_{rd}^1([t_0, \infty)_{\mathbb{T}}, \mathbb{R})$ such that for some $0 < k < 1$ and for all constants $L > 0$

$$\limsup_{t \rightarrow \infty} \int_{t_0}^t \left(\eta(s) p(s) \zeta(s) - \frac{r(s) (\eta^\Delta(s))^2}{4k\gamma(L\sigma(s))^{\gamma-1} \eta(s)} \right) \Delta s = \infty, \quad (2.84)$$

where ζ is as defined as in Theorem 2.5. Then every solution x of (1.2) is either oscillatory or $\lim_{t \rightarrow \infty} x(t) = 0$.

Proof. Suppose that (1.2) has a nonoscillatory solution x . We may assume without loss of generality that $x(t) > 0$, $x(\tau(t)) > 0$ and $x(\delta(t)) > 0$ for all $t_1 t \in [t_1, \infty)_{\mathbb{T}}$, $\tau \in [t_0, \infty)_{\mathbb{T}}$. Then by Lemma 2.1, z satisfies three cases. Assume z satisfies case (i). Define the function ω as (2.44).

We proceed as in the proof of Theorem 2.5 and we get (2.49). In view of $\gamma \leq 1$, from (2.1) and (i) of Lemma 2.1, we have

$$\begin{aligned} \left((z^\Delta(t))^\gamma \right)^\Delta &= \gamma \int_0^1 \left[h z^{\Delta\sigma}(t) + (1-h) z^\Delta(t) \right]^{\gamma-1} z^{\Delta\Delta}(t) dh \\ &\geq \gamma \left(z^{\Delta\sigma}(t) \right)^{\gamma-1} z^{\Delta\Delta}(t), \end{aligned} \tag{2.85}$$

from (2.27), there exists a constant $L > 0$ such that $z^\Delta(t) \leq Lt$, so

$$\left((z^\Delta(t))^\gamma \right)^\Delta \geq \gamma (L\sigma(t))^{\gamma-1} z^{\Delta\Delta}(t). \tag{2.86}$$

By (2.49), we have

$$\omega^\Delta(t) \leq \frac{\eta^\Delta(t)}{\eta^\sigma(t)} \omega^\sigma(t) - k\eta(t)p(t)\zeta(t) - \gamma(L\sigma(t))^{\gamma-1} \frac{\eta(t)}{r(t)(\eta^\sigma(t))^2} (\omega^\sigma(t))^2. \tag{2.87}$$

Therefore, we obtain

$$\omega^\Delta(t) \leq -k\eta(t)p(t)\zeta(t) + \frac{r(t)(\eta^\Delta(t))^2}{4\gamma(L\sigma(t))^{\gamma-1}\eta(t)}. \tag{2.88}$$

Integrating inequality (2.88) from t_1 to t , we obtain

$$-\omega(t_1) \leq \omega(t) - \omega(t_1) \leq - \int_{t_1}^t \left(k\eta(s)p(s)\zeta(s) - \frac{r(s)(\eta^\Delta(s))^2}{4\gamma(L\sigma(s))^{\gamma-1}\eta(s)} \right) \Delta s, \tag{2.89}$$

which yields

$$\int_{t_1}^t \left(k\eta(s)p(s)\zeta(s) - \frac{r(s)(\eta^\Delta(s))^2}{4\gamma(L\sigma(s))^{\gamma-1}\eta(s)} \right) \Delta s \leq \omega(t_1) \tag{2.90}$$

for all large t , which contradicts (2.84). If case (ii) holds, from Lemma 2.1, then $\lim_{t \rightarrow \infty} x(t) = 0$. If case (iii) holds, by Lemma 2.4, then $\lim_{t \rightarrow \infty} x(t) = 0$. The proof is complete. \square

Remark 2.13. From Theorem 2.12, we can obtain different conditions for oscillation of all solutions of (1.2) with different choices of η .

For example, let $\eta(t) = t$. Now Theorem 2.12 yields the following results.

Corollary 2.14. *Assume that (H), (2.2), (2.26), and (2.38) hold, $\gamma \leq 1$. If*

$$\limsup_{t \rightarrow \infty} \int_{t_0}^t \left(sp(s) \left(\frac{h_2(\delta(s), t_0)}{s} \right)^\gamma - \frac{r(s)}{4k\gamma(L\sigma(s))^{\gamma-1}s} \right) \Delta s = \infty \tag{2.91}$$

holds for some $0 < k < 1$ and for all constants $L > 0$, then every solution x of (1.2) is either oscillatory or $\lim_{t \rightarrow \infty} x(t) = 0$.

For example, let $\eta(t) = 1$. From Theorem 2.12, we have the following result which can be considered as the extension of the Leighton-Wintner theorem.

Corollary 2.15. *Assume that (H), (2.2), (2.26), and (2.38) hold, $\gamma \leq 1$. If (2.59) holds, then every solution x of (1.2) is either oscillatory or $\lim_{t \rightarrow \infty} x(t) = 0$.*

In the following theorem, we present a new Kamenev-type oscillation criteria for (1.2).

Theorem 2.16. *Assume that (H), (2.2), (2.26), and (2.38) hold, $\gamma \leq 1$. Let ζ and η be as defined in Theorem 2.12. If for some $0 < k < 1$ and for all constants $L > 0$*

$$\limsup_{t \rightarrow \infty} \frac{1}{t^m} \int_{t_0}^t \left((t-s)^m \eta(s) p(s) \zeta(s) - \frac{r(s) B^2(t, s) (\eta^\sigma(s))^2}{4k\gamma (L\sigma(s))^{\gamma-1} \eta(s) (t-s)^m} \right) \Delta s = \infty, \quad (2.92)$$

where $m > 1$, and

$$B(t, s) = (t-s)^m \frac{\eta^\Delta(s)}{\eta^\sigma(s)} - m(t-\sigma(s))^{m-1}, \quad t \geq \sigma(s) \geq t_0, \quad (2.93)$$

then every solution x of (1.2) oscillates or $\lim_{t \rightarrow \infty} x(t) = 0$.

The proof is similar to that of Theorem 2.9 using inequality (2.88), so we omit the details.

In the following theorem, we present a new Philos-type oscillation criteria for (1.2).

Theorem 2.17. *Assume that (H), (2.2), (2.26), and (2.38) hold, $\gamma \leq 1$. Let ζ and η be as defined in Theorem 2.12. Furthermore, assume that there exist functions $H, h \in C_{rd}(\mathbb{D}, \mathbb{R})$, where $\mathbb{D} \equiv \{(t, s) : t \geq s \geq t_0\}$ such that (2.71) holds, and H has a nonpositive continuous Δ -partial derivation $H^{\Delta_s}(t, s)$ with respect to the second variable and satisfies (2.72). If*

$$\limsup_{t \rightarrow \infty} \frac{1}{H(t, t_0)} \int_{t_0}^t K(t, s) \Delta s = \infty \quad (2.94)$$

holds for some $0 < k < 1$ and for all constants $L > 0$, where

$$K(t, s) = H(t, s) \eta(s) p(s) \zeta(s) - \frac{r(s) (h_-(t, s))^2}{4k\gamma (L\sigma(s))^{\gamma-1} \eta(s)}, \quad (2.95)$$

where $h_-(t, s) = \max\{0, -h(t, s)\}$. Then every solution x of (1.2) oscillates or $\lim_{t \rightarrow \infty} x(t) = 0$.

The proof is similar to that of the proof of Theorem 2.10 using inequality (2.88), so we omit the details.

The following result can be considered as the extension of the Belohorec's theorem [40].

Theorem 2.18. Assume that (H), (2.2), (2.26), and (2.38) hold $\gamma < 1$. If

$$\limsup_{t \rightarrow \infty} \int_{t_0}^t \frac{p(s)}{r^\gamma(\delta(s))} (h_2(\delta(s), t_0))^\gamma \Delta s = \infty, \tag{2.96}$$

then every solution x of (1.2) is either oscillatory or satisfies $\lim_{t \rightarrow \infty} x(t) = 0$.

Proof. Suppose that (1.2) has a nonoscillatory solution x . We may assume without loss of generality that $x(t) > 0, x(\tau(t)) > 0$, and $x(\delta(t)) > 0$ for all $t_1 t \in [t_1, \infty)_{\mathbb{T}}, \in [t_0, \infty)_{\mathbb{T}}$. Then by Lemma 2.1, z satisfies three cases. Assume that z satisfies case (i). From (i) and (2.1) we have

$$\begin{aligned} \left((r(t)z^{\Delta\Delta}(t))^{1-\gamma} \right)^\Delta &= (1-\gamma) \int_0^1 \left[h(r(t)z^{\Delta\Delta}(t))^\sigma + (1-h)r(t)z^{\Delta\Delta}(t) \right]^{-\gamma} (r(t)z^{\Delta\Delta}(t))^\Delta dh \\ &\leq (1-\gamma) \int_0^1 \left[hr(t)z^{\Delta\Delta}(t) + (1-h)r(t)z^{\Delta\Delta}(t) \right]^{-\gamma} (r(t)z^{\Delta\Delta}(t))^\Delta dh \\ &= (1-\gamma) (r(t)z^{\Delta\Delta}(t))^{-\gamma} (r(t)z^{\Delta\Delta}(t))^\Delta, \end{aligned} \tag{2.97}$$

so

$$(r(t)z^{\Delta\Delta}(t))^{-\gamma} (r(t)z^{\Delta\Delta}(t))^\Delta \geq \frac{\left((r(t)z^{\Delta\Delta}(t))^{1-\gamma} \right)^\Delta}{1-\gamma}. \tag{2.98}$$

By (1.2), we have that (2.35) holds. Using (2.25) and (2.27), for any $0 < k < 1$, we obtain after dividing (2.35) by $(r(t)z^{\Delta\Delta}(t))^\gamma$ for all large t

$$\begin{aligned} 0 &\geq \frac{(r(t)z^{\Delta\Delta}(t))^\Delta + p(t)z^\gamma(\delta(t))}{(r(t)z^{\Delta\Delta}(t))^\gamma} \\ &= (r(t)z^{\Delta\Delta}(t))^{-\gamma} (r(t)z^{\Delta\Delta}(t))^\Delta + p(t) \left(\frac{z(\delta(t))}{r(t)z^{\Delta\Delta}(t)} \right)^\gamma \\ &\geq \frac{\left((r(t)z^{\Delta\Delta}(t))^{1-\gamma} \right)^\Delta}{1-\gamma} + \frac{p(t)}{r^\gamma(\delta(t))} \left(\frac{z(\delta(t))}{z^\Delta(\delta(t))} \frac{z^\Delta(\delta(t))}{z^{\Delta\Delta}(\delta(t))} \right)^\gamma \\ &\geq \frac{\left((r(t)z^{\Delta\Delta}(t))^{1-\gamma} \right)^\Delta}{1-\gamma} + \frac{p(t)}{r^\gamma(\delta(t))} \left(k \frac{h_2(\delta(t), t_0)}{\delta(t)} \delta(t) \right)^\gamma \\ &= \frac{\left((r(t)z^{\Delta\Delta}(t))^{1-\gamma} \right)^\Delta}{1-\gamma} + k^\gamma \frac{p(t)}{r^\gamma(\delta(t))} (h_2(\delta(t), t_0))^\gamma. \end{aligned} \tag{2.99}$$

So,

$$k^\gamma \frac{p(t)}{r^\gamma(\delta(t))} (h_2(\delta(t), t_0))^\gamma \leq \frac{\left((r(t)z^{\Delta\Delta}(t))^{1-\gamma} \right)^\Delta}{\gamma - 1}. \quad (2.100)$$

Upon integration we arrive at

$$\int_{t_1}^t k^\gamma \frac{p(s)}{r^\gamma(\delta(s))} (h_2(\delta(s), t_0))^\gamma \Delta s \leq \int_{t_1}^t \frac{\left((r(s)z^{\Delta\Delta}(s))^{1-\gamma} \right)^\Delta}{\gamma - 1} \Delta s \leq \frac{(r(t_1)z^{\Delta\Delta}(t_1))^{1-\gamma}}{1 - \gamma}. \quad (2.101)$$

This contradicts (2.96). If case (ii) holds, from Lemma 2.1, then $\lim_{t \rightarrow \infty} x(t) = 0$. If case (iii) holds, by Lemma 2.4, then $\lim_{t \rightarrow \infty} x(t) = 0$. The proof is complete. \square

Remark 2.19. One can easily see that the results obtained in [14–16, 21, 23, 24, 35] cannot be applied in (1.2), so our results are new.

3. Examples

In this section we give the following examples to illustrate our main results.

Example 3.1. Consider the third-order neutral delay dynamic equations on time-scales

$$\left(x(t) - \frac{1}{2}x(\tau(t)) \right)^{\Delta\Delta\Delta} + \frac{\beta}{t} \left(\frac{t}{h_2(\delta(t), t_0)} \right)^\gamma x^\gamma(\delta(t)) = 0, \quad t \in [t_0, \infty)_{\mathbb{T}}, \quad (3.1)$$

where $\beta > 0$, $1 < \gamma < 2$ is a quotient of odd positive integers, $h_2(\delta(t), t_0) \leq t^2$.

Let $r(t) = 1$, $a(t) = 1/2$, $p(t) = (\beta/t) (t/h_2(\delta(t), t_0))^\gamma$. It is easy to see that (2.2), (2.26), and (2.38) hold. Also

$$\limsup_{t \rightarrow \infty} \int_{t_0}^t p(s) \left(\frac{h_2(\delta(s), t_0)}{s} \right)^\gamma \Delta s = \beta \limsup_{t \rightarrow \infty} \int_{t_0}^t \frac{\Delta s}{s} = \infty. \quad (3.2)$$

Hence by Corollary 2.8, every solution x of (3.1) is either oscillatory or $\lim_{t \rightarrow \infty} x(t) = 0$.

Example 3.2. Consider the third-order neutral delay differential equation

$$\left(x(t) - \frac{1}{10}x(t-2) \right)''' + \left(1 - \frac{e^2}{10} \right) e^{2t} x^3(t) = 0, \quad t \in [t_0, \infty). \quad (3.3)$$

Let $\gamma = 3$, $r(t) = 1$, $a(t) = 1/10$, $p(t) = (1 - e^2/10)e^{2t}$. It is easy to see that all the conditions of Corollary 2.8 hold. Then by Corollary 2.8, every solution x of (3.3) is either oscillatory or satisfies $\lim_{t \rightarrow \infty} x(t) = 0$. In fact, $x(t) = e^{-t}$ is a solution of (3.3).

Example 3.3. Consider the third-order delay dynamic equation

$$\left(t \left(x(t) - \frac{1}{2} x(\tau(t)) \right)^{\Delta\Delta} \right)^{\Delta} + \frac{\beta t^{\gamma-1}}{\delta^2(t)} x^{\gamma}(\delta(t)) = 0, \quad t \in [1, \infty)_{\mathbb{T}}, \tag{3.4}$$

where $\mathbb{T} = q^{\mathbb{N}_0}$, $\beta > 0$, $\gamma > 1$ is a quotient of odd positive integers.

For $\mathbb{T} = q^{\mathbb{N}_0}$, we have $h_2(\delta(t), t_0) = h_2(\delta(t), 1) = (\delta(t) - 1)(\delta(t) - q)/(1 + q)$, $\sigma(t) = qt$. Let $r(t) = t$, $p(t) = \beta t^{\gamma-1}/\delta^2(t)$. It is easy to see that (2.2) and (2.38) hold, and

$$\begin{aligned} \int_{t_0}^{\infty} p(t) (h_2(\delta(t), t_0))^{\gamma} \Delta t &= \beta \int_1^{\infty} \frac{t^{\gamma-1}}{\delta^2(t)} \left(\frac{(\delta(t) - 1)(\delta(t) - q)}{1 + q} \right)^{\gamma} \Delta t \\ &\geq l\beta \int_1^{\infty} t^{\gamma-1} \Delta t = \infty, \quad \text{for some } 0 < l < 1. \end{aligned} \tag{3.5}$$

Hence (2.26) holds. Also

$$\begin{aligned} \limsup_{t \rightarrow \infty} \int_{t_0}^t \frac{p(s)}{r(s)} \sigma(s) \left(\frac{h_2(\delta(s), t_0)}{\sigma(s)} \right)^{\gamma} \Delta s \\ = \beta q^{1-\gamma} \limsup_{t \rightarrow \infty} \int_1^t \frac{1}{s \delta^2(s)} \left(\frac{(\delta(s) - 1)(\delta(s) - q)}{1 + q} \right)^{\gamma} \Delta s = \infty, \end{aligned} \tag{3.6}$$

so (2.78) holds. By Theorem 2.11, every solution x of (3.4) is either oscillatory or satisfies $\lim_{t \rightarrow \infty} x(t) = 0$.

Example 3.4. Consider the third-order delay dynamic equation

$$\left(x(t) - \frac{1}{3} x(\tau(t)) \right)^{\Delta\Delta\Delta} + \frac{\beta}{t} \left(\frac{1}{h_2(\delta(t), t_0)} \right)^{\gamma} x^{\gamma}(\delta(t)) = 0, \quad t \in [t_0, \infty)_{\mathbb{T}}, \tag{3.7}$$

where $h_2(\delta(t), t_0) \leq t^2$, $\beta > 0$, $\gamma < 1$ is a quotient of odd positive integers.

Let $r(t) = 1$, $p(t) = (\beta/t)(1/h_2(\delta(t), t_0))^{\gamma}$. It is easy to see that (2.2), (2.26), and (2.38) hold. Also we have

$$\limsup_{t \rightarrow \infty} \int_{t_0}^t \frac{p(s)}{r^{\gamma}(\delta(s))} (h_2(\delta(s), t_0))^{\gamma} \Delta s = \beta \limsup_{t \rightarrow \infty} \int_{t_0}^t \frac{\Delta s}{s} = \infty. \tag{3.8}$$

Hence (2.96) holds. By Theorem 2.18, every solution x of (3.7) is either oscillatory or satisfies $\lim_{t \rightarrow \infty} x(t) = 0$.

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