

## Research Article

# Integral BVPs for a Class of First-Order Impulsive Functional Differential Equations

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The methods of lower and upper solutions and monotone iterative technique are employed to the study of integral boundary value problems for a class of first-order impulsive functional differential equations. Sufficient conditions are obtained for the existence of extreme solutions.

## 1. Introduction and Preliminaries

In this paper, we study the following integral boundary value problems (BVPs for short) of the impulsive functional differential equation

$$\begin{aligned}x'(t) + b(t)x(t) &= f(t, x(t), [Kx](t)), \quad t \neq t_k, \quad t \in J = [0, T], \\ \Delta x(t_k) &= I_k(x(t_k)), \quad k = 1, 2, \dots, m, \\ x(0) + \mu \int_0^T x(s) ds &= x(T), \quad \mu \leq 0,\end{aligned}\tag{1.1}$$

where  $f \in C(J \times R^2, R)$ ,  $I_k \in C(R, R)$ ,  $(1 \leq k \leq m)$ ,  $b(t) \in C(R)$ ,  $b(t) \leq 0$ ,  $J = [0, T]$ ,  $0 = t_0 < t_1 < t_2 < \dots < t_m < t_{m+1} = T$ .  $K : PC(J) \rightarrow PC(J)$ , where  $PC(J) = \{u : J \rightarrow R, u \text{ is continuous for } t \in J, t \neq t_k, u(t_i^+), u(t_i^-) \text{ exist, and } u(t_i^-) = u(t_i), i = 1, 2, \dots, m\}$ . Furthermore, we will assume that  $K$  is continuous and monotone nondecreasing, and for any bounded set  $A \subseteq PC(J)$ ,  $KA$  is bounded.  $\Delta x(t_k) = x(t_k^+) - x(t_k^-)$  denotes the jump of  $x(t)$  at  $t = t_k$ ;  $x(t_k^+)$  and  $x(t_k^-)$  represent the right and left limits of  $x(t)$  at  $t = t_k$ , respectively. Denote  $J' = J \setminus \{t_1, t_2, \dots, t_m\}$ .

Let  $PC^1(J) = \{u \in PC(J) : u \text{ be continuously differentiable for } t \in J, t \neq t_k\}$ .  $PC(J)$  and  $PC^1(J)$  are Banach spaces with the norms

$$\|u\|_{PC(J)} = \sup\{|u(t)| : t \in J\}, \quad \|u\|_{PC^1(J)} = \max\{\|u\|_{PC(J)}, \|u'\|_{PC(J)}\}. \quad (1.2)$$

By a solution of (1.1) we mean a  $u \in PC^1(J)$  for which problem (1.1) is satisfied.

Note that (1.1) has a very general form, as special instances resulting from (1.1), one can have impulsive differential equations with deviating arguments and impulsive differential equations with the Volterra or Fredholm operators. When  $\mu = 0$ ,  $I_k \equiv 0$ , (1.1) reduces to

$$\begin{aligned} x'(t) + b(t)x(t) &= f(t, x(t), [Kx](t)), \quad t \in J = [0, T], \\ x(0) &= x(T). \end{aligned} \quad (1.3)$$

In [1], Cao and Li. studied and understood existence and stability of solution of this equation by using fixed theorem and monotone iteration techniques.

When  $\mu = 0$ ,  $b(t) \equiv 0$ , (1.1) reduces to

$$\begin{aligned} x'(t) &= f(t, x(t), [Kx](t)), \quad t \neq t_k, \quad t \in J = [0, T], \\ \Delta x(t_k) &= I_k(x(t_k)), \quad k = 1, 2, \dots, m, \\ x(0) &= x(T). \end{aligned} \quad (1.4)$$

In [2], Li discussed and built the existence theorem of solutions of this equation by using fixed theorem, upper and lower solutions methods and monotone iterative techniques.

When  $\mu = 0$ ,  $b(t) \equiv 0$ ,  $[Kx](t) = x(t)$ , the equation (1.1) reduces to the periodic boundary value problem of the impulsive differential equation

$$\begin{aligned} x'(t) &= f(t, x(t)), \quad t \neq t_k, \quad t \in J = [0, T], \\ \Delta x(t_k) &= I_k(x(t_k)), \quad k = 1, 2, \dots, m, \\ x(0) &= x(T). \end{aligned} \quad (1.5)$$

There are plenty of results on studying the periodic boundary value problem of impulsive differential equations (see [3–8]). According to author's know, there are no dependent references for studying the (1.1) yet. To fill in this void, we try to find the conditions on  $f$  and  $I_k$ , so that make sure that the (1.1) exists extremal solution.

It is well known that the monotone iterative technique offers an approach for obtaining approximate solutions of nonlinear differential equations, for details, see [4] and the references therein. There also exist several works devoted to the applications of this technique to boundary value problems of impulsive differential equations, see, for example, [1–3, 5–14]. In this paper, we consider (1.1) by using the method of upper and lower

solutions combined with monotone iterative technique. This technique plays an important role in constructing monotone sequences which converge to the solutions of our problems. In presence of a lower solution  $\alpha$  and an upper solution  $\beta$  with  $\alpha \leq \beta$ , we show under suitable conditions the sequences converge to the solutions of (1.1) by using the method of upper and lower solutions and monotone iterative technique.

*Definition 1.1.* The functions  $\alpha, \beta \in PC^1(J)$  are called lower solution and upper solution of (1.1), respectively, if

$$\begin{aligned} \alpha'(t) + b(t)\alpha(t) &\leq f(t, \alpha(t), [K\alpha](t)), \quad t \neq t_k, t \in J, \\ \Delta\alpha(t_k) &\leq I_k(\alpha(t_k)), \quad k = 1, 2, \dots, m, \\ \alpha(0) + \mu \int_0^T \alpha(s) ds &\leq \alpha(T), \quad \mu \leq 0. \\ \beta'(t) + b(t)\beta(t) &\geq f(t, \beta(t), [K\beta](t)), \quad t \neq t_k, t \in J, \\ \Delta\beta(t_k) &\geq I_k(\beta(t_k)), \quad k = 1, 2, \dots, m, \\ \beta(0) + \mu \int_0^T \beta(s) ds &\geq \beta(T), \quad \mu \leq 0. \end{aligned} \tag{1.6}$$

In what follows we define the set

$$[\alpha, \beta] = \{w \in PC(J, R) : \alpha(t) \leq w(t) \leq \beta(t), t \in J\} \tag{1.7}$$

for  $\alpha, \beta \in PC(J, R)$  and  $\alpha \leq \beta$ .

We list the following conditions.

(H<sub>1</sub>)  $\alpha(t), \beta(t)$  are lower and upper solutions of (1.1) such that  $\alpha(t) \leq \beta(t)$ .

(H<sub>2</sub>) There exists  $M \geq 0$  such that

$$f(t, x, y) - f(t, \bar{x}, \bar{y}) \geq -M(x - \bar{x}), \tag{1.8}$$

for  $\alpha(t) \leq \bar{x} \leq x \leq \beta(t)$ ,  $[T\alpha](t) \leq \bar{y} \leq y \leq [T\beta](t)$ ,  $t \in J$ .

(H<sub>3</sub>) There exist  $0 \leq L_k < 1$ ,  $k = 1, 2, \dots, m$  such that

$$I_k(x) - I_k(y) \geq -L_k(x - y), \quad k = 1, 2, \dots, m, \tag{1.9}$$

for  $\alpha(t) \leq y \leq x \leq \beta(t)$ ,  $t \in J$ .

## 2. Main Results

To obtain our main results, we need the following lemmas.

**Lemma 2.1** (see [9]). *Suppose that the following conditions are satisfied.*

(A<sub>0</sub>) *Sequence  $\{t_k\}$  satisfies  $0 \leq t_0 < t_1 < t_2 \cdots$ , and  $\lim_{n \rightarrow \infty} t_n = \infty$ .*

(A<sub>1</sub>)  *$m \in PC^1[J, R]$  and  $m(t)$  is left continuous at  $t_k$ ,  $k = 1, 2, \dots$*

(A<sub>2</sub>) *For  $k = 1, 2, \dots$ ,  $t \geq t_0$ ,*

$$\begin{aligned} m'(t) &\leq p(t)m(t) + q(t), \quad t \neq t_k, \quad t \in J, \\ m(t_k^+) &\leq d_k m(t_k) + b_k, \quad k = 1, 2, \dots, m, \end{aligned} \quad (2.1)$$

where  $q, p \in C[R_+, R]$ ,  $b_k, d_k \geq 0$  are constants, then

$$\begin{aligned} m(t) &\leq m(t_0) \prod_{t_0 < t_k \leq t} d_k \exp\left(\int_{t_0}^t p(s) ds\right) \\ &+ \sum_{t_0 < t_k \leq t} \left( \prod_{t_k < t_j \leq t} d_j \exp\left(\int_{t_k}^t p(s) ds\right) \right) b_k \\ &+ \int_{t_0}^t \prod_{t_0 < t_k < t} d_k \exp\left(\int_s^t p(\sigma) d\sigma\right) q(s) ds. \end{aligned} \quad (2.2)$$

**Lemma 2.2** (see [12]). *If  $m \in PC^1(J)$  and*

$$\begin{aligned} m'(t) &\leq -Mm(t), \quad t \neq t_k, \quad t \in J = [0, T], \\ \Delta m(t_k) &\leq -L_k m(t_k), \quad k = 1, 2, \dots, m, \\ m(0) &\leq m(T), \end{aligned} \quad (2.3)$$

where  $M > 0$ ,  $0 < L_k \leq 1$ , then  $m(t) \leq 0$ ,  $t \in J$ .

**Lemma 2.3.** *If  $x \in PC(J)$ ,  $M > 0$ ,  $0 < L_k \leq 1$ ,  $k = 1, 2, \dots, m$ , and  $(1/(1 - e^{-MT})) \sum_{k=0}^m L_k < 1$ , then the equation*

$$\begin{aligned} x'(t) + Mx(t) &= \sigma(t), \quad t \neq t_k, \quad t \in J = [0, T], \\ \Delta x(t_k) &= -L_k x(t_k) + d_k, \quad k = 1, 2, \dots, m, \\ x(0) + d &= x(T), \quad d \in R \end{aligned} \quad (2.4)$$

has one unique solution.

*Proof.* Firstly, we prove that (2.4) is equivalent to the integral equation

$$x(t) = -\frac{e^{-Mt}}{1 - e^{-MT}}d + \int_0^T G(t, s)\sigma(s)ds + \sum_{k=0}^m G(t, t_k)(-L_k x(t_k) + d_k), \quad (2.5)$$

where

$$G(t, s) = \begin{cases} \frac{e^{-M(t-s)}}{1 - e^{-MT}}, & 0 \leq s < t \leq T, \\ \frac{e^{-M(T+t-s)}}{1 - e^{-MT}}, & 0 \leq t \leq s \leq T. \end{cases} \quad (2.6)$$

If  $x(t) \in PC^1(J)$  is solution of (2.4), then, by directly integrating we obtain

$$x(t) = -\frac{e^{-Mt}}{1 - e^{-MT}}d + \int_0^T G(t, s)\sigma(s)ds + \sum_{k=0}^m G(t, t_k)(-L_k x(t_k) + d_k). \quad (2.7)$$

If  $x(t) \in PC^1(J)$  is solution of the above-mentioned integral equation, then

$$\begin{aligned} x'(t) &= -M \left[ -\frac{e^{-Mt}}{1 - e^{-MT}}d + \int_0^T G(t, s)\sigma(s)ds + \sum_{k=0}^m G(t, t_k)(-L_k x(t_k) + d_k) \right] + \sigma(t) \\ &= -Mx(t) + \sigma(t), \quad t \neq t_k, \\ \Delta x(t_k) &= -L_k(x(t_k)) + d_k, \quad k = 1, 2, \dots, m, \end{aligned} \quad (2.8)$$

$$\begin{aligned} x(0) &= -\frac{1}{1 - e^{-MT}}d + \int_0^T \frac{e^{-M(T-s)}}{1 - e^{-MT}}\sigma(s)ds + \sum_{k=0}^m \frac{e^{-M(T-t_k)}}{1 - e^{-MT}}(-L_k x(t_k) + d_k), \\ x(T) &= -\frac{e^{-MT}}{1 - e^{-MT}}d + \int_0^T \frac{e^{-M(T-s)}}{1 - e^{-MT}}\sigma(s)ds + \sum_{k=0}^m \frac{e^{-M(T-t_k)}}{1 - e^{-MT}}(-L_k x(t_k) + d_k). \end{aligned}$$

This yields  $x(0) + d = x(T)$ . So (2.4) is equivalent to the integral equation

$$x(t) = -\frac{e^{-Mt}}{1 - e^{-MT}}d + \int_0^T G(t, s)\sigma(s)ds + \sum_{k=0}^m G(t, t_k)(-L_k x(t_k) + d_k). \quad (2.9)$$

Now, we define operator  $A : PC(J) \rightarrow PC(J)$  as

$$(Ax)(t) = -\frac{e^{-Mt}}{1 - e^{-MT}}d + \int_0^T G(t, s)\sigma(s)ds + \sum_{k=0}^m G(t, t_k)(-L_k x(t_k) + d_k). \quad (2.10)$$

For each  $x, y \in PC(J)$ ,

$$|(Ax)(t) - (Ay)(t)| \leq \frac{1}{1 - e^{-MT}} \sum_{k=0}^m L_k |x - y| \leq \frac{1}{1 - e^{-MT}} \sum_{k=0}^m L_k \|x(t_k) - y(t_k)\|, \quad (2.11)$$

and so

$$\|(Ax)(t) - (Ay)(t)\| \leq \frac{1}{1 - e^{-MT}} \sum_{k=0}^m L_k \|x(t_k) - y(t_k)\|. \quad (2.12)$$

This indicates that  $A : PC(J) \rightarrow PC(J)$  is a contraction mapping. Then there is one unique  $x \in PC(J)$  such that  $Ax = x$ , that is, (2.4) has an unique solution  $x(t)$ . The proof is complete.  $\square$

**Theorem 2.4.** *If the conditions  $(H_1)$ ,  $(H_2)$ ,  $(H_3)$  are all satisfied, and, in addition, if there exist  $M > 0$ ,  $0 < L_k \leq 1$ ,  $k = 1, 2, \dots, m$ , such that  $(1/(1 - e^{-MT})) \sum_{k=0}^m L_k < 1$ , then the impulsive equation (1.1) has minimal and maximal solutions  $\rho(t), r(t) \in PC^1(J)$  in  $[\alpha, \beta]$ , and there are monotone sequences  $\{\alpha_n\}, \{\beta_n\}$  converging uniformly to  $\rho(t), r(t)$  in  $J$ , respectively, where  $\alpha_0 = \alpha$ ,  $\beta_0 = \beta$ , and  $\alpha_n(t), \beta_n(t)$  are lower and upper solutions of (1.1), respectively.*

*Proof.* For each  $\psi \in [\alpha, \beta]$ , we consider the equation

$$\begin{aligned} x'(t) &= f(t, \psi(t), [K\psi](t)) - b(t)\psi(t) - M(x(t) - \psi(t)), \quad t \neq t_k, \quad t \in J, \\ \Delta x(t_k) &= I_k(\psi(t_k)) - L_k(x(t_k) - \psi(t_k)), \quad k = 1, 2, \dots, m, \\ x(0) + \mu \int_0^T \psi(s) ds &= x(T), \quad \mu \leq 0. \end{aligned} \quad (2.13)$$

By Lemma 2.3, we know that (2.13) has a unique solution  $x(t) \in PC^1(J)$ . Now, we define operator  $A : PC^1(J) \rightarrow PC^1(J)$  as  $A\psi = x$ .

We will prove that  $\{\alpha_n\}, \{\beta_n\}$  have the following properties.

- (a)  $\alpha_0 \leq A\alpha_0, A\beta_0 \leq \beta_0$ .
- (b)  $A$  is monotone nondecreasing on  $[\alpha_0, \beta_0]$ .

Proofs of properties (a), (b) are divided into three steps to proceed.

*Step 1.* Suppose that  $p = \alpha_0 - \alpha_1$ , then

$$\begin{aligned} p' &= \alpha'_0 - \alpha'_1 \leq -b(t)\alpha(t) + f(t, \alpha(t), [K\alpha](t)) - f(t, \alpha(t), [K\alpha(t)](t)) \\ &\quad + b(t)\alpha(t) + M(\alpha_1(t) - \alpha(t)) = -Mp(t), \quad t \neq t_k, \\ \Delta p(t_k) &= \Delta\alpha_0 - \Delta\alpha_1 \leq I_k(\alpha(t_k)) - I_k(\alpha(t_k)) + L_k(\alpha_1(t_k) - \alpha(t_k)) = -L_k p(t_k), \quad t = t_k, \\ p(0) &= \alpha_0(0) - \alpha_1(0) \leq p(T). \end{aligned} \quad (2.14)$$

By Lemma 2.2, we obtain  $p(t) \leq 0, t \in J$ , so  $\alpha_0(t) \leq \alpha_1(t)$ .

Step 2. Suppose that  $p = \beta_1 - \beta_0$ , then

$$\begin{aligned} p' &= \beta_1' - \beta_0' \leq b(t)\beta(t) - f(t, \beta(t), [K\beta](t)) + f(t, \beta(t), [K\beta(t)](t)) \\ &\quad - b(t)\beta(t) - M(\beta_1(t) - \beta(t)) = -Mp(t), \quad t = t_k, \\ \Delta p(t_k) &= \Delta\beta_1 - \Delta\beta_0 \leq -I_k(\beta(t_k)) + I_k(\beta(t_k)) - L_k(\beta_1(t_k) - \beta(t_k)) = -L_k p(t_k), \quad t = t_k, \\ p(0) &= \beta_1(0) - \beta_0(0) \leq p(T). \end{aligned} \quad (2.15)$$

By Lemma 2.2, we obtain  $p(t) \leq 0, t \in J$ , so  $\beta_1(t) \leq \beta_0(t)$ .

Similarly we can show that  $\alpha_1(t) \leq \beta_1(t)$ , hence  $\alpha_0(t) \leq \alpha_1(t) \leq \beta_1(t) \leq \beta_0(t)$ .

Step 3. If  $n = m$ ,  $\alpha_{m-1} \leq \alpha_m \leq \beta_m \leq \beta_{m-1}$ , then when  $n = m + 1$ , let  $p = \alpha_m - \alpha_{m+1}$ . Then

$$\begin{aligned} p' &= \alpha_m' - \alpha_{m+1}' \leq -b(t)\alpha_{m-1}(t) + f(t, \alpha_{m-1}(t), [K\alpha_{m-1}](t)) \\ &\quad - M(\alpha_m(t) - \alpha_{m-1}(t)) - f(t, \alpha_m(t), [K\alpha_m(t)](t)) \\ &\quad + b(t)\alpha_m(t) + M(\alpha_{m+1}(t) - \alpha_m(t)) \\ &= -b(t)(\alpha_{m-1} - \alpha_m) - Mp(t), \quad t \neq t_k. \end{aligned} \quad (2.16)$$

Furthermore,  $b(t) \leq 0$ ,  $\alpha_{m-1} - \alpha_m \leq 0$ , thus  $p' = \alpha_m' - \alpha_{m+1}' \leq -Mp(t)$ ,

$$\begin{aligned} \Delta p(t_k) &= \Delta\alpha_m - \Delta\alpha_{m+1} = I_k(\alpha_{m-1}(t_k)) - L_k(\alpha_m(t_k) - \alpha_{m-1}(t_k)) \\ &\quad - I_k(\alpha_m(t_k)) + L_k(\alpha_{m+1}(t_k) - \alpha_m(t_k)) \leq -L_k p(t_k), \quad t = t_k, \\ p(0) &= \alpha_m(0) - \alpha_{m+1}(0) = \mu \int_0^T (\alpha_m(s) - \alpha_{m-1}(s)) ds + p(T) \leq p(T). \end{aligned} \quad (2.17)$$

By Lemma 2.2, we obtain  $p(t) \leq 0, t \in J$ , so  $\alpha_m(t) \leq \alpha_{m+1}(t)$ .

Similarly, we can assume that  $p = \beta_{m+1} - \beta_m$ . When  $t \neq t_k$ ,

$$\begin{aligned} p' &= \beta_{m+1}' - \beta_m' \leq -b(t)\beta_m(t) + f(t, \beta_m(t), [K\beta_m](t)) - M(\beta_{m+1}(t) - \beta_m(t)) \\ &\quad - f(t, \beta_{m-1}(t), [K\beta_{m-1}](t)) + b(t)\beta_{m-1}(t) + M(\beta_m(t) - \beta_{m-1}(t)) \\ &= -b(t)(\beta_m - \beta_{m-1}) - Mp(t). \end{aligned} \quad (2.18)$$

Furthermore,  $b(t) \leq 0$ ,  $\beta_m - \beta_{m-1} \leq 0$ , thus  $p' = \beta_{m+1}' - \beta_m' \leq -Mp(t)$ , when  $t = t_k$ ,

$$\begin{aligned} \Delta p(t_k) &= \Delta\beta_{m+1} - \Delta\beta_m = I_k(\beta_m(t_k)) - L_k(\beta_{m+1}(t_k) - \beta_m(t_k)) \\ &\quad - I_k(\beta_{m-1}(t_k)) + L_k(\beta_m(t_k) - \beta_{m-1}(t_k)) \leq -L_k p(t_k), \\ p(0) &= \beta_{m+1}(0) - \beta_m(0) = \mu \int_0^T (\beta_{m-1}(s) - \beta_m(s)) ds + p(T) \leq p(T), \end{aligned} \quad (2.19)$$

hence by Lemma 2.2, we obtain  $p(t) \leq 0, t \in J$ , so  $\beta_{m+1}(t) \leq \beta_m(t)$ .

In the same way we can prove that  $\alpha_{m+1}(t) \leq \beta_{m+1}(t)$ .  
Thus by mathematical induction we can know that

$$\alpha_{n-1} \leq \alpha_n \leq \beta_n \leq \beta_{n-1}, \quad n = 0, 1, 2, \dots, t \in J. \quad (2.20)$$

So far, we finish the proof of the properties (a), (b).

Now we prove that  $\alpha_n, \beta_n, n = 0, 1, 2, \dots$ , are lower and upper solutions of (1.1).  
Similarly, we can use mathematical induction to prove this.

When  $n = 0$ ,  $\alpha_0, \beta_0$  are already lower and upper solutions of (1.1).

When  $n = 1$ ,

$$\begin{aligned} \alpha_1(t) &= f(t, \alpha(t), [K\alpha](t)) - b(t)\alpha(t) - M(\alpha_1(t) - \alpha(t)) \\ &\quad - f(t, \alpha_1(t), [K\alpha_1](t)) + f(t, \alpha_1(t), [K\alpha_1](t)) \\ &\leq f(t, \alpha_1(t), [K\alpha_1](t)) - b(t)\alpha_1(t), \quad t \neq t_k, t \in J, \\ \Delta\alpha_1(t_k) &= I_k(\alpha(t_k)) - L_k(\alpha_1(t_k) - \alpha(t_k)) + I_k(\alpha_1(t_k)) - I_k(\alpha_1(t_k)) \\ &\leq I_k(\alpha_1(t_k)), \quad k = 1, 2, \dots, m, \\ \alpha_1(0) + \mu \int_0^T \alpha_1(s) ds &\leq \alpha_1(0) + \mu \int_0^T \alpha(s) ds = \alpha_1(T), \quad \mu \leq 0. \end{aligned} \quad (2.21)$$

Thus  $\alpha_1$  is lower solution of (1.1).

Suppose that  $\alpha_n$  is lower solution of (1.1) when  $n = m$ .

Then when  $n = m + 1$ ,

$$\begin{aligned} \alpha_{m+1}(t) &= f(t, \alpha_m(t), [K\alpha_m](t)) - b(t)\alpha_m(t) - M(\alpha_{m+1}(t) - \alpha_m(t)) \\ &\quad - f(t, \alpha_{m+1}(t), [K\alpha_{m+1}](t)) + f(t, \alpha_{m+1}(t), [K\alpha_{m+1}](t)) \\ &\leq f(t, \alpha_{m+1}(t), [K\alpha_{m+1}](t)) - b(t)\alpha_{m+1}(t), \quad t \neq t_k, t \in J, \\ \Delta\alpha_{m+1}(t_k) &= I_k(\alpha_m(t_k)) - L_k(\alpha_{m+1}(t_k) - \alpha_m(t_k)) + I_k(\alpha_{m+1}(t_k)) \\ &\quad - I_k(\alpha_{m+1}(t_k)) \leq I_k(\alpha_{m+1}(t_k)), \quad k = 1, 2, \dots, m, \\ \alpha_{m+1}(0) + \mu \int_0^T \alpha_{m+1}(s) ds &\leq \alpha_{m+1}(0) + \mu \int_0^T \alpha_m(s) ds = \alpha_{m+1}(T). \end{aligned} \quad (2.22)$$

Thus by mathematical induction we can know that  $\alpha_n$  is lower solution of (1.1). In the same way we can prove that  $\beta_n$  is upper solution of (1.1).

By  $\alpha_{n-1} \leq \alpha_n \leq \beta_n \leq \beta_{n-1}, n = 0, 1, 2, \dots, t \in J$ , we can know that when  $n \rightarrow +\infty, \{\alpha_n\}, \{\beta_n\}$  have limits  $\rho(t), r(t)$ , respectively. Since they are independent of  $t$  when  $n \rightarrow +\infty, \{\alpha_n\}, \{\beta_n\}$  converge uniformly to  $\rho(t), r(t)$  and  $\alpha_n \leq \rho(t) \leq r(t) \leq \beta_n \leq \beta_{n-1}, n = 0, 1, 2, \dots, t \in J$ .



According to  $\alpha_n, \beta_n$  satisfying (2.13), that is,

$$\begin{aligned}
 \alpha'_n(t) &= f(t, \alpha_{n-1}(t), [K\alpha_{n-1}](t)) - b(t)\alpha_{n-1}(t) - M(\alpha_n(t) - \alpha_{n-1}(t)), \quad t \neq t_k, t \in J, \\
 \Delta\alpha_n(t_k) &= I_k(\alpha_{n-1}(t_k)) - L_k(\alpha_n(t_k) - \alpha_{n-1}(t_k)), \quad k = 1, 2, \dots, m, \\
 \alpha_n(0) + \mu \int_0^T \alpha_{n-1}(s) ds &= \alpha_n(T), \quad \mu \leq 0, \\
 \beta'_n(t) &= f(t, \beta_{n-1}(t), [K\beta_{n-1}](t)) - b(t)\beta_{n-1}(t) - M(\beta_n(t) - \beta_{n-1}(t)), \quad t \neq t_k, t \in J, \\
 \Delta\beta_n(t_k) &= I_k(\beta_{n-1}(t_k)) - L_k(\beta_n(t_k) - \beta_{n-1}(t_k)), \quad k = 1, 2, \dots, m, \\
 \beta_n(0) + \mu \int_0^T \beta_{n-1}(s) ds &= \beta_n(T), \quad \mu \leq 0,
 \end{aligned} \tag{2.23}$$

when  $n \rightarrow +\infty$ , we have

$$\begin{aligned}
 \rho'(t) &= f(t, \rho(t), [K\rho](t)) - b(t)\rho(t), \quad t \neq t_k, t \in J, \\
 \Delta\rho(t_k) &= I_k(\rho(t_k)), \quad k = 1, 2, \dots, m, \\
 \rho(0) + \mu \int_0^T \rho(s) ds &= \rho(T), \quad \mu \leq 0. \\
 r'(t) &= f(t, r(t), [Kr](t)) - b(t)r(t), \quad t \neq t_k, t \in J, \\
 \Delta r(t_k) &= I_k(r(t_k)), \quad k = 1, 2, \dots, m, \\
 r(0) + \mu \int_0^T r(s) ds &= r(T), \quad \mu \leq 0.
 \end{aligned} \tag{2.24}$$

Equation (2.24) indicates that  $\rho(t), r(t)$  are solutions of (1.1).

Lastly, we prove that  $\rho(t), r(t)$  are minimal and maximal solutions of the equation (1.1) in  $[\alpha, \beta]$ .

Suppose that  $x(t)$  is a solution of the equation and satisfies  $x(t) \in [\alpha, \beta], t \in J$ , obviously, we can assume that there is an  $n$  such that  $\alpha_n \leq x \leq \beta_n$ .

If  $p(t) = \alpha_{n+1} - x$ , then

$$\begin{aligned}
 p' &= \alpha'_{n+1} - x' \leq -b(t)\alpha_n(t) + f(t, \alpha_n(t), [K\alpha_n](t)) \\
 &\quad - M(\alpha_{n+1}(t) - \alpha_n(t)) - f(t, x(t), [Kx(t)](t)) + b(t)x(t) \\
 &\leq -b(t)(\alpha_n - x) - Mp(t), t \neq t_k.
 \end{aligned} \tag{2.25}$$

And since  $b(t) \leq 0$ ,  $\alpha_m - x \leq 0$ ,  $p' \leq -Mp(t)$ ,

$$\begin{aligned} \Delta p(t_k) &= \Delta \alpha_{n+1} - \Delta x = I_k(\alpha_n(t_k)) - L_k(\alpha_{n+1}(t_k) - \alpha_n(t_k)) - I_k(x(t_k)) \leq -L_k p(t_k), \quad t = t_k, \\ p(0) &= \alpha_{n+1}(0) - x(0) = \mu \int_0^T (x(s) - \alpha_n(s)) ds + p(T) \leq p(T). \end{aligned} \quad (2.26)$$

Hence by Lemma 2.2, we can obtain  $p(t) \leq 0$ ,  $t \in J$ , so  $\alpha_{n+1}(t) \leq x(t)$ . Similarly, we can obtain:  $x(t) \leq \beta_{n+1}(t)$ ,  $t \in J$ . This indicates that  $\alpha_n(t) \leq x(t) \leq \beta_{n+1}(t)$ ,  $t \in J$ ,  $n = 0, 1, 2, \dots$ . Hence when  $n \rightarrow +\infty$ , we can obtain that  $\rho(t) \leq x(t) \leq r(t)$ ,  $t \in J$ . This ends the proof.  $\square$

Finally, we give an example to illustrate the efficiency of our results.

*Example 2.5.* Consider the problem of

$$\begin{aligned} x'(t) - x(t) \sin t &= -x(t) + t + \int_0^t x(s) ds, \quad 0 < t < 1, \quad t \neq t_1, \\ \Delta x(t_1) &= -\frac{1}{8}x(t_1), \quad t_1 = \frac{1}{2}, \\ x(0) - \int_0^1 x(s) ds &= x(1), \end{aligned} \quad (2.27)$$

where  $b(t) = \sin t$ ,  $f(t, x(t), Kx(t)) = -x(t) + t + \int_0^t x(s) ds$ ,  $I_1(x) = -x$ . Obviously,  $\alpha(t) = 0$ ,  $\beta(t) = 1 - t$  are the lower solution and upper solution for (2.27) with  $\alpha(t) \leq \beta(t)$ , respectively.  $f(t, x, Kx) - f(t, y, Ky) = -(x - y) - \int_0^t (x(s) - y(s)) ds$ ,  $I_1(x) - I_1(y) = -(x - y)$ . Let  $T = 1$ ,  $L_k = 1/8$ , the conditions of Theorem 2.4 are all satisfied, so problem (2.27) has the maximal and minimal solutions in the segment  $[\alpha(t), \beta(t)]$ .

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