

EXISTENCE AND ALGORITHM OF SOLUTIONS FOR GENERALIZED NONLINEAR VARIATIONAL-LIKE INEQUALITIES

ZEQING LIU, JUHE SUN, SOO HAK SHIM, AND SHIN MIN KANG

Received 28 December 2004 and in revised form 9 June 2005

We introduce and study a new class of generalized nonlinear variational-like inequalities. Under suitable conditions, we prove the existence of solutions for the class of generalized nonlinear variational-like inequalities. A new iterative algorithm for finding the approximate solutions of the generalized nonlinear variational-like inequality is given and the convergence of the algorithm is also proved. The results presented in this paper improve and generalize some results in recent literature.

1. Introduction

Variational-like inequalities are a useful and important generalization of variational inequalities [3, 8, 26]. They have potential and significant applications in optimization theory, structural analysis, and economics, see [3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29]. Some mixed variational-like inequalities have been studied by Parida and Sen [26], Tian [27], and Yao [29] by using the Berge maximum theorem in finite- and infinite-dimensional spaces. Huang and Deng [10] extended the auxiliary principle technique to study the existence of solutions for a class of generalized strongly nonlinear mixed variational-like inequalities. By using the minimax inequality technique, Ding [5, 6] studied some classes of nonlinear variational-like inequalities in reflexive Banach spaces.

The purpose of this paper is to introduce and study a new class of generalized nonlinear variational-like inequalities, which includes several kinds of variational-like inequalities as special cases. A few existence results of solutions for the generalized nonlinear variational-like inequality are established. We construct an iterative algorithm for finding the approximate solutions of the generalized nonlinear variational-like inequality and obtain the convergence of the algorithm under certain conditions.

2. Preliminaries

Let H be a real Hilbert space endowed with an inner product $\langle \cdot, \cdot \rangle$ and norm $\| \cdot \|$, respectively. Let K be a nonempty closed convex subset of H , let $A, C, F : K \rightarrow H$, $N : H \times H \rightarrow H$, and $\eta : K \times K \rightarrow H$ be mappings, and let $f : K \rightarrow (-\infty, \infty]$ be a real functional.

Suppose that $a : H \times H \rightarrow (-\infty, \infty)$ is a coercive continuous bilinear form, that is, there exist positive constants c and d such that

$$(C1) \quad a(v, v) \geq c\|v\|^2, \text{ for all } v \in H;$$

$$(C2) \quad a(u, v) \leq d\|u\|\|v\|, \text{ for all } u, v \in H.$$

Clearly, $c \leq d$.

We consider the following generalized nonlinear variational-like inequality problem.

Find $u \in K$ such that

$$a(u, v - u) + f(v) - f(u) \geq \langle N(Au, Cu) + Fu, \eta(v, u) \rangle, \quad \forall v \in K. \quad (2.1)$$

Special cases. (A) If $N(Au, Cu) = Au - Cu$, $a(u, v) = 0$ and $Fu = 0$ for all $u, v \in K$, then the generalized nonlinear variational-like inequality problem (2.1) is equivalent to finding $u \in K$ such that

$$\langle Cu - Au, \eta(v, u) \rangle \geq f(u) - f(v), \quad \forall v \in K, \quad (2.2)$$

which was introduced and studied by Ding [5].

(B) If $N(Au, Cu) = Au - Cu$, $a(u, v) = 0$ and $\eta(u, v) = gu - gv$ for all $u, v \in K$, then the generalized nonlinear variational-like inequality problem (2.1) is equivalent to finding $u \in K$ such that

$$\langle Cu - Au, gv - gu \rangle \geq f(u) - f(v), \quad \forall v \in K, \quad (2.3)$$

which was studied by Yao [29].

Definition 2.1. Let $A, C : K \rightarrow H$, $N : H \times H \rightarrow H$ and $\eta : K \times K \rightarrow H$ be mappings.

(1) A is said to be *Lipschitz continuous* with constant α if there exists a constant $\alpha > 0$ such that

$$\|Au - Av\| \leq \alpha\|u - v\|, \quad \forall u, v \in K. \quad (2.4)$$

(2) N is said to be *Lipschitz continuous* with constant β in the first argument if there exists a constant $\beta > 0$ such that

$$\|N(u, w) - N(v, w)\| \leq \beta\|u - v\|, \quad \forall u, v, w \in H. \quad (2.5)$$

(3) N is said to be η -*antimonotone* with respect to A in the first argument if

$$\langle N(Au, w) - N(Av, w), \eta(u, v) \rangle \leq 0, \quad \forall u, v \in K, w \in H. \quad (2.6)$$

(4) N is said to be η -*relaxed Lipschitz* with constant γ with respect to C in the second argument if there exists a constant $\gamma > 0$ such that

$$\langle N(w, Cu) - N(w, Cv), \eta(u, v) \rangle \leq -\gamma\|u - v\|^2, \quad \forall u, v \in K, w \in H. \quad (2.7)$$

(5) η is said to be *Lipschitz continuous* with constant δ if there exists a constant $\delta > 0$ such that

$$\|\eta(u, v)\| \leq \delta\|u - v\|, \quad \forall u, v \in K. \quad (2.8)$$

Similarly, we can define the Lipschitz continuity of N in the second argument.

Definition 2.2. Let K be a nonempty closed convex subset of a Hilbert space H and $f : K \rightarrow (-\infty, \infty]$ be a real functional.

(1) f is said to be *convex* if for any $u, v \in K$ and for any $\alpha \in [0, 1]$,

$$f(\alpha u + (1 - \alpha)v) \leq \alpha f(u) + (1 - \alpha)f(v). \tag{2.9}$$

(2) f is said to be *lower semicontinuous* on K if for each $\alpha \in (-\infty, \infty]$, the set $\{u \in K : f(u) \leq \alpha\}$ is closed in K .

LEMMA 2.3 [1, 2]. Let X be a nonempty closed convex subset of a Hausdorff linear topological space E , and let $\phi, \psi : K \times K \rightarrow R$ be mappings satisfying the following conditions:

- (a) $\psi(x, y) \leq \phi(x, y)$, for all $x, y \in X$, and $\psi(x, x) \geq 0$, for all $x \in X$;
- (b) for each $x \in X$, $\phi(x, y)$ is upper semicontinuous with respect to y ;
- (c) for each $y \in X$, the set $\{x \in X : \psi(x, y) < 0\}$ is a convex set;
- (d) there exists a nonempty compact set $K \subset X$ and $x_0 \in K$ such that $\psi(x_0, y) < 0$, for all $y \in X \setminus K$.

Then there exists $\hat{y} \in K$ such that $\phi(x, \hat{y}) \geq 0$, for all $x \in X$.

3. Existence theorems

In this section, we give four existence theorems of solutions for the generalized nonlinear variational-like inequality (2.1).

THEOREM 3.1. Let K be a nonempty closed convex subset of a Hilbert space H . Let $a : H \times H \rightarrow (-\infty, \infty)$ be a coercive continuous bilinear form with (C1) and (C2) and let $f : K \rightarrow (-\infty, \infty]$ be a proper convex lower semicontinuous functional with $\text{int}(\text{dom } f) \cap K \neq \emptyset$. Suppose that $A, C : K \rightarrow H$ and $N : H \times H \rightarrow H$ are continuous mappings, $\eta : K \times K \rightarrow H$ is Lipschitz continuous with constant δ , for each $v \in K$, $\eta(\cdot, v)$ is continuous and $\eta(v, u) = -\eta(u, v)$ for all $u, v \in K$. Assume that N is η -antimonotone with respect to A in the first argument and η -relaxed Lipschitz with constant ξ with respect to C in the second argument. Suppose that for given $x, y \in H$ and $v \in K$, the mapping $u \mapsto \langle N(x, y), \eta(u, v) \rangle$ is concave and upper semicontinuous. If $F : K \rightarrow H$ is completely continuous, then the generalized nonlinear variational-like inequality (2.1) has a solution $u \in K$.

Proof. We first prove that for each fixed $\hat{u} \in K$, there exists a unique $\hat{w} \in K$ such that

$$a(\hat{w}, v - \hat{w}) + f(v) - f(\hat{w}) \geq \langle N(A\hat{w}, C\hat{w}) + F\hat{u}, \eta(v, \hat{w}) \rangle, \quad \forall v \in K. \tag{3.1}$$

Let \hat{u} be in K . Define the functionals ϕ and $\psi : K \times K \rightarrow R$ by

$$\begin{aligned} \phi(v, w) &= a(v, v - w) + f(v) - f(w) - \langle N(Av, Cv) + F\hat{u}, \eta(v, w) \rangle, \\ \psi(v, w) &= a(w, v - w) + f(v) - f(w) - \langle N(Aw, Cw) + F\hat{u}, \eta(v, w) \rangle \end{aligned} \tag{3.2}$$

for all $v, w \in K$.

We check that the functionals ϕ and ψ satisfy all the conditions of Lemma 2.3 in the weak topology. It follows from the definitions of ϕ and ψ that for all $v, w \in K$,

$$\begin{aligned} \phi(v, w) - \psi(v, w) &= a(v - w, v - w) - \langle N(Av, Cv) - N(Aw, Cv), \eta(v, w) \rangle \\ &\quad - \langle N(Aw, Cv) - N(Aw, Cw), \eta(v, w) \rangle \\ &\geq (c + \xi) \|v - w\|^2 \geq 0, \end{aligned} \tag{3.3}$$

which means that ϕ and ψ satisfy the condition (a) of Lemma 2.3. Notice that f is a convex lower semicontinuous functional and for given $x, y \in H, v \in K$, the mapping $u \mapsto \langle N(x, y), \eta(u, v) \rangle$ is concave and upper semicontinuous. It follows that $\phi(v, w)$ is weakly upper semicontinuous with respect to w and the set $\{v \in K : \psi(v, w) < 0\}$ is convex for each $w \in K$. Therefore, the conditions (b) and (c) of Lemma 2.3 hold. Since f is proper convex lower semicontinuous, for each $v \in \text{int}(\text{dom } f)$, $\partial f(v) \neq \emptyset$, see Ekeland and Temam [9]. Let v^* be in $\text{int}(\text{dom } f) \cap K$. It follows that

$$f(u) \geq f(v^*) + \langle r, u - v^* \rangle, \quad \forall r \in \partial f(v^*), u \in K. \tag{3.4}$$

Put

$$\begin{aligned} D &= (c + \xi)^{-1} (\|r\| + \delta \|N(Av^*, Cv^*)\| + \delta \|F\hat{u}\|), \\ T &= \{w \in K : \|w - v^*\| \leq D\}. \end{aligned} \tag{3.5}$$

Obviously, T is a weakly compact subset of K and for any $w \in K \setminus T$,

$$\begin{aligned} \psi(v^*, w) &= a(w - v^*, v^* - w) + f(v^*) - f(w) - \langle N(Aw, Cw) + F\hat{u}, \eta(v^*, w) \rangle \\ &\leq -a(w - v^*, w - v^*) - \langle r, w - v^* \rangle \\ &\quad + \langle N(Aw, Cw) - N(Av^*, Cw), \eta(w, v^*) \rangle \\ &\quad + \langle N(Av^*, Cw) - N(Av^*, Cv^*), \eta(w, v^*) \rangle \\ &\quad + \langle N(Av^*, Cv^*), \eta(w, v^*) \rangle + \langle F\hat{u}, \eta(w, v^*) \rangle \\ &\leq -\|w - v^*\| [(c + \xi) \|w - v^*\| - \|r\| - \delta \|N(Av^*, Cv^*)\| - \delta \|F\hat{u}\|] < 0, \end{aligned} \tag{3.6}$$

which yields that the condition (d) of Lemma 2.3 holds. Thus Lemma 2.3 ensures that there exists a $\hat{w} \in K$ such that $\phi(v, \hat{w}) \geq 0$ for all $v \in K$, that is,

$$a(v, v - \hat{w}) + f(v) - f(\hat{w}) \geq \langle N(Av, Cv) + F\hat{u}, \eta(v, \hat{w}) \rangle, \quad \forall v \in K. \tag{3.7}$$

Let t be in $(0, 1]$ and v be in K . Replacing v by $v_t = tv + (1 - t)\hat{w}$ in (3.7), we see that

$$a(v_t, t(v - \hat{w})) + f(v_t) - f(\hat{w}) \geq \langle N(Av_t, Cv_t) + F\hat{u}, \eta(v_t, \hat{w}) \rangle, \quad \forall v \in K. \tag{3.8}$$

Note that a is bilinear and f is convex. From (3.8) we deduce that

$$t[a(v_t, v - \hat{w}) + f(v) - f(\hat{w})] \geq t \langle N(Av_t, Cv_t) + F\hat{u}, \eta(v, \hat{w}) \rangle, \quad \forall v \in K, \tag{3.9}$$

which implies that

$$a(v_t, v - \hat{w}) + f(v) - f(\hat{w}) \geq \langle N(Av_t, Cv_t) + F\hat{u}, \eta(v, \hat{w}) \rangle, \quad \forall v \in K. \tag{3.10}$$

Letting $t \rightarrow 0^+$ in the above inequality, we conclude that

$$a(\hat{w}, v - \hat{w}) + f(v) - f(\hat{w}) \geq \langle N(A\hat{w}, C\hat{w}) + F\hat{u}, \eta(v, \hat{w}) \rangle, \quad \forall v \in K. \tag{3.11}$$

That is, \hat{w} is a solution of (3.1). Now we prove the uniqueness. For any two solutions $w_1, w_2 \in K$ of (3.1), we know that

$$\begin{aligned} a(w_1, w_2 - w_1) + f(w_2) - f(w_1) &\geq \langle N(Aw_1, Cw_1) + F\hat{u}, \eta(w_2, w_1) \rangle, \\ a(w_2, w_1 - w_2) + f(w_1) - f(w_2) &\geq \langle N(Aw_2, Cw_2) + F\hat{u}, \eta(w_1, w_2) \rangle. \end{aligned} \tag{3.12}$$

Adding these inequalities, we deduce that

$$\begin{aligned} c\|w_1 - w_2\|^2 &\leq a(w_1 - w_2, w_1 - w_2) \\ &\leq \langle N(Aw_1, Cw_1) - N(Aw_2, Cw_1), \eta(w_1, w_2) \rangle \\ &\quad + \langle N(Aw_2, Cw_1) - N(Aw_2, Cw_2), \eta(w_1, w_2) \rangle \\ &\leq -\xi\|w_1 - w_2\|^2, \end{aligned} \tag{3.13}$$

which yields that $w_1 = w_2$. That is, \hat{w} is a unique solution of (3.1). This means that there exists a mapping $G : K \rightarrow K$ satisfying $G(\hat{u}) = \hat{w}$, where \hat{w} is the unique solution of (3.1) for each $\hat{u} \in K$.

Next we show that G is a completely continuous mapping. Let u_1 and u_2 be arbitrary elements in K . Using (3.1), we get that

$$\begin{aligned} a(Gu_1, Gu_2 - Gu_1) + f(Gu_2) - f(Gu_1) &\geq \langle N(A(Gu_1), C(Gu_1)) + Fu_1, \eta(Gu_2, Gu_1) \rangle, \\ a(Gu_2, Gu_1 - Gu_2) + f(Gu_1) - f(Gu_2) &\geq \langle N(A(Gu_2), C(Gu_2)) + Fu_2, \eta(Gu_1, Gu_2) \rangle. \end{aligned} \tag{3.14}$$

Adding (3.14), we arrive at

$$\begin{aligned} c\|Gu_1 - Gu_2\|^2 &\leq a(Gu_1 - Gu_2, Gu_1 - Gu_2) \\ &\leq \langle N(A(Gu_1), C(Gu_1)) - N(A(Gu_2), C(Gu_1)), \eta(Gu_1, Gu_2) \rangle \\ &\quad + \langle N(A(Gu_2), C(Gu_1)) - N(A(Gu_2), C(Gu_2)), \eta(Gu_1, Gu_2) \rangle \\ &\quad + \langle Fu_1 - Fu_2, \eta(Gu_1, Gu_2) \rangle \\ &\leq -\xi\|Gu_1 - Gu_2\|^2 + \delta\|Fu_1 - Fu_2\|\|Gu_1 - Gu_2\|, \end{aligned} \tag{3.15}$$

that is,

$$\|Gu_1 - Gu_2\| \leq \frac{\delta}{c + \xi} \|Fu_1 - Fu_2\|. \tag{3.16}$$

Since F is completely continuous, it follows from (3.16) that $G : K \rightarrow K$ is a completely continuous mapping. Hence the Schauder fixed point theorem guarantees that G has a fixed point $u \in K$, which means that u is a solution of the generalized nonlinear variational-like inequality (2.1). This completes the proof. \square

THEOREM 3.2. *Let a, f, C, N, F , and η be as in Theorem 3.1 and let N be Lipschitz continuous with constant ζ in the first argument. Suppose that $A : K \rightarrow H$ is Lipschitz continuous with constant ρ . If $c + \xi > \delta\zeta\rho$, then the generalized nonlinear variational-like inequality (2.1) has a solution $u \in K$.*

Proof. Put

$$D = (c + \xi - \delta\zeta\rho)^{-1} (\|r\| + \delta\|N(Av^*, Cv^*)\| + \delta\|F\hat{u}\|), \tag{3.17}$$

$$T = \{w \in K : \|w - v^*\| \leq D\}.$$

As in the proof of Theorem 3.1, we conclude that

$$\begin{aligned} \psi(v^*, w) &\leq -a(w - v^*, w - v^*) - \langle r, w - v^* \rangle \\ &\quad + \langle N(Aw, Cw) - N(Av^*, Cw), \eta(w, v^*) \rangle \\ &\quad + \langle N(Av^*, Cw) - N(Av^*, Cv^*), \eta(w, v^*) \rangle \\ &\quad + \langle N(Av^*, Cv^*), \eta(w, v^*) \rangle + \langle F\hat{u}, \eta(w, v^*) \rangle \\ &\leq -\|w - v^*\| [(c + \xi - \delta\zeta\rho)\|w - v^*\| \\ &\quad - \|r\| - \delta\|N(Av^*, Cv^*)\| - \delta\|F\hat{u}\|] < 0 \end{aligned} \tag{3.18}$$

for any $w \in K \setminus T$. The rest of the argument is now essentially the same as in the proof of Theorem 3.1 and therefore is omitted. \square

THEOREM 3.3. *Let a, f, A, C, N , and η be as in Theorem 3.1. Suppose that $F : K \rightarrow H$ is Lipschitz continuous with constant l . If $\delta l / (c + \xi) < 1$, then the generalized nonlinear variational-like inequality (2.1) has a unique solution $u \in K$.*

Proof. Let u_1 and u_2 be arbitrary elements in K . As in the proof of Theorem 3.1, we deduce that

$$\|Gu_1 - Gu_2\| \leq \frac{\delta}{c + \xi} \|Fu_1 - Fu_2\| \leq \frac{\delta l}{c + \xi} \|u_1 - u_2\|, \quad \forall u_1, u_2 \in K, \tag{3.19}$$

which yields that $G : K \rightarrow K$ is a contraction mapping and hence it has a unique fixed point $u \in K$, which is a unique solution of the generalized nonlinear variational-like inequality (2.1). This completes the proof. \square

The following theorem follows from the arguments of Theorems 3.1, 3.2 and, 3.3.

THEOREM 3.4. *Let a, f, A, C, N , and η be as in Theorem 3.2. Suppose that $F : K \rightarrow H$ is Lipschitz continuous with constant l . If $0 < \delta l / (c + \xi - \delta\zeta\rho) < 1$, then the generalized nonlinear variational-like inequality (2.1) has a unique solution $u \in K$.*

4. Algorithm and convergence theorems

Based on Theorem 3.1, we suggest the following iterative algorithm.

ALGORITHM 4.1. Let $A, C, F : K \rightarrow H$, $N : H \times H \rightarrow H$, and $\eta : K \times K \rightarrow H$ be mappings, and let $f : K \rightarrow (-\infty, \infty]$ be a real functional. For any given $u_0 \in K$, compute sequence $\{u_n\}_{n \geq 0}$ by the iterative scheme

$$a(u_{n+1}, v - u_{n+1}) + f(v) - f(u_{n+1}) \geq \langle N(Au_{n+1}, Cu_{n+1}) + Fu_n, \eta(v, u_{n+1}) \rangle, \tag{4.1}$$

for all $v \in K$ and $n \geq 0$.

THEOREM 4.2. Let a, f, F, N, A, C , and η be as in Theorem 3.3. If $\delta l / (c + \xi) < 1$, then the generalized nonlinear variational-like inequality (2.1) possesses a unique solution and the iterative sequence $\{u_n\}_{n \geq 0}$ generated by Algorithm 4.1 converges strongly to the unique solution.

Proof. Using Algorithm 4.1, we obtain that

$$\begin{aligned} a(u_{n+1}, u_n - u_{n+1}) + f(u_n) - f(u_{n+1}) &\geq \langle N(Au_{n+1}, Cu_{n+1}) + Fu_n, \eta(u_n, u_{n+1}) \rangle, \\ a(u_n, u_{n+1} - u_n) + f(u_{n+1}) - f(u_n) &\geq \langle N(Au_n, Cu_n) + Fu_{n-1}, \eta(u_{n+1}, u_n) \rangle, \end{aligned} \tag{4.2}$$

for all $n \geq 1$. Adding (4.2), we get that

$$\begin{aligned} c \|u_{n+1} - u_n\|^2 &\leq a(u_{n+1} - u_n, u_{n+1} - u_n) \\ &\leq \langle N(Au_{n+1}, Cu_{n+1}) - N(Au_n, Cu_{n+1}), \eta(u_{n+1}, u_n) \rangle \\ &\quad + \langle N(Au_n, Cu_{n+1}) - N(Au_n, Cu_n), \eta(u_{n+1}, u_n) \rangle \\ &\quad + \langle Fu_n - Fu_{n-1}, \eta(u_{n+1}, u_n) \rangle \\ &\leq -\xi \|u_{n+1} - u_n\|^2 + \delta l \|u_n - u_{n-1}\| \|u_{n+1} - u_n\|, \end{aligned} \tag{4.3}$$

that is,

$$\|u_{n+1} - u_n\| \leq \frac{\delta l}{c + \xi} \|u_n - u_{n-1}\|, \quad \forall n \geq 1, \tag{4.4}$$

which yields that $\{u_n\}_{n \geq 0}$ is a Cauchy sequence by $\delta l / (c + \xi) < 1$. Consequently, $\{u_n\}_{n \geq 0}$ converges to some element u in K . Letting $n \rightarrow \infty$ in (4.1), we infer that

$$a(u, v - u) + f(v) - f(u) \geq \langle N(Au, Cu) + Fu, \eta(v, u) \rangle, \quad \forall v \in K. \tag{4.5}$$

Hence u is a solution of the generalized nonlinear variational-like inequality (2.1). It follows from Theorem 3.3 that u is the unique solution of the generalized nonlinear variational-like inequality (2.1). This completes the proof. \square

Similarly we have the following result.

THEOREM 4.3. *Let $a, f, F, N, A, C,$ and η be as in Theorem 3.4. If $0 < \delta l / (c + \xi - \delta \zeta \rho) < 1,$ then the generalized nonlinear variational-like inequality (2.1) possesses a unique solution and the iterative sequence $\{u_n\}_{n \geq 0}$ generated by Algorithm 4.1 converges strongly to the unique solution.*

Acknowledgments

The authors thank the referees for their valuable suggestions for the improvement of the paper. This work was supported by the Science Research Foundation of Educational Department of Liaoning Province (2004C063) and Korea Research Foundation Grant (KRF-2003-005-C00013).

References

- [1] S. S. Chang, *Variational Inequality and Complementarity Theory with Applications*, Shanghai Scientific Technology and Literature Press, Shanghai, 1991.
- [2] ———, *On the existence of solutions for a class of quasi-bilinear variational inequalities*, J. Systems Sci. Math. Sci. **16** (1996), 136–140 (Chinese).
- [3] M. S. R. Chowdhury and K.-K. Tan, *Generalization of Ky Fan's minimax inequality with applications to generalized variational inequalities for pseudo-monotone operators and fixed point theorems*, J. Math. Anal. Appl. **204** (1996), no. 3, 910–929.
- [4] P. Cubiotti, *Existence of solutions for lower semicontinuous quasi-equilibrium problems*, Comput. Math. Appl. **30** (1995), no. 12, 11–22.
- [5] X. P. Ding, *Algorithm of solutions for mixed-nonlinear variational-like inequalities in reflexive Banach space*, Appl. Math. Mech. **19** (1998), no. 6, 489–496 (Chinese).
- [6] ———, *Existence and algorithm of solutions for nonlinear mixed variational-like inequalities in Banach spaces*, J. Comput. Appl. Math. **157** (2003), no. 2, 419–434.
- [7] X. P. Ding and K.-K. Tan, *A minimax inequality with applications to existence of equilibrium point and fixed point theorems*, Colloq. Math. **63** (1992), no. 2, 233–247.
- [8] X. P. Ding and E. Tarafdar, *Generalized variational-like inequalities with pseudomonotone set-valued mappings*, Arch. Math. (Basel) **74** (2000), no. 4, 302–313.
- [9] I. Ekeland and R. Temam, *Convex Analysis and Variational Problems*, North-Holland, Amsterdam, 1976.
- [10] N.-J. Huang and C.-X. Deng, *Auxiliary principle and iterative algorithms for generalized set-valued strongly nonlinear mixed variational-like inequalities*, J. Math. Anal. Appl. **256** (2001), no. 2, 345–359.
- [11] Z. Liu, L. Debnath, S. M. Kang, and J. S. Ume, *Completely generalized multivalued nonlinear quasi-variational inclusions*, Int. J. Math. Math. Sci. **30** (2002), no. 10, 593–604.
- [12] ———, *On the generalized nonlinear quasivariational inclusions*, Acta Math. Inform. Univ. Ostraviensis **11** (2003), no. 1, 81–90.
- [13] ———, *Sensitivity analysis for parametric completely generalized nonlinear implicit quasivariational inclusions*, J. Math. Anal. Appl. **277** (2003), no. 1, 142–154.
- [14] ———, *Generalized mixed quasivariational inclusions and generalized mixed resolvent equations for fuzzy mappings*, Appl. Math. Comput. **149** (2004), no. 3, 879–891.
- [15] Z. Liu and S. M. Kang, *Generalized multivalued nonlinear quasivariational inclusions*, Math. Nachr. **253** (2003), no. 1, 45–54.

- [16] ———, *Convergence and stability of perturbed three-step iterative algorithm for completely generalized nonlinear quasivariational inequalities*, Appl. Math. Comput. **149** (2004), no. 1, 245–258.
- [17] Z. Liu, S. M. Kang, and J. S. Ume, *On general variational inclusions with noncompact valued mappings*, Adv. Nonlinear Var. Inequal. **5** (2002), no. 2, 11–25.
- [18] ———, *Completely generalized multivalued strongly quasivariational inequalities*, Publ. Math. Debrecen **62** (2003), no. 1-2, 187–204.
- [19] ———, *Generalized variational inclusions for fuzzy mappings*, Adv. Nonlinear Var. Inequal. **6** (2003), no. 1, 31–40.
- [20] ———, *The solvability of a class of quasivariational inequalities*, Adv. Nonlinear Var. Inequal. **6** (2003), no. 2, 69–78.
- [21] Z. Liu, J. S. Ume, and S. M. Kang, *General strongly nonlinear quasivariational inequalities with relaxed Lipschitz and relaxed monotone mappings*, J. Optim. Theory Appl. **114** (2002), no. 3, 639–656.
- [22] ———, *Resolvent equations technique for general variational inclusions*, Proc. Japan Acad. Ser. A Math. Sci. **78** (2002), no. 10, 188–193.
- [23] ———, *Nonlinear variational inequalities on reflexive Banach spaces and topological vector spaces*, Int. J. Math. Math. Sci. **2003** (2003), no. 4, 199–207.
- [24] ———, *Completely generalized quasivariational inequalities*, Adv. Nonlinear Var. Inequal. **7** (2004), no. 1, 35–46.
- [25] P. D. Panagiotopoulos and G. E. Stavroulakis, *New types of variational principles based on the notion of quasidifferentiability*, Acta Mech. **94** (1992), no. 3-4, 171–194.
- [26] J. Parida and A. Sen, *A variational-like inequality for multifunctions with applications*, J. Math. Anal. Appl. **124** (1987), no. 1, 73–81.
- [27] G. Q. Tian, *Generalized quasi-variational-like inequality problem*, Math. Oper. Res. **18** (1993), no. 3, 752–764.
- [28] J. C. Yao, *The generalized quasi-variational inequality problem with applications*, J. Math. Anal. Appl. **158** (1991), no. 1, 139–160.
- [29] ———, *Existence of generalized variational inequalities*, Oper. Res. Lett. **15** (1994), no. 1, 35–40.

Zeqing Liu: Department of Mathematics, Liaoning Normal University, P.O. Box 200, Dalian, Liaoning 116029, China
E-mail address: zeqingliu@dl.cn

Juhe Sun: Department of Mathematics, Liaoning Normal University, P.O. Box 200, Dalian, Liaoning 116029, China
E-mail address: juhesun@163.com

Soo Hak Shim: Department of Mathematics and Research Institute of Natural Science, Gyeongsang National University, Chinju 660-701, Korea
E-mail address: math@nongae.gsnu.ac.kr

Shin Min Kang: Department of Mathematics and Research Institute of Natural Science, Gyeongsang National University, Chinju 660-701, Korea
E-mail address: smkang@nongae.gsnu.ac.kr

Special Issue on Modeling Experimental Nonlinear Dynamics and Chaotic Scenarios

Call for Papers

Thinking about nonlinearity in engineering areas, up to the 70s, was focused on intentionally built nonlinear parts in order to improve the operational characteristics of a device or system. Keying, saturation, hysteretic phenomena, and dead zones were added to existing devices increasing their behavior diversity and precision. In this context, an intrinsic nonlinearity was treated just as a linear approximation, around equilibrium points.

Inspired on the rediscovering of the richness of nonlinear and chaotic phenomena, engineers started using analytical tools from "Qualitative Theory of Differential Equations," allowing more precise analysis and synthesis, in order to produce new vital products and services. Bifurcation theory, dynamical systems and chaos started to be part of the mandatory set of tools for design engineers.

This proposed special edition of the *Mathematical Problems in Engineering* aims to provide a picture of the importance of the bifurcation theory, relating it with nonlinear and chaotic dynamics for natural and engineered systems. Ideas of how this dynamics can be captured through precisely tailored real and numerical experiments and understanding by the combination of specific tools that associate dynamical system theory and geometric tools in a very clever, sophisticated, and at the same time simple and unique analytical environment are the subject of this issue, allowing new methods to design high-precision devices and equipment.

Authors should follow the Mathematical Problems in Engineering manuscript format described at <http://www.hindawi.com/journals/mpe/>. Prospective authors should submit an electronic copy of their complete manuscript through the journal Manuscript Tracking System at <http://mts.hindawi.com/> according to the following timetable:

Manuscript Due	February 1, 2009
First Round of Reviews	May 1, 2009
Publication Date	August 1, 2009

Guest Editors

José Roberto Castilho Piqueira, Telecommunication and Control Engineering Department, Polytechnic School, The University of São Paulo, 05508-970 São Paulo, Brazil; piqueira@lac.usp.br

Elbert E. Neher Macau, Laboratório Associado de Matemática Aplicada e Computação (LAC), Instituto Nacional de Pesquisas Espaciais (INPE), São José dos Campos, 12227-010 São Paulo, Brazil ; elbert@lac.inpe.br

Celso Grebogi, Department of Physics, King's College, University of Aberdeen, Aberdeen AB24 3UE, UK; grebogi@abdn.ac.uk