

Research Article

Convergence Theorems for Maximal Monotone Operators, Weak Relatively Nonexpansive Mappings and Equilibrium Problems

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We introduce hybrid-iterative schemes for solving a system of the zero-finding problems of maximal monotone operators, the equilibrium problem, and the fixed point problem of weak relatively nonexpansive mappings. We then prove, in a uniformly smooth and uniformly convex Banach space, strong convergence theorems by using a shrinking projection method. We finally apply the obtained results to a system of convex minimization problems.

1. Introduction

Let E be a real Banach space and C a nonempty subset of E . Let E^* be the dual space of E . We denote the value of $x^* \in E^*$ at $x \in E$ by $\langle x^*, x \rangle$. Let $T : C \rightarrow C$ be a nonlinear mapping. We denote by $F(T)$ the fixed points set of T , that is, $F(T) = \{x \in C : x = Tx\}$. Let $A : E \rightarrow 2^{E^*}$ be a set-valued mapping. We denote $D(A)$ by the domain of A , that is, $D(A) = \{x \in E : Ax \neq \emptyset\}$ and also denote $G(A)$ by the graph of A , that is, $G(A) = \{(x, x^*) \in E \times E^* : x^* \in Ax\}$. A set-valued mapping A is said to be *monotone* if $\langle x^* - y^*, x - y \rangle \geq 0$ whenever $(x, x^*), (y, y^*) \in G(A)$. It is said to be *maximal monotone* if its graph is not contained in the graph of any other monotone operators on E . It is known that if A is maximal monotone, then the set $A^{-1}(0^*) = \{z \in E : 0^* \in Az\}$ is closed and convex.

The problem of finding a zero point of maximal monotone operators plays an important role in optimizations. This is because it can be reformulated to a convex minimization

problem and a variational inequality problem. Many authors have studied the convergence of such problems in various spaces (see, e.g., [1–16]). Initiated by Martinet [17], in a real Hilbert space H , Rockafellar [18] introduced the following iterative scheme: $x_1 \in H$ and

$$x_{n+1} = J_{\lambda_n} x_n, \quad \forall n \geq 1, \quad (1.1)$$

where $\{\lambda_n\} \subset (0, \infty)$, J_λ is the resolvent of A defined by $J_\lambda := J_{\lambda A} = (I + \lambda A)^{-1}$ for all $\lambda > 0$, and A is a maximal monotone operator on H . Such an algorithm is called the *proximal point algorithm*. It was proved that the sequence $\{x_n\}$ generated by (1.1) converges weakly to an element in $A^{-1}(0)$ provided that $\liminf_{n \rightarrow \infty} \lambda_n > 0$. Recently, Kamimura and Takahashi [19] introduced the following iteration in a real Hilbert space: $x_1 \in H$ and

$$x_{n+1} = \alpha_n x_n + (1 - \alpha_n) J_{\lambda_n} x_n, \quad \forall n \geq 1, \quad (1.2)$$

where $\{\alpha_n\} \subset [0, 1]$ and $\{\lambda_n\} \subset (0, \infty)$. The weak convergence theorems are also established in a real Hilbert space under suitable conditions imposed on $\{\alpha_n\}$ and $\{\lambda_n\}$.

In 2004, Kamimura et al. [20] extended the above iteration process to a much more general setting. In fact, they proposed the following algorithm: $x_1 \in E$ and

$$x_{n+1} = J^{-1}(\alpha_n J(x_n) + (1 - \alpha_n) J(J_{\lambda_n} x_n)), \quad \forall n \geq 1, \quad (1.3)$$

where $\{\alpha_n\} \subset [0, 1]$, $\{\lambda_n\} \subset (0, \infty)$, and $J_\lambda := J_{\lambda A} = (J + \lambda A)^{-1} J$ for all $\lambda > 0$. They proved, in a uniformly smooth and uniformly convex Banach space, a weak convergence theorem.

Let $F : C \times C \rightarrow \mathbb{R}$, where \mathbb{R} is the set of real numbers, be a bifunction. The equilibrium problem is to find $x \in C$ such that

$$F(x, y) \geq 0, \quad \forall y \in C. \quad (1.4)$$

The solutions set of (1.4) is denoted by $EP(F)$.

For solving the equilibrium problem, we assume that

- (A1) $F(x, x) = 0$ for all $x \in C$,
- (A2) F is monotone, that is $F(x, y) + F(y, x) \leq 0$ for all $x, y \in C$,
- (A3) for all $x, y, z \in C$, $\limsup_{t \downarrow 0} F(tz + (1 - t)x, y) \leq F(x, y)$,
- (A4) for all $x \in C$, $F(x, \cdot)$ is convex and lower semi-continuous.

Recently, Takahashi and Zembayashi [21] introduced the following iterative scheme for a relatively nonexpansive mapping $T : C \rightarrow C$ in a uniformly smooth and uniformly convex Banach space: $x_1 \in C$ and

$$C_1 = C,$$

$$y_n = J^{-1}(\alpha_n J x_n + (1 - \alpha_n) J T x_n),$$

$$\begin{aligned}
&u_n \in C \text{ such that } F(u_n, y) + \frac{1}{r_n} \langle y - u_n, Ju_n - Jy_n \rangle \geq 0 \quad \forall y \in C, \\
&C_{n+1} = \{z \in C_n : \phi(z, u_n) \leq \phi(z, x_n)\}, \\
&x_{n+1} = \Pi_{C_{n+1}}(x_1), \quad \forall n \geq 1,
\end{aligned} \tag{1.5}$$

where $\{\alpha_n\} \subset [0, 1]$ and $\{r_n\} \subset (0, \infty)$. Such an algorithm is called the *shrinking projection method* which was introduced by Takahashi et al. [22]. They proved that the sequence $\{x_n\}$ converges strongly to an element in $F(T) \cap EP(F)$ under appropriate conditions. The equilibrium problem has been intensively studied by many authors (see, e.g., [23–31]).

Motivated by the previous results, we introduce a hybrid-iterative scheme for finding a zero point of maximal monotone operators $A_i : E \rightarrow 2^{E^*}$ ($i = 1, 2, \dots, N$) which is also a common element in the solutions set of an equilibrium problem for F and in the fixed points set of weak relatively nonexpansive mappings $T_i : C \rightarrow C$ ($i = 1, 2, \dots$). Using the projection technique, we also prove that the sequence generated by a constructed algorithm converges strongly to an element in $[\bigcap_{i=1}^N A_i^{-1}(0^*)] \cap [\bigcap_{i=1}^\infty F(T_i)] \cap EP(F)$ in a uniformly smooth and uniformly convex Banach space. Finally, we apply our results to a system of convex minimization problems.

2. Preliminaries and Lemmas

In this section, we give some useful preliminaries and lemmas which will be used in the sequel.

Let E be a real Banach space and let $U = \{x \in E : \|x\| = 1\}$ be the unit sphere of E . A Banach space E is said to be *strictly convex* if for any $x, y \in U$,

$$x \neq y \text{ implies } \|x + y\| < 2. \tag{2.1}$$

A Banach space E is said to be *uniformly convex* if, for each $\varepsilon \in (0, 2]$, there exists $\delta > 0$ such that for any $x, y \in U$,

$$\|x - y\| \geq \varepsilon \text{ implies } \|x + y\| < 2(1 - \delta). \tag{2.2}$$

It is known that a uniformly convex Banach space is reflexive and strictly convex. The function $\delta : [0, 2] \rightarrow [0, 1]$ which is called the *modulus of convexity* of E is defined as follows:

$$\delta(\varepsilon) = \inf \left\{ 1 - \left\| \frac{x + y}{2} \right\| : x, y \in E, \|x\| = \|y\| = 1, \|x - y\| \geq \varepsilon \right\}. \tag{2.3}$$

Then E is uniformly convex if and only if $\delta(\varepsilon) > 0$ for all $\varepsilon \in (0, 2]$. A Banach space E is said to be *smooth* if the limit

$$\lim_{t \rightarrow 0} \frac{\|x + ty\| - \|x\|}{t} \tag{2.4}$$

exists for all $x, y \in U$. It is also said to be *uniformly smooth* if the limit (2.4) is attained uniformly for $x, y \in U$. The duality mapping $J : E \rightarrow 2^{E^*}$ is defined by

$$J(x) = \{x^* \in E^* : \langle x, x^* \rangle = \|x\|^2 = \|x^*\|^2\} \quad (2.5)$$

for all $x \in E$. It is also known that if E is uniformly smooth, then J is uniformly norm-to-norm continuous on bounded subsets of E (see [32] for more details).

Let E be a smooth Banach space. The function $\phi : E \times E \rightarrow \mathbb{R}$ is defined by

$$\phi(x, y) = \|x\|^2 - 2\langle x, Jy \rangle + \|y\|^2 \quad (2.6)$$

for all $x, y \in E$. From the definition of ϕ , we see that

$$\begin{aligned} (\|x\| - \|y\|)^2 &\leq \phi(x, y) \leq (\|x\| + \|y\|)^2, \\ \phi(x, y) &= \phi(x, z) + \phi(z, y) + 2\langle x - z, Jz - Jy \rangle \end{aligned} \quad (2.7)$$

for all $x, y, z \in E$.

Let C be a closed and convex subset of E , and let T be a mapping from C into itself. A point p in C is said to be an *asymptotic fixed point* of T [33] if C contains a sequence $\{x_n\}$ which converges weakly to p such that $\lim_{n \rightarrow \infty} \|x_n - Tx_n\| = 0$. The set of asymptotic fixed points of T will be denoted by $\widehat{F}(T)$. A mapping T is said to be *relatively nonexpansive* [33, 34] if $\widehat{F}(T) = F(T)$ and $\phi(p, Tx) \leq \phi(p, x)$ for all $p \in F(T)$ and $x \in C$. A point p in C is said to be a *strong asymptotic fixed point* of T if C contains a sequence $\{x_n\}$ which converges strongly to p such that $\lim_{n \rightarrow \infty} \|x_n - Tx_n\| = 0$. The set of strong asymptotic fixed points of T will be denoted by $\widetilde{F}(T)$. A mapping T is said to be *weak relatively nonexpansive* [35] if $\widetilde{F}(T) = F(T)$ and $\phi(p, Tx) \leq \phi(p, x)$ for all $p \in F(T)$ and $x \in C$. It is obvious by definition that the class of weak relatively nonexpansive mappings contains the class of relatively nonexpansive mappings. Indeed, for any mapping $T : C \rightarrow C$, we see that $F(T) \subset \widetilde{F}(T) \subset \widehat{F}(T)$. Therefore, if T is a relatively nonexpansive mapping, then $F(T) = \widetilde{F}(T) = \widehat{F}(T)$.

Nontrivial examples of weak relatively nonexpansive mappings which are not relatively nonexpansive can be found in [36].

Let E be a reflexive, strictly convex and smooth Banach space, and let C be a nonempty, closed, and convex subset of E . The *generalized projection mapping*, introduced by Alber [37], is a mapping $\Pi_C : E \rightarrow C$, that assigns to an arbitrary point $x \in E$ the minimum point of the function $\phi(y, x)$, that is, $\Pi_C(x) = \bar{x}$, where \bar{x} is the solution to the minimization problem

$$\phi(\bar{x}, x) = \min\{\phi(y, x) : y \in C\}. \quad (2.8)$$

In a Hilbert space, Π_C is coincident with the metric projection denoted by P_C .

Lemma 2.1 (see [38]). *Let E be a uniformly convex and smooth Banach space and let $\{x_n\}, \{y_n\}$ be two sequences in E . If $\lim_{n \rightarrow \infty} \phi(x_n, y_n) = 0$ and either $\{x_n\}$ or $\{y_n\}$ is bounded, then $\lim_{n \rightarrow \infty} \|x_n - y_n\| = 0$.*

Lemma 2.2 (see [37, 38]). *Let C be a nonempty, closed, and convex subset of a smooth, strictly convex and reflexive Banach space E , let $x \in E$ and let $z \in C$. Then $z = \Pi_C(x)$ if and only if $\langle y - z, Jx - Jz \rangle \leq 0$ for all $y \in C$.*

Lemma 2.3 (see [37, 38]). *Let C be a nonempty, closed, and convex subset of a smooth, strictly convex, and reflexive Banach space E . Then*

$$\phi(x, \Pi_C y) + \phi(\Pi_C y, y) \leq \phi(x, y) \quad \forall x \in C, y \in E. \quad (2.9)$$

Lemma 2.4 (see [39]). *Let E be a smooth and strictly convex Banach space, and let C be a nonempty, closed, and convex subset of E . Let T be a mapping from C into itself such that $F(T)$ is nonempty and $\phi(u, Tx) \leq \phi(u, x)$ for all $(u, x) \in F(T) \times C$. Then $F(T)$ is closed and convex.*

Let E be a reflexive, strictly convex, and smooth Banach space. It is known that $A : E \rightarrow 2^{E^*}$ is maximal monotone if and only if $R(J + \lambda A) = E^*$ for all $\lambda > 0$, where $R(B)$ stands for the range of B .

Define the *resolvent* of A by $J_{\lambda A} = (J + \lambda A)^{-1}J$ for all $\lambda > 0$. It is known that $J_{\lambda A}$ is a single-valued mapping from E to $D(A)$ and $A^{-1}(0^*) = F(J_{\lambda A})$ for all $\lambda > 0$. For each $\lambda > 0$, the *Yosida approximation* of A is defined by

$$A_\lambda(x) = \frac{1}{\lambda}(J(x) - JJ_{\lambda A}(x)) \quad (2.10)$$

for all $x \in E$. We know that $A_\lambda(x) \in A(J_{\lambda A}(x))$ for all $\lambda > 0$ and $x \in E$.

Lemma 2.5 (see [5]). *Let E be a smooth, strictly convex, and reflexive Banach space, let $A \subset E \times E^*$ be a maximal monotone operator with $A^{-1}(0^*) \neq \emptyset$, and let $J_{\lambda A} = (J + \lambda A)^{-1}J$ for each $\lambda > 0$. Then*

$$\phi(p, J_{\lambda A}(x)) + \phi(J_{\lambda A}(x), x) \leq \phi(p, x) \quad (2.11)$$

for all $\lambda > 0$, $p \in A^{-1}(0^*)$, and $x \in E$.

Lemma 2.6 (see [40]). *Let C be a closed and convex subset of a smooth, strictly convex, and reflexive Banach space E , let F be a bifunction from $C \times C$ to \mathbb{R} satisfying (A1)–(A4), and let $r > 0$ and $x \in E$. Then, there exists $z \in C$ such that*

$$F(z, y) + \frac{1}{r}\langle y - z, Jz - Jx \rangle \geq 0, \quad \forall y \in C. \quad (2.12)$$

Lemma 2.7 (see [41]). *Let C be a closed and convex subset of a uniformly smooth, strictly convex, and reflexive Banach space E , and let F be a bifunction from $C \times C$ to \mathbb{R} satisfying (A1)–(A4). For all $r > 0$ and $x \in E$, define the mapping $T_r : E \rightarrow C$ as follows:*

$$T_r(x) = \left\{ z \in C : F(z, y) + \frac{1}{r}\langle y - z, Jz - Jx \rangle \geq 0, \forall y \in C \right\}. \quad (2.13)$$

Then, the following holds:

- (1) T_r is single-valued;
- (2) T_r is a firmly nonexpansive-type mapping [42], that is, for all $x, y \in E$,

$$\langle T_r x - T_r y, J T_r x - J T_r y \rangle \leq \langle T_r x - T_r y, J x - J y \rangle; \quad (2.14)$$

- (3) $F(T_r) = EP(F)$;
- (4) $EP(F)$ is closed and convex.

Lemma 2.8 (see [41]). Let C be a closed and convex subset of a smooth, strictly, and reflexive Banach space E , let F be a bifunction from $C \times C$ to \mathbb{R} satisfying (A1)–(A4), let $r > 0$. Then

$$\phi(p, T_r x) + \phi(T_r x, x) \leq \phi(p, x), \quad (2.15)$$

for all $x \in E$ and $p \in F(T_r)$.

3. Strong Convergence Theorems

In this section, we are now ready to prove our main theorem.

Theorem 3.1. Let E be a uniformly smooth and uniformly convex Banach space, and let C be a nonempty, closed and convex subset of E . Let $A_i : E \rightarrow 2^{E^*}$ ($i = 1, 2, \dots, N$) be maximal monotone operators, let $F : C \times C \rightarrow \mathbb{R}$ be a bifunction, and let $T_i : C \rightarrow C$ ($i = 1, 2, \dots$) be weak relatively nonexpansive mappings such that $\mathcal{F} := [\bigcap_{i=1}^N A_i^{-1}(0^*)] \cap [\bigcap_{i=1}^{\infty} F(T_i)] \cap EP(F) \neq \emptyset$. Let $\{e_n\}_{n=1}^{\infty} \subset E$ be the sequence such that $\lim_{n \rightarrow \infty} e_n = 0$. Define the sequence $\{x_n\}_{n=1}^{\infty}$ in C as follows:

$$\begin{aligned} x_1 &\in C_1 = C, \\ y_n &= J_{\lambda_n^N A_N} \circ J_{\lambda_n^{N-1} A_{N-1}} \circ \cdots \circ J_{\lambda_n^1 A_1}(x_n + e_n), \\ u_n &= T_{r_n} y_n, \\ C_{n+1} &= \left\{ z \in C_n : \sup_{i \geq 1} \phi(z, T_i u_n) \leq \phi(z, x_n + e_n) \right\}, \\ x_{n+1} &= \Pi_{C_{n+1}}(x_1), \quad \forall n \geq 1. \end{aligned} \quad (3.1)$$

If $\liminf_{n \rightarrow \infty} \lambda_n^i > 0$ for each $i = 1, 2, \dots, N$ and $\liminf_{n \rightarrow \infty} r_n > 0$, then the sequence $\{x_n\}$ converges strongly to $q = \Pi_{\mathcal{F}}(x_1)$.

Proof. We split the proof into several steps as follows.

Step 1. $\mathcal{F} \subset C_n$ for all $n \geq 1$.

From Lemma 2.4, we know that $\bigcap_{i=1}^{\infty} F(T_i)$ is closed and convex. From Lemma 2.7(4), we also know that $EP(F)$ is closed and convex. On the other hand, since A_i ($i = 1, 2, \dots, N$) are maximal monotone, $A_i^{-1}(0^*)$ are closed and convex for each $i = 1, 2, \dots, N$; consequently, $\bigcap_{i=1}^N A_i^{-1}(0^*)$ is closed and convex. Hence \mathcal{F} is a nonempty, closed, and convex subset of C .

We next show that C_n is closed and convex for all $n \geq 1$. Obviously, $C_1 = C$ is closed and convex. Now suppose that C_k is closed and convex for some $k \in \mathbb{N}$. Then, for each $z \in C_k$ and $i \geq 1$, we see that $\phi(z, T_i u_k) \leq \phi(z, x_k)$ is equivalent to

$$2\langle z, Jx_k \rangle - 2\langle z, JT_i u_k \rangle \leq \|x_k\|^2 - \|T_i u_k\|^2. \quad (3.2)$$

By the construction of the set C_{k+1} , we see that

$$\begin{aligned} C_{k+1} &= \left\{ z \in C_k : \sup_{i \geq 1} \phi(z, T_i u_k) \leq \phi(z, x_k) \right\} \\ &= \bigcap_{i=1}^{\infty} \{ z \in C_k : \phi(z, T_i u_k) \leq \phi(z, x_k) \}. \end{aligned} \quad (3.3)$$

Hence, C_{k+1} is closed and convex. This shows, by induction, that C_n is closed and convex for all $n \geq 1$. It is obvious that $\mathcal{F} \subset C_1 = C$. Now, suppose that $\mathcal{F} \subset C_k$ for some $k \in \mathbb{N}$. For any $p \in \mathcal{F}$, by Lemmas 2.5 and 2.8, we have

$$\begin{aligned} \phi(p, T_i u_k) &\leq \phi(p, u_k) = \phi(p, T_{r_k} y_k) \\ &\leq \phi(p, y_k) \\ &= \phi\left(p, J_{\lambda_k^N A_N} \circ J_{\lambda_k^{N-1} A_{N-1}} \circ \cdots \circ J_{\lambda_k^1 A_1}(x_k + e_k)\right) \\ &\leq \phi\left(p, J_{\lambda_k^{N-1} A_{N-1}} \circ J_{\lambda_k^{N-2} A_{N-2}} \circ \cdots \circ J_{\lambda_k^1 A_1}(x_k + e_k)\right) \\ &\quad \vdots \\ &\leq \phi\left(p, J_{\lambda_k^2 A_2} \circ J_{\lambda_k^1 A_1}(x_k + e_k)\right) \\ &\leq \phi\left(p, J_{\lambda_k^1 A_1}(x_k + e_k)\right) \\ &\leq \phi(p, x_k + e_k). \end{aligned} \quad (3.4)$$

This shows that $\mathcal{F} \subset C_{k+1}$. By induction, we can conclude that $\mathcal{F} \subset C_n$ for all $n \geq 1$.

Step 2. $\lim_{n \rightarrow \infty} \phi(x_n, x_1)$ exists.

From $x_n = \Pi_{C_n}(x_1)$ and $x_{n+1} = \Pi_{C_{n+1}}(x_1) \in C_{n+1} \subset C_n$, we have

$$\phi(x_n, x_1) \leq \phi(x_{n+1}, x_1), \quad \forall n \geq 1. \quad (3.5)$$

From Lemma 2.3, for any $p \in \mathcal{F} \subset C_n$, we have

$$\phi(x_n, x_1) = \phi(\Pi_{C_n}(x_1), x_1) \leq \phi(p, x_1) - \phi(p, x_n) \leq \phi(p, x_1). \quad (3.6)$$

Combining (3.5) and (3.6), we conclude that $\lim_{n \rightarrow \infty} \phi(x_n, x_1)$ exists.

Step 3. $\lim_{n \rightarrow \infty} \|J(T_i y_n) - J(x_n + e_n)\| = 0$.

Since $x_m = \Pi_{C_m}(x_1) \in C_m \subset C_n$ for $m > n \geq 1$, by Lemma 2.3, it follows that

$$\begin{aligned} \phi(x_m, x_n) &= \phi(x_m, \Pi_{C_n}(x_1)) \leq \phi(x_m, x_1) - \phi(\Pi_{C_n}(x_1), x_1) \\ &= \phi(x_m, x_1) - \phi(x_n, x_1). \end{aligned} \quad (3.7)$$

Letting $m, n \rightarrow \infty$, we have $\phi(x_m, x_n) \rightarrow 0$. By Lemma 2.1, it follows that $\|x_m - x_n\| \rightarrow 0$ as $m, n \rightarrow \infty$. Therefore, $\{x_n\}$ is a Cauchy sequence. By the completeness of the space E and the closedness of C , we can assume that $x_n \rightarrow q \in C$ as $n \rightarrow \infty$. In particular, we obtain that

$$\lim_{n \rightarrow \infty} \|x_{n+1} - x_n\| = 0. \quad (3.8)$$

Since $e_n \rightarrow 0$, we have

$$\lim_{n \rightarrow \infty} \|x_{n+1} - (x_n + e_n)\| = 0. \quad (3.9)$$

Since $x_{n+1} = \Pi_{C_{n+1}}(x_1) \in C_{n+1}$, for each $i \geq 1$,

$$\begin{aligned} \phi(x_{n+1}, T_i u_n) &\leq \phi(x_{n+1}, x_n + e_n) \\ &= \langle x_{n+1}, J(x_{n+1}) - J(x_n + e_n) \rangle + \langle x_{n+1} - (x_n + e_n), J(x_{n+1}) \rangle. \end{aligned} \quad (3.10)$$

Since E is uniformly smooth, J is uniformly norm-to-norm continuous on bounded sets. It follows from (3.9) and by the boundedness of $\{x_n\}$ that

$$\lim_{n \rightarrow \infty} \phi(x_{n+1}, T_i u_n) = 0 \quad (3.11)$$

for all $i = 1, 2, \dots$. So from Lemma 2.1, we have

$$\begin{aligned} \lim_{n \rightarrow \infty} \|x_{n+1} - T_i u_n\| &= 0, \\ \lim_{n \rightarrow \infty} \|T_i u_n - x_n\| &= 0, \end{aligned} \quad (3.12)$$

and, since $e_n \rightarrow 0$, therefore

$$\lim_{n \rightarrow \infty} \|T_i u_n - (x_n + e_n)\| = 0, \quad (3.13)$$

for all $i = 1, 2, \dots$. Since J is uniformly norm-to-norm continuous on bounded subsets of E ,

$$\lim_{n \rightarrow \infty} \|J(T_i u_n) - J(x_n + e_n)\| = 0 \quad (3.14)$$

for all $i = 1, 2, \dots$

Step 4. $\lim_{n \rightarrow \infty} \|T_i u_n - u_n\| = 0$ for all $i = 1, 2, \dots$.

Denote that $\Theta_n^i = J_{\lambda_n A_i} \circ J_{\lambda_n^{i-1} A_{i-1}} \circ \dots \circ J_{\lambda_n A_1}$ for each $i \in \{1, 2, \dots, N\}$ and $\Theta_n^0 = I$ for each $n \geq 1$. We note that $y_n = \Theta_n^N(x_n + e_n)$ for each $n \geq 1$.

To this end, we will show that

$$\lim_{n \rightarrow \infty} \left\| J\left(\Theta_n^i(x_n + e_n)\right) - J\left(\Theta_n^{i-1}(x_n + e_n)\right) \right\| = 0 \quad (3.15)$$

for all $i = 1, 2, \dots, N$.

For any $p \in \mathcal{F}$, by (3.4), we see that

$$\begin{aligned} \phi\left(p, \Theta_n^{N-1}(x_n + e_n)\right) &\leq \phi\left(p, \Theta_n^{N-2}(x_n + e_n)\right) \\ &\leq \phi\left(p, \Theta_n^{N-3}(x_n + e_n)\right) \\ &\vdots \\ &\leq \phi\left(p, (x_n + e_n)\right). \end{aligned} \quad (3.16)$$

Since $p \in \mathcal{F}$, by Lemma 2.5 and (3.16), it follows that

$$\begin{aligned} \phi\left(y_n, \Theta_n^{N-1}(x_n + e_n)\right) &\leq \phi\left(p, \Theta_n^{N-1}(x_n + e_n)\right) - \phi\left(p, y_n\right) \\ &\leq \phi\left(p, (x_n + e_n)\right) - \phi\left(p, y_n\right) \\ &\leq \phi\left(p, (x_n + e_n)\right) - \phi\left(p, u_n\right) \\ &\leq \phi\left(p, (x_n + e_n)\right) - \phi\left(p, T_i u_n\right) \\ &= \|x_n + e_n\|^2 - \|T_i u_n\|^2 - 2\langle p, J(x_n + e_n) - J(T_i u_n) \rangle. \end{aligned} \quad (3.17)$$

From (3.13) and (3.14), we get that $\lim_{n \rightarrow \infty} \phi\left(y_n, \Theta_n^{N-1}(x_n + e_n)\right) = 0$. So we obtain that

$$\lim_{n \rightarrow \infty} \left\| y_n - \Theta_n^{N-1}(x_n + e_n) \right\| = 0. \quad (3.18)$$

Again, since $p \in \mathcal{F}$,

$$\begin{aligned} \phi\left(\Theta_n^{N-1}(x_n + e_n), \Theta_n^{N-2}(x_n + e_n)\right) &\leq \phi\left(p, \Theta_n^{N-2}(x_n + e_n)\right) - \phi\left(p, \Theta_n^{N-1}(x_n + e_n)\right) \\ &\leq \phi\left(p, (x_n + e_n)\right) - \phi\left(p, \Theta_n^{N-1}(x_n + e_n)\right) \\ &\leq \phi\left(p, (x_n + e_n)\right) - \phi\left(p, T_i u_n\right). \end{aligned} \quad (3.19)$$

From (3.13) and (3.14), we get that

$$\lim_{n \rightarrow \infty} \phi\left(\Theta_n^{N-1}(x_n + e_n), \Theta_n^{N-2}(x_n + e_n)\right) = 0. \quad (3.20)$$

It also follows that

$$\lim_{n \rightarrow \infty} \left\| \Theta_n^{N-1}(x_n + e_n) - \Theta_n^{N-2}(x_n + e_n) \right\| = 0. \quad (3.21)$$

Continuing in this process, we can show that

$$\lim_{n \rightarrow \infty} \left\| \Theta_n^{N-2}(x_n + e_n) - \Theta_n^{N-3}(x_n + e_n) \right\| = \dots = \lim_{n \rightarrow \infty} \left\| \Theta_n^1(x_n + e_n) - (x_n + e_n) \right\| = 0. \quad (3.22)$$

So, we now conclude that

$$\lim_{n \rightarrow \infty} \left\| \Theta_n^i(x_n + e_n) - \Theta_n^{i-1}(x_n + e_n) \right\| = 0 \quad (3.23)$$

for each $i = 1, 2, \dots, N$. By the uniform norm-to-norm continuity of J , we also have

$$\lim_{n \rightarrow \infty} \left\| J\left(\Theta_n^i(x_n + e_n)\right) - J\left(\Theta_n^{i-1}(x_n + e_n)\right) \right\| = 0 \quad (3.24)$$

for each $i = 1, 2, \dots, N$. Using (3.23), it is easily seen that

$$\lim_{n \rightarrow \infty} \left\| y_n - (x_n + e_n) \right\| = 0. \quad (3.25)$$

From $u_n = T_{r_n}y_n$, by Lemma 2.8, it follows that

$$\begin{aligned} \phi(u_n, y_n) &= \phi(T_{r_n}y_n, y_n) \\ &\leq \phi(p, y_n) - \phi(p, T_{r_n}y_n) \\ &\leq \phi(p, x_n + e_n) - \phi(p, u_n) \\ &\leq \phi(p, x_n + e_n) - \phi(p, T_i u_n). \end{aligned} \quad (3.26)$$

This implies that $\lim_{n \rightarrow \infty} \phi(u_n, y_n) = 0$ and hence

$$\lim_{n \rightarrow \infty} \left\| u_n - y_n \right\| = 0. \quad (3.27)$$

Combining (3.13), (3.25), and (3.27), we obtain that

$$\lim_{n \rightarrow \infty} \left\| T_i u_n - u_n \right\| = 0 \quad (3.28)$$

for all $i \geq 1$.

Step 5. $q \in \bigcap_{i=1}^{\infty} F(T_i)$.

Since $x_n \rightarrow q$ and $e_n \rightarrow 0$, $x_n + e_n \rightarrow q$. So from (3.25) and (3.27), we have $u_n \rightarrow q$. Note that T_i ($i = 1, 2, \dots$) are weak relatively nonexpansive. Using (3.28), we can conclude that $q \in \tilde{F}(T_i) = F(T_i)$ for all $i \geq 1$. Hence $q \in \bigcap_{i=1}^{\infty} F(T_i)$.

Step 6. $q \in \bigcap_{i=1}^N A_i^{-1}(0^*)$.

Noting that $\Theta_n^i(x_n + e_n) = J_{\lambda_n^i A_i} \Theta_n^{i-1}(x_n + e_n)$ for each $i = 1, 2, \dots, N$, we obtain that

$$\|A_{\lambda_n^i} \Theta_n^{i-1}(x_n + e_n)\| = \frac{1}{\lambda_n^i} \|J(\Theta_n^{i-1}(x_n + e_n)) - J(\Theta_n^i(x_n + e_n))\|. \quad (3.29)$$

From (3.24) and $\liminf_{n \rightarrow \infty} \lambda_n^i > 0$, we have

$$\lim_{n \rightarrow \infty} \|A_{\lambda_n^i} \Theta_n^{i-1}(x_n + e_n)\| = 0. \quad (3.30)$$

We note that $(\Theta_n^i(x_n + e_n), A_{\lambda_n^i} \Theta_n^{i-1}(x_n + e_n)) \in G(A_i)$ for each $i = 1, 2, \dots, N$. If $(w, w^*) \in G(A_i)$ for each $i = 1, 2, \dots, N$, then it follows from the monotonicity of A_i that

$$\langle w^* - A_{\lambda_n^i} \Theta_n^{i-1}(x_n + e_n), w - \Theta_n^i(x_n + e_n) \rangle \geq 0. \quad (3.31)$$

We see that $\Theta_n^i(x_n + e_n) \rightarrow q$ for each $i = 1, 2, \dots, N$. Thus, from (3.30) and (3.31), we have

$$\langle w^*, w - q \rangle \geq 0. \quad (3.32)$$

By the maximality of A_i , it follows that $q \in A_i^{-1}(0^*)$ for each $i = 1, 2, \dots, N$. Therefore, $q \in \bigcap_{i=1}^N A_i^{-1}(0^*)$.

Step 7. $q \in \text{EP}(F)$.

From $u_n = T_{r_n} y_n$, we have

$$F(u_n, y) + \frac{1}{r_n} \langle y - u_n, Ju_n - Jy_n \rangle \geq 0, \quad \forall y \in C. \quad (3.33)$$

By (A2), we have

$$\begin{aligned} \|y - u_n\| \frac{\|Ju_n - Jy_n\|}{r_n} &\geq \frac{1}{r_n} \langle y - u_n, Ju_n - Jy_n \rangle \\ &\geq -F(u_n, y) \geq F(y, u_n), \quad \forall y \in C. \end{aligned} \quad (3.34)$$

Note that $\|Ju_n - Jy_n\|/r_n \rightarrow 0$ since $\liminf_{n \rightarrow \infty} r_n > 0$. From (A4) and $u_n \rightarrow q$, we get $F(y, q) \leq 0$ for all $y \in C$. For $0 < t < 1$ and $y \in C$, define that $y_t = ty + (1-t)q$. Then $y_t \in C$, which implies that $F(y_t, q) \leq 0$. From (A1), we obtain that $0 = F(y_t, y_t) \leq tF(y_t, y) + (1-t)F(y_t, q) \leq tF(y_t, y)$. Thus, $F(y_t, y) \geq 0$. From (A3), we have $F(q, y) \geq 0$ for all $y \in C$. Hence, $q \in \text{EP}(F)$. From Steps 5, 6, and 7, we now can conclude that $q \in \mathcal{F}$.

Step 8. $q = \Pi_{\mathcal{F}}(x_1)$.

From $x_n = \Pi_{C_n}(x_1)$, we have

$$\langle J(x_1) - J(x_n), x_n - z \rangle \geq 0, \quad \forall z \in C_n. \quad (3.35)$$

Since $\mathcal{F} \subset C_n$, we also have

$$\langle J(x_1) - J(x_n), x_n - z \rangle \geq 0, \quad \forall z \in \mathcal{F}. \quad (3.36)$$

Letting $n \rightarrow \infty$ in (3.36), we obtain that

$$\langle J(x_1) - J(q), q - z \rangle \geq 0, \quad \forall z \in \mathcal{F}. \quad (3.37)$$

This shows that $q = \Pi_{\mathcal{F}}(x_1)$ by Lemma 2.2. We thus complete the proof. \square

As a direct consequence of Theorem 3.1, we can also apply to a system of convex minimization problems.

Theorem 3.2. *Let E be a uniformly smooth and uniformly convex Banach space, and let C be a nonempty, closed, and convex subset of E . Let $f_i : E \rightarrow (-\infty, \infty]$ ($i = 1, 2, \dots, N$) be proper lower semicontinuous convex functions, let $F : C \times C \rightarrow \mathbb{R}$ be a bifunction, and let $T_i : C \rightarrow C$ ($i = 1, 2, \dots$) be weak relatively nonexpansive mappings such that $\mathcal{F} := [\bigcap_{i=1}^N (\partial f_i^{-1})(0^*)] \cap [\bigcap_{i=1}^{\infty} F(T_i)] \cap EP(F) \neq \emptyset$. Let $\{e_n\}_{n=1}^{\infty} \subset E$ be the sequence such that $\lim_{n \rightarrow \infty} e_n = 0$. Define the sequence $\{x_n\}_{n=1}^{\infty}$ in C as follows:*

$$\begin{aligned} x_1 &\in C_1 = C, \\ z_n^1 &= \arg \min_{y \in E} \left\{ f_1(y) + \frac{1}{2\lambda_n^1} \|y\|^2 + \frac{1}{\lambda_n^1} \langle y, J(x_n + e_n) \rangle \right\}, \\ &\vdots \\ z_n^{N-1} &= \arg \min_{y \in E} \left\{ f_{N-1}(y) + \frac{1}{2\lambda_n^{N-1}} \|y\|^2 + \frac{1}{\lambda_n^{N-1}} \langle y, J(z_n^{N-2}) \rangle \right\}, \\ y_n &= \arg \min_{y \in E} \left\{ f_N(y) + \frac{1}{2\lambda_n^N} \|y\|^2 + \frac{1}{\lambda_n^N} \langle y, J(z_n^{N-1}) \rangle \right\}, \\ u_n &= T_{r_n} y_n, \\ C_{n+1} &= \left\{ z \in C_n : \sup_{i \geq 1} \phi(z, T_i u_n) \leq \phi(z, x_n + e_n) \right\}, \\ x_{n+1} &= \Pi_{C_{n+1}}(x_1), \quad \forall n \geq 1. \end{aligned} \quad (3.38)$$

If $\liminf_{n \rightarrow \infty} \lambda_n^i > 0$ for each $i = 1, 2, \dots, N$ and $\liminf_{n \rightarrow \infty} r_n > 0$, then the sequence $\{x_n\}$ converges strongly to $q = \Pi_{\mathcal{F}}(x_1)$.

Proof. By Rockafellar's theorem [43, 44], ∂f_i are maximal monotone operators for each $i = 1, 2, \dots, N$. Let $\lambda^i > 0$ for each $i = 1, 2, \dots, N$. Then, $z^i = J_{\lambda^i \partial f_i}(x)$ if and only if

$$\begin{aligned} 0 &\in \partial f_i(z^i) + \frac{1}{\lambda^i} (J(z^i) - J(x)) \\ &= \partial \left(f_i + \frac{1}{\lambda^i} \left(\frac{\|\cdot\|^2}{2} - J(x) \right) \right) (z^i), \end{aligned} \quad (3.39)$$

which is equivalent to

$$z^i = \arg \min_{y \in E} \left\{ f_i(y) + \frac{1}{\lambda^i} \left(\frac{\|y\|^2}{2} - \langle y, J(x) \rangle \right) \right\}. \quad (3.40)$$

Using Theorem 3.1, we thus complete the proof. \square

If $E = H$ is a real Hilbert space, we then obtain the following results.

Corollary 3.3. *Let C be a nonempty, closed and convex subset of a real Hilbert space H . Let $A_i : H \rightarrow 2^H$ ($i = 1, 2, \dots, N$) be maximal monotone operators, let $F : C \times C \rightarrow \mathbb{R}$ be a bifunction, and let $T_i : C \rightarrow C$ ($i = 1, 2, \dots$) be weak relatively nonexpansive mappings such that $\mathcal{F} := [\bigcap_{i=1}^N A_i^{-1}(0)] \cap [\bigcap_{i=1}^{\infty} F(T_i)] \cap EP(F) \neq \emptyset$. Let $\{e_n\}_{n=1}^{\infty} \subset H$ be the sequence such that $\lim_{n \rightarrow \infty} e_n = 0$. Define the sequence $\{x_n\}_{n=1}^{\infty}$ in C as follows:*

$$\begin{aligned} x_1 &\in C_1 = C, \\ y_n &= J_{\lambda_n^N A_N} \circ J_{\lambda_n^{N-1} A_{N-1}} \circ \cdots \circ J_{\lambda_n^1 A_1} (x_n + e_n), \\ u_n &= T_{r_n} y_n, \\ C_{n+1} &= \left\{ z \in C_n : \sup_{i \geq 1} \|z - T_i u_n\| \leq \|z - (x_n + e_n)\| \right\}, \\ x_{n+1} &= P_{C_{n+1}}(x_1), \quad \forall n \geq 1. \end{aligned} \quad (3.41)$$

If $\liminf_{n \rightarrow \infty} \lambda_n^i > 0$ for each $i = 1, 2, \dots, N$ and $\liminf_{n \rightarrow \infty} r_n > 0$, then the sequence $\{x_n\}$ converges strongly to $q = P_{\mathcal{F}}(x_1)$.

Corollary 3.4. *Let C be a nonempty, closed, and convex subset of a real Hilbert space H . Let $f_i : H \rightarrow (-\infty, \infty]$ ($i = 1, 2, \dots, N$) be proper lower semi-continuous convex functions, let $F : C \times C \rightarrow \mathbb{R}$ be a bifunction, and let $T_i : C \rightarrow C$ ($i = 1, 2, \dots$) be weak relatively nonexpansive mappings such*

that $\mathcal{F} := [\bigcap_{i=1}^N (\partial f_i^{-1})(0)] \cap [\bigcap_{i=1}^{\infty} F(T_i)] \cap EP(F) \neq \emptyset$. Let $\{e_n\}_{n=1}^{\infty} \subset H$ be the sequence such that $\lim_{n \rightarrow \infty} e_n = 0$. Define the sequence $\{x_n\}_{n=1}^{\infty}$ in C as follows:

$$\begin{aligned} x_1 &\in C_1 = C, \\ z_n^1 &= \arg \min_{y \in H} \left\{ f_1(y) + \frac{1}{2\lambda_n^1} \|y\|^2 + \frac{1}{\lambda_n^1} \langle y, x_n + e_n \rangle \right\}, \\ &\vdots \\ z_n^{N-1} &= \arg \min_{y \in H} \left\{ f_{N-1}(y) + \frac{1}{2\lambda_n^{N-1}} \|y\|^2 + \frac{1}{\lambda_n^{N-1}} \langle y, z_n^{N-2} \rangle \right\}, \\ y_n &= \arg \min_{y \in H} \left\{ f_N(y) + \frac{1}{2\lambda_n^N} \|y\|^2 + \frac{1}{\lambda_n^N} \langle y, z_n^{N-1} \rangle \right\}, \\ u_n &= T_{r_n} y_n, \\ C_{n+1} &= \left\{ z \in C_n : \sup_{i \geq 1} \|z - T_i u_n\| \leq \|z - (x_n + e_n)\| \right\}, \\ x_{n+1} &= P_{C_{n+1}}(x_1), \quad \forall n \geq 1. \end{aligned} \tag{3.42}$$

If $\liminf_{n \rightarrow \infty} \lambda_n^i > 0$ for each $i = 1, 2, \dots, N$ and $\liminf_{n \rightarrow \infty} r_n > 0$, then the sequence $\{x_n\}$ converges strongly to $q = P_{\mathcal{F}}(x_1)$.

Remark 3.5. Using the shrinking projection method, we can construct a hybrid-proximal point algorithm for solving a system of the zero-finding problems, the equilibrium problems, and the fixed point problems of weak relatively nonexpansive mappings.

Remark 3.6. Since every relatively nonexpansive mapping is weak relatively nonexpansive, our results also hold if $T_i : C \rightarrow C$ ($i = 1, 2, \dots$) are relatively nonexpansive mappings.

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