

## ON FIXED POINT THEOREMS OF MAIA TYPE

*Bogdan Rzepecki*

**1.** In this note we present some variants of the following result of Maia [10]:  
*Let  $X$  be a non-empty set endowed in with two metrics  $\rho, \sigma$ , and let  $f$  be a mapping of  $X$  into itself. Suppose that  $\rho(x, y) \leq \sigma(x, y)$  in  $X$ ,  $X$  is a complete space and  $f$  is continuous with respect to  $\rho$ , and  $\sigma(fx, fy) \leq k \cdot \sigma(x, y)$  for all  $x, y$  in  $X$ , where  $0 \leq k < 1$ . Then,  $f$  has a unique fixed point in  $X$ .*

This theorem (cf. also [18], [11], [4], [12], [17]) generalizes the Banach fixed-point principle and is connected with Bielecki's method [1] of changing the norm in the theory of differential equations. Our results follow as a consequence of two metrics, of two transformations [3] and of the generalized metric space concept ([8], [9]).

**2.** Let  $(E, \|\cdot\|)$  be a Banach space, let  $S$  be a normal cone in  $E$  (see e.g. [6]) and let  $\preceq$  denote the partial order in  $E$  generated by the cone  $S$ . Suppose that  $X$  is a non-empty set and a function  $d_E: X \times X \rightarrow S$  satisfying for arbitrary elements  $x, y, z$  in  $X$  the following conditions:

(A 1)  $d_E(x, y) = \theta$  if and only if  $x = y$  ( $\theta$  denotes the zero of the space  $E$ );

(A 2)  $d_E(x, y) = d_E(y, x)$ ;

(A 3)  $d_E(x, y) \preceq d_E(x, z) + d_E(z, y)$

Then, this function  $d_E$  is called the *generalized metric* in  $X$ .

Further, let us put  $d^+(x, y) = \|d_E(x, y)\|$  for  $x$  and  $y$  in  $X$ . If every  $d^+$ -Cauchy sequence in  $X$  is  $d^+$ -convergent (i.e.,  $\lim_{p, q \rightarrow \infty} d^+(x_p, x_q) = 0$  for a sequence  $(x_n)$  in  $X$ , implies the existence of an element  $x_0$  in  $X$  such that  $\lim_{n \rightarrow \infty} d^+(x_n, x_0) = 0$ ), then  $(X, d_E)$  is called [6] a *generalized complete metric space*.

Moreover, in this paper we shall use the notations of  $\mathcal{L}^*$ -space, the  $\mathcal{L}^*$ -product of  $\mathcal{L}^*$ -spaces and a continuous mapping of  $\mathcal{L}^*$ -space into  $\mathcal{L}^*$ -space (see e.g. [7]).

**3.** Let  $E, S$  and  $\preceq$  be as above. In this section suppose we are given:

$L$  – a bounded positive linear operator of  $E$  into itself with the spectral radius  $r(L)$  less than one (see e.g. [6]);

$X, A$  – two non-empty sets;

$\rho_E, \sigma_E$  – two generalized metrics in  $X$  such that  $\rho_E(x, y) \preceq C \cdot \sigma_E(x, y)$  for all  $x, y$  in  $X$ , where  $C$  is a positive constant;

$T$  – a transformation from  $A$  to  $X$  such that  $(T[A], \rho_E)$  is a generalized complete metric space<sup>1</sup>.

Modifying the reasoning from [6, Th. II. 6. 2], we obtain the following result:

**PROPOSITION 1.** *Let  $(X, \rho_E)$  be a generalized complete metric space, let  $f: X \rightarrow X$  be a continuous mapping with respect to  $\rho^+$ , and let  $\sigma_E(fx, fy) \preceq L(\sigma_E(x, y))$  for all  $x, y$  in  $X$ . Then  $f$  has a unique fixed point  $\xi$  in  $X$ . Moreover, if  $x_0 \in X$  and  $x_n = fx_{n-1}$  for  $n \geq 1$ , then:*

(i)  $\lim_{n \rightarrow \infty} \|\rho_E(x_n, \xi)\| = 0,$

(ii)  $\|\rho_E(x_m, \xi)\| \leq N \cdot C \cdot \|L^m u\|$  for all  $m \geq 0$ , where  $N$  is same constant and  $u$  is a solution of equation  $u = \sigma_E(x_0, fx_0) + Lu$  in the space  $E$  (see [6, Th. I. 2. 2]).

Now, we shall prove

**PROPOSITION 2.** *Let  $(X, \rho_E)$  be a generalized complete metric space, let  $f_m: X \rightarrow X$  ( $m = 0, 1, \dots$ ) be continuous mappings with respect to  $\rho^+$ , and let  $\sigma_E(f_m x, f_m y) \preceq L(\sigma_E(x, y))$  for all  $x, y$  in  $X$ . Denote by  $\xi_m$  ( $m = 0, 1, \dots$ ) a unique fixed point of  $f_m$ , and suppose that  $\lim_{n \rightarrow \infty} \|\sigma_E(f_n x, f_0 x)\| = 0$  for every  $x$  in  $X$ . Then  $\lim_{n \rightarrow \infty} \|\rho_E(\xi_n, \xi_0)\| = 0$ .*

**PROOF.** Consider the linear equation  $u = \sigma_E(\xi_0, f_n \xi_0) + Lu$  ( $n = 1, 2, \dots$ ) with the unique solution  $u_n$  in  $E$  (see [6, Th. I. 2. 2]). By Proposition 1 we obtain  $\|\rho_E(\xi_n, \xi_0)\| \leq N \cdot C \cdot \|u_n\|$  for  $n \geq 1$ , where  $N$  is constant.

Let  $\varepsilon > 0$  be such that  $r(L) + \varepsilon < 1$ . Further, let us denote by  $\|\cdot\|_\varepsilon$  the norm equivalent to  $\|\cdot\|$  such that  $\|L\|_\varepsilon \leq \varepsilon + r(L)$  (see [6, p. 15]) ( $\|L\|_\varepsilon$  is the norm of  $L$  generated by  $\|\cdot\|_\varepsilon$ ). We have

$$\|u_n\|_\varepsilon \leq \|\sigma_E(f_n \xi_0, f_0 \xi_0)\|_\varepsilon + \|Lu_n\|_\varepsilon \leq \|\sigma_E(f_n \xi_0, f_0 \xi_0)\|_\varepsilon + (r(L) + \varepsilon)\|u_n\|_\varepsilon$$

for  $n \geq 1$ . Since  $\lim_{n \rightarrow \infty} \|\sigma_E(f_n \xi_0, f_0 \xi_0)\|_\varepsilon = 0$ , so  $\lim_{n \rightarrow \infty} \|u_n\|_\varepsilon \leq (\varepsilon + r(L)) \cdot \lim_{n \rightarrow \infty} \|u_n\|_\varepsilon$ , and consequently  $\lim_{n \rightarrow \infty} \|\rho_E(\xi_n, \xi_0)\| = 0$ .

**THEOREM 1.** *Let  $H: A \rightarrow X$  be a mapping such that  $H[A] \subset T[A]$  and  $\sigma_E(Hx, Hy) \preceq L(\sigma_E(Tx, Ty))$  for all  $x, y$  in  $A$ . Suppose that  $\lim_{n \rightarrow \infty} \|\rho_E(Hx_n, Hx)\| = 0$  for every sequence  $(x_n)$  in  $A$  with  $\lim_{n \rightarrow \infty} \|\rho_E(Tx_n, Tx)\| = 0$ . Then:*

(i) *for every  $u$  in  $T[A]$  the set  $H[T_{-1}u]$  contains only one element<sup>2</sup>;*

(ii) *there exists a unique element  $\xi$  in  $T[A]$  such that  $H[T_{-1}\xi] = \xi$ , and every sequence of successive approximations  $u_{n+1} = H[T_{-1}u_n]$  ( $n = 1, 2, \dots$ ) is  $\rho^+$ -convergent to  $\xi$ ;*

<sup>1</sup> $T[A]$  denotes the image of the set  $A$  by the transformation  $T$

<sup>2</sup> $T_{-1}u$  denotes the inverse image of  $u$  under  $T$

- (iii)  $Hx = Tx$  for all  $x$  in  $T_{-1}\xi$ ;
- (iv) if  $Hx_i = Tx_i$  ( $i = 1, 2$ ), then  $Tx_1 = Tx_2$ .

PROOF. Let us put  $fz = H[T_{-1}z]$  for  $z$  in  $T[A]$ . Obviously,  $fz \in T[A]$  for all  $z$  in  $T[A]$ . If  $v_i \in fz$  ( $i = 1, 2$ ), then  $v_i = Hx_i$  with  $Tx_i = z$ . Hence  $\theta \preceq \sigma_E(v_1, v_2) \preceq L(\sigma_E(Tx_1, Tx_2)) = \theta$  and  $v_1 = v_2$ . Therefore,  $H[T_{-1}z]$  contains only one element.

It can be easily seen that the mapping  $f$  of  $T[A]$  into itself is continuous with respect to  $\rho^+$ . Indeed, let  $z_n \in T[A]$  for  $n \geq 1$  and let  $\lim_{n \rightarrow \infty} \|\rho_E(z_n, z_0)\| = 0$ . Then there exist  $x_m \in T_{-1}z_m$  ( $m = 0, 1, \dots$ ) such that  $fz_m = Hx_m$ . We have  $\|\rho_E(Hx_n, Hx_0)\| = \|\rho_E(fz_n, fz_0)\|$  for  $n \geq 1$ , and consequently  $\lim_{n \rightarrow \infty} \|\rho_E(fz_n, fz_0)\| = \lim_{n \rightarrow \infty} \|\rho_E(Hx_n, Hx_0)\| = 0$ .

Further, it is easy to verify that  $\sigma_E(fu, fv) \preceq L(\sigma_E(u, v))$  for all  $u, v$  in  $T[A]$ . Consequently, applying Proposition 1 the proof of (ii) is completed.

Obviously, (iii) holds and we omit the proof. Now, we prove (iv): Suppose that  $Hx_i = Tx_i$  ( $i = 1, 2$ ) and  $Tx_1 \neq Tx_2$ . Then,  $\sigma_E(Tx_1, Tx_2) \preceq L(\sigma_E(Tx_1, Tx_2))$  and  $-\sigma_E(Tx_1, Tx_2) \notin S$ . Therefore, by theorem II. 5. 4 from [6. p. 81], we obtain  $r(L) \geq 1$ . This contradiction completes our proof.

Using Theorem 1 and Proposition 2 we obtain the following

**THEOREM 2.** *Let  $H_m: A \rightarrow X$  ( $m = 0, 1, \dots$ ) be mappings with  $H_m[A] \subset T[A]$  and  $\sigma_E(H_mx, H_my) \preceq L(\sigma_E(Tx, Ty))$  for all  $x, y$  in  $A$ . Further, suppose that  $\lim_{n \rightarrow \infty} \|\rho_E(H_mx_n, H_mx)\| = 0$  for every sequence  $(x_n)$  in  $A$  with  $\lim_{n \rightarrow \infty} \|\rho_E(Tx_n, Tx)\| = 0$ .*

*Let  $\xi_m$  ( $m = 0, 1, \dots$ ) be an element in  $T[A]$  such that  $H_m[T_{-1}\xi_m] = \xi_m$ . Assume that  $\lim_{n \rightarrow \infty} \|\sigma_E(H_nx, H_0x)\| = 0$  for every  $x$  in  $A$ . Then  $\lim_{n \rightarrow \infty} \|\rho_E(Ty_n, Ty_0)\| = 0$ , where  $y_m \in T_{-1}\xi_m$  for  $m \geq 0$ .*

**4.** M. Krasnoselskii [5] has given the following version of well-known result of Schauder: *If  $W$  is a non-empty bounded closed convex subset of a Banach space,  $f$  is a contraction and  $g$  is completely continuous on  $W$  with  $fx + gy \in W$  for all  $x, y$  in  $W$ , then the equation  $fx + gx = x$  has a solution in  $W$ .*

Now, we give a modification and some generalization of this Krasnoselskii's result.

Let  $(E, \|\cdot\|)$  be a Banach space, let  $S$  be a cone in  $E$  with the partial order  $\preceq$  such that if  $\theta \preceq x \preceq y$  then  $\|x\| \leq \|y\|$ , and let  $L$  be as in Sec. 3. Further, let  $X$  be a vector space endowed with two generalized norms  $\|\cdot\|_i: X \rightarrow S$  ( $i = 1, 2$ ) (see [6, p. 94]) such that  $\|x\|_1 \preceq C \cdot \|x\|_2$  for all  $x$  in  $X$ . Denote:  $\rho_E, \sigma_E$ -generalized metrics in  $X$  generated by  $\|\cdot\|_1$  and  $\|\cdot\|_2$ , respectively.

**THEOREM 3.** *Let  $K$  be a non-empty convex subset of  $X$ , let  $(K, \rho^+)$  be a complete space and let  $Q, F$  be transformations with the values in  $K$  defined on  $K$  and  $K \times K$  respectively. Assume, moreover, that the following condition holds:*

- (i)  $Q: (K, \rho^+) \rightarrow (K, \rho^+)$  is continuous,  $Q[K]$  is a conditionally compact set with respect to  $\sigma^+$  and  $\|F(u, y) - F(v, y)\|_2 \preceq \|Qu - Qv\|_2$  for all  $u, v, y$  in  $K$ ;

(ii)  $\|F(x, y) - F(x, z)\|_2 \leq L(\|y - z\|_2)$  for all  $x, y, z$  in  $K$ ;

(iii) for every  $x$  in  $K$  the function  $y \mapsto F(x, y)$  of  $K$  into itself is continuous with respect to  $\rho^+$ .

Then there exists a point  $x$  in  $K$  such that  $F(x, x) = x$ .

PROOF. Consider the mapping  $y \mapsto F(x, y)$  ( $x$  is fix in  $K$ ) of  $K$  into itself. By Proposition 1, there exists exactly one  $u_x$  in  $K$  such that  $F(x, u_x) = u_x$ . Now define an operator  $V$  as  $x \mapsto u_x$ .

This operator  $V$  maps continuously  $(K, \rho^+)$  into itself. Indeed, let  $(x_n)$  be a sequence in  $K$  such that  $\rho^+(x_n, x_0) \rightarrow 0$  as  $n \rightarrow \infty$ . Let us put  $f_m x = F(x_m, x)$  ( $m = 0, 1, \dots$ ) for  $x$  in  $K$ . The conditions (i) and (ii) imply that all the assumptions of the Proposition 2 are satisfied. Therefore,  $f_m$  has a unique fixed point  $\xi_m$  and  $\rho^+(\xi_n, \xi_0) \rightarrow 0$  as  $n \rightarrow \infty$ , so we are done.

Now we are going to show that  $V[K]$  is conditionally compact with respect to  $\rho^+$ : Let  $(x_n)$  be a sequence in  $K$ , and let  $y_n = F(x_n, u_{x_n})$  for  $n \geq 1$ . Let  $\varepsilon > 0$  be such that  $r(L) + \varepsilon < 1$ , let  $\|\cdot\|_\varepsilon$  be the norm equivalent to  $\|\cdot\|$  with  $\|L\|_\varepsilon \leq r(L) + \varepsilon$ , and let us put  $\sigma_\varepsilon^+(x, y) = \|\|x - y\|_2\|_\varepsilon$  for  $x, y$  in  $K$ . We have

$$\begin{aligned} \|\|y_i - y_j\|_2\|_\varepsilon &\leq \|L(\|y_i - y_j\|_2) + \|Qx_i - Qx_j\|_2\|_\varepsilon \\ &\leq (r(L) + \varepsilon)\|\|y_i - y_j\|_2\|_\varepsilon + \|\|Qx_i - Qx_j\|_2\|_\varepsilon. \end{aligned}$$

hence

$$(1 - (r(L) + \varepsilon)) \cdot \|\|y_i - y_j\|_2\|_\varepsilon \leq \|\|Qx_i - Qx_j\|_2\|_\varepsilon$$

for every  $i, j \leq 1$ . Suppose that  $(Qx_n)$  is a  $\sigma^+$ -Cauchy sequence. Then,  $(Qx_n)$  is a  $\sigma_\varepsilon^+$ -Cauchy sequence and consequently  $(y_n)$  is  $\rho^+$ -convergent in  $K$ .

By application of the Schauder fixed point theorem, our proof is completed.

REMARK. The above theorem will remain true if (i) is replaced by the following condition:  $Q$  is continuous and  $Q[K]$  is a conditionally compact set with respect to  $\rho^+$ , and  $\|F(u, y) - F(v, y)\|_2 \leq \|Qu - Qv\|_1$  for all  $u, v, y$  in  $K$ .

**5.** Let us remark applications and further results can be obtained if the concept of a generalized metric space in the Luxemburg sense [9] (not every two points have necessarily a finite distance) will be used. Cf. [13]–[17]. How, we give some application of Theorem 2 (in the cose of) to functional equations.

In this section, let  $(\mathbf{R}^k, \|\cdot\|)$  denote the  $k$ -dimensional Euclidean space, let  $E = \mathbf{R}^k$ , and let  $S = \{(t_1, t_2, \dots, t_k) \in \mathbf{R}^k: t_i \geq 0 \text{ for } 1 \leq i \leq k\}$ . Then,  $(x_1, x_2, \dots, x_k) \preceq (y_1, y_2, \dots, y_k)$  if we have  $x_i \leq y_i$  for every  $1 \leq i \leq k$ .

Suppose that  $J = [0, \infty)$ ,  $K_{ij} \geq 0$  ( $i, j = 1, 2, \dots, k$ ) are constants, and  $p: J \rightarrow J$  is a locally bounded function. Let us denote by:

$A$  – the set of continuous functions  $(x_1, x_2, \dots, x_k)$  from  $J$  to  $\mathbf{R}^k$  such that  $x_i(t) = 0(\exp(p(t)))$  ( $1 \leq i \leq k$ ) for every  $t$  in  $J$ ;

$X$  – the set of bounded continuous functions from  $J$  to  $\mathbf{R}^k$ ;

$\Lambda$  – the metric space with the metric  $\delta$ ;

$\mathcal{F}$  – the set of continuous functions  $(f_1, f_2, \dots, f_k)$  from  $J \times \mathbf{R}^k \times \Lambda$  into  $\mathbf{R}^k$  satisfying the following conditions:

$$|f_i(t, t_1, \dots, t_k, \lambda) - f_i(t, s_1, s_2, \dots, s_k, \lambda)| \leq \sum_{j=1}^k K_{ij} |t_j - s_j|$$

( $1 \leq i \leq k$ ) for every  $t$  in  $J$ ,  $t_j, s_j$  in  $\mathbf{R}^k$  and  $\lambda$  in  $\Lambda$ ;  $f_i(t, \theta, \lambda) = 0$  ( $\exp(p(t))$ )  
 ( $1 \leq i \leq k$ ) for fixed  $\lambda$  in  $\Lambda$  and every  $t$  in  $J$  ( $\theta$  denotes the zero of space  $\mathbf{R}^k$ ).

The set  $A$  admits a norm  $\|\cdot\|$  defined as  $\|x\| = \sup\{\exp(-p(t)) \cdot |x(t)| : t \geq 0\}$ . In  $X$  we define the generalized metric  $d_E$  as follows: for each  $x = (x_1, \dots, x_k)$  and  $y = (y_1, \dots, y_k)$  write  $d_E(x, y) = (\|x_1 - y_1\|, \|x_2 - y_2\|, \dots, \|x_k - y_k\|)$ , where  $\|\cdot\|$  denotes the usual supremum norm in the space of bounded continuous functions on  $J$ . Obviously,  $(X, d_E)$  is a generalized complete metric space.

We shall deal with the set  $\mathcal{F}$  as an  $\mathcal{L}^*$ -space endowed with convergence:  $\lim_{n \rightarrow \infty} (f_1^{(n)}, f_2^{(n)}, \dots, f_k^{(n)}) = (f_1^{(0)}, f_2^{(0)}, \dots, f_k^{(0)})$  if and only if

$$\lim_{n \rightarrow \infty} \sup\{\exp(-p(t)) \cdot |f_i^{(n)}(t, u, \lambda) - f_i^{(0)}(t, u, \lambda)| : (t, u) \in J \times \mathbf{R}^k\} = 0$$

for every  $\lambda$  in  $\Lambda$  and every  $1 \leq i \leq k$ . Moreover,  $\mathcal{F} \times \Lambda$  be the  $\mathcal{L}^*$ -product of the  $\mathcal{L}^*$ -spaces  $\mathcal{F}, \Lambda$ .

Further, suppose that  $h: J \rightarrow J$  is a continuous function, there exists a constant  $q > 0$  such that  $\exp(p(h(t))) \leq q \cdot \exp(p(t))$  for all  $t$  in  $J$ , and  $[q \cdot K_{ij}]$  ( $1 \leq i, j \leq k$ ) is a non-zero matrix with

$$\begin{vmatrix} 1 - qK_{11} & -qK_{12} & \dots & -qK_{1i} \\ -qK_{21} & 1 - qK_{22} & \dots & -qK_{2i} \\ \dots & \dots & \dots & \dots \\ -qK_{i1} & -qK_{i2} & \dots & 1 - qK_{ii} \end{vmatrix} > 0$$

for every  $i = 1, 2, \dots, k$ .

Under these conditions we have the following theorem:

*For an arbitrary  $F$  in  $\mathcal{F}$  and  $\lambda$  in  $\Lambda$  there exists a unique function  $x_{(F, \lambda)}$  in  $A$  such that*

$$x_{(F, \lambda)}(t) = F(t, x_{(F, \lambda)}(h(t)), \lambda)$$

*for every  $t \geq 0$ . Moreover, if there exists functions  $\alpha, \beta$  from  $J$  to  $J$  such that  $\alpha(t) = 0$  ( $\exp(p(t))$ ) for  $t \geq 0$ ,  $\beta(t) \rightarrow 0$  as  $t \rightarrow 0_+$  and*

$$|f_i(t, u, \lambda) - f_i(t, u, \mu)| \leq \alpha(t) \cdot \beta(\delta(\lambda, \mu)) \quad (1 \leq i \leq k)$$

*for all  $(f_1, f_2, \dots, f_k) \in \mathcal{F}$ ,  $t \geq 0$ ,  $u \in \mathbf{R}^k$  and  $\lambda, \mu$  in  $\Lambda$ , then the function*

$$(F, \lambda) \mapsto x_{(F, \lambda)}$$

maps continuously  $\mathcal{L}^*$ -space  $\mathcal{F} \times \Lambda$  into Banach space  $A$ .

PROOF. Let  $m = 0, 1, \dots$ . Let  $F^{(m)} = (f_1^{(m)}, \dots, f_k^{(m)}) \in \mathcal{F}$  and  $\lambda_m \in \Lambda$  be such that  $\lim_{n \rightarrow \infty} F^{(n)} = F^{(0)}$  and  $\lim_{n \rightarrow \infty} \delta(\lambda_n, \lambda_0) = 0$ . For each  $x$  in  $A$ , define:

$$\begin{aligned} (Tx)(t) &= \exp(-p(t)) \cdot x(t), \\ (H_m x)(t) &= \exp(-p(t)) \cdot F^{(m)}(t, x(h(t)), \lambda_m) \end{aligned}$$

on  $J$ .

For  $x = (x_1, x_2, \dots, x_k) \in A$  and  $t \geq 0$  we obtain

$$\begin{aligned} |(H_m x)(t)| &\leq (|F^{(m)}(t, x(h(t)), \lambda_m) - F^{(m)}(t, \theta, \lambda_m)| + \\ &\quad + |F^{(m)}(t, \theta, \lambda_m)|) \cdot \exp(-p(t)) \leq \\ &\leq \left( \sum_{j=1}^k \sum_{j=1}^k K_{ij} |x_j(h(t))| + |F^{(m)}(t, \theta, \lambda_m)| \right) \cdot \exp(-p(t)) \leq \\ &\leq (c_1 \cdot \exp(p(h(t))) + c_2 \cdot \exp(p(t))) \cdot \exp(-p(t)) \leq c_1 q + c_2 \end{aligned}$$

with some constants  $c_1, c_2$ , and therefore  $H_m$  maps  $A$  into  $X$ . Further, it can be easily seen that  $T[A] = X$  and  $H_m[A] \subset T[A]$ .

We observe [2] that the operator  $L$  generated by the matrix  $[q \cdot K_{ij}]$  is a bounded positive linear operator with the spectral radius less than 1. For  $x = (x_1, \dots, x_k), y = (y_1, \dots, y_k)$  in  $A$  and  $t \geq 0$  we have

$$\begin{aligned} &\exp(-p(t)) \cdot |f_i^{(m)}(t, x(h(t)), \lambda_m) - f_i^{(m)}(t, y(h(t)), \lambda_m)| \leq \\ &\leq \left( \sum_{j=1}^k K_{ij} \cdot \sup_{t \geq 0} \exp(-p(t)) |x_j(t) - y_j(t)| \right) \cdot \exp(-p(t)) \cdot \exp(p(h(t))) \leq \\ &\leq q \cdot \sum_{j=1}^k K_{ij} \cdot \sup_{t \geq 0} \exp(-p(t)) \cdot |x_j(t) - y_j(t)|, \\ d_E(H_m x, H_m y) &= (\sup_{t \geq 0} \exp(-p(t)) \cdot |f_1^{(m)}(t, x(h(t)), \lambda_m) - f_1^{(m)}(t, y(h(t)), \lambda_m)|, \\ &\dots \\ &\quad \sup_{t \geq 0} \exp(-p(t)) \cdot |f_k^{(m)}(t, x(h(t)), \lambda_m) - f_k^{(m)}(t, y(h(t)), \lambda_m)|), \\ L(d_E(Tx, Ty)) &= \left( q \cdot \sum_{j=1}^k K_{1j} \cdot \sup_{t \geq 0} \exp(-p(t)) \cdot |x_j(t) - y_j(t)|, \dots \right. \\ &\quad \left. \dots, q \cdot \sum_{j=1}^k k_{kj} \cdot \sup_{t \geq 0} \exp(-p(t)) \cdot |x_j(t) - y_j(t)| \right) \end{aligned}$$

and therefore  $d_E(H_m x, H_m y) \preceq L(d_E(Tx, Ty))$ .

Let us fix  $x$  in  $A$ . For  $t \geq 0$ ,  $1 \leq i \leq k$  and  $n \geq 1$  we get

$$|f_i^{(n)}(t, x(h(t)), \lambda_n) - f_i^{(0)}(t, x(h(t)), \lambda_0)| \leq \alpha(t) \cdot \beta(\delta(\lambda_n, \lambda_0)) + \\ + |f_i^{(n)}(t, x(h(t)), \lambda_0) - f_i^{(0)}(t, x(h(t)), \lambda_0)|$$

hence

$$\sup_{t \geq 0} \exp(-p(t)) |f_i^{(n)}(t, x(h(t)), \lambda_n) - f_i^{(0)}(t, x(h(t)), \lambda_0)| \leq c \cdot \beta(\delta(\lambda_n, \lambda_0)) + \\ + \sup\{\exp(-p(t)) |f_i^{(n)}(t, u, \lambda_0) - f_i^{(0)}(t, u, \lambda_0)| : (t, u) \in J \times \mathbf{R}^k\}$$

with some constant  $c$ , and it follows

$$\lim_{n \rightarrow \infty} \sup_{t \geq 0} \exp(-p(t)) |f_i^{(n)}(t, x(h(t)), \lambda_n) - f_i^{(0)}(t, x(h(t)), \lambda_0)| = 0.$$

Finally,  $\|d_E(H_n x, H_0 x)\| \rightarrow 0$  as  $n \rightarrow \infty$ .

This proves that the theorem 1 and 2 is applicable to the mappings  $T$ ,  $H_m$  ( $m = 0, 1, \dots$ ), and the proof is finished.

#### REFERENCES

- [1] A. Bielecki, *Une remarque sur la méthode de Banach-Cacciopoli-Tikhonow dans la théorie des équations différentielles ordinaires*, Bull. Acad. Polon. Sci. Sér. Sci. Math. Astronom. Phys. **4** (1956), 261–264.
- [2] F. R. Gantmacher, *The theory of matrices*, [in Russian], Moscow 1966.
- [3] K. Goebel, *A coincidence theorem*, Bull. Acad. Polon. Sci., Sér. Sci. Math. Astronom. Phys. **16** (1968), 733–735.
- [4] K. Iseki, *A common fixed point theorem*, Rend. Sem. Mat. Univ. Padova **53** (1975), 13–14.
- [5] M. A. Krasnoselskii, *Two remarks on the method of successive approximations*, Uspehi Mat. Nauk **10** (1955), 123–127 [in Russian].
- [6] M. A. Krasnoselskii, G. M. Vainikko, P. P. Zabreiko, Ja. B. Rutickii and V. Ja. Stecenko, *Approximate solution of operator equations*, Moscow 1969 [in Russian].
- [7] C. Kuratowski, *Topologie*, vol. I, Warsaw 1952.
- [8] D. Kurepa, *Tableaux ramifiés d'ensembles. Espaces pseudodistanciés*, C. R. **198** (1934), 1563–1565.
- [9] W. A. J. Luxemburg, *On the convergence of successive approximations in the theory of ordinary differential equations II*, Indag. Math. **20** (1958), 540–546.
- [10] M. G. Maia, *Un' Osservazione sulle contrazioni metriche*, Ren. Sem. Mat. Univ. Padova **40** (1968), 139–143.
- [11] B. Ray, *On a fixed point theorem in a space with two metric*, The Math. Education **9** (173), 57 A–58A.
- [12] B. E. Rhoades, *A common fixed point theorem*, Rend. Sem. Mat. Univ. Padova **56** (1977), 265–266.
- [13] B. Rzepecki, *A generalization of Banach's contraction theorem*, to appear in Bull. Acad. Polon. Sci. Sér. Sci. Math. Astronom. Phys.

- [14] B. Rzepecki, *On some classes of differential equations*, in preparation (Publ. Inst. Math.).
- [15] B. Rzepecki, *Note of differential equation  $F(t, y(t), y(h(t)), y'(t)) = 0$* , to appear in Comment. Math. Univ. Caroline.
- [16] B. Rzepecki, *Existence and continuous dependence of solutions for some classes of nonlinear differential equations and Bielecki's method of changing the norm*, in preparation.
- [17] B. Rzepecki, *Remarks on the Banach Fixed Point Principle and its applications*, in preparation.
- [18] S. P. Singh, *On a fixed point theorem in metric space*, Rend. Math. Sem. Univ. Padova **43** (1970), 229–231.

Institute of Mathematics  
A. Mickiewicz University  
Matejki 48/49, Poznań, Poland

Osiedle Bohaterów II Wojny Światowej 43/13  
61-385 Poznań, Poland