

## DIFFERENT KINDS OF THE COVARIANT DIFFERENTIATIONS IN RECURRENT FINSLER SPACES

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**Abstract.** A Finsler spaces defined to be recurrent if the metric tensor is recurrent. In such a space two orthogonal families of vector fields are defined. Using a family of connection coefficients depending on a parameter, we examine conditions which should be satisfied so that the projections of the metric tensor in the direction of mentioned vector fields are recurrent.

**1. Introduction.** In this paper the Finsler spaces in which the metric tensor is recurrent i.e. satisfies (2.14)–(2.17) will be examined. In this space  $m$  vectorfields  $B_a^\alpha(x, \dot{x})$  and  $n - m$  vectorfields  $N_k^\alpha(x, \dot{x})$  which are linearly independent and satisfy (2.1) are given. The vector  $dx^a$  and  $\dot{x}^a$  are decomposed in the direction of these vectors as it is given by (2.6) and (2.7). We shall suppose that

$$F^\alpha(x^1, \dots, x^n, \dot{x}^1, \dots, \dot{x}^n, u^1, \dots, u^m, v^{m+1}, \dots, v^n, \dot{u}^1, \dots, \dot{u}^m, \dot{v}^{m+1}, \dots, \dot{v}^n) = 0, \\ \alpha = 1, 2, \dots, n$$

any of the solutions of system of differential equations (2.6), together with (2.7) define  $x$  and  $\dot{x}$  as the functions of  $u, \dot{u}, v, \dot{v}$  in the form

$$x^\alpha = x^\alpha(u^1, \dots, u^m, v^{m+1}, \dots, v^n, \dot{u}^1, \dots, \dot{u}^m, \dot{v}^{m+1}, \dots, \dot{v}^n) \\ \dot{x}^\alpha = \dot{x}^\alpha(u^1, \dots, u^m, v^{m+1}, \dots, v^n, \dot{u}^1, \dots, \dot{u}^m, \dot{v}^{m+1}, \dots, \dot{v}^n) \\ \alpha = 1, 2, \dots, n$$

In this paper we shall not obtain the above equations but the partial derivatives of tensors with respect to  $u, v, \dot{u}, \dot{v}$  will be substituted by derivatives with respect to  $x$  and  $\dot{x}$  (see (4.8)). We shall suppose that the tensor and vector fields in  $F_n$  are homogeneous of degree zero in  $\dot{x}$ . For a vector field  $\xi^\alpha(x, \dot{x})$  we have

$$(1.1) \quad \xi^\alpha(x, \dot{x}) = B_a^\alpha(x, \dot{x})\xi^a(x, \dot{x}) + N_k^\alpha(x, \dot{x})\xi^k(x, \dot{x})$$

where  $\xi^a = B_a^\alpha \xi^a$ ,  $\xi^k = N_k^\alpha \xi^a$  are also homogeneous functions of degree zero in  $x$ .  
As

$$\xi^x(x, \dot{x}) = \xi^x(u, v, \dot{u}, \dot{v}) \quad (x = a \text{ or } x = k)$$

and

$$\lambda \dot{x}^\alpha = B_a^\alpha(x, \dot{x}) \lambda \dot{u}^a + N_k^\alpha(x, \dot{x}) \lambda \dot{v}^k$$

it follows that

$$\xi^x(u, v, \lambda \dot{u}, \lambda \dot{v}) = \xi^x(u, v, \dot{u}, \dot{v})$$

and

$$(1.2) \quad \dot{\delta}_a \xi^x \dot{u}^a + \dot{\delta}_k \xi^x \dot{v}^k = 0$$

where

$$\dot{\delta}_a = \delta / \delta \dot{u}^a, \quad \dot{\delta}_k = \delta / \delta \dot{v}^k.$$

Formulae (1.2) are valid always when instead of  $\xi^x$  there are coordinates of any tensor field homogeneous of degree zero in  $\dot{x}$ .

We shall define different kinds of connection coefficients and covariant differentiations which are generalisations of the induced differential on a subspace of  $F_n$ .

For some special cases of (2.6) its solution is a family of subspaces of  $F_n$ . Some of these are mentioned here.

If we fix the vector  $\dot{x}$  in the equation  $dx^\alpha = B_a^\alpha(x, \dot{x}) du^a + N_k^\alpha(x, \dot{x}) dv^k$  we obtain

$$dx^\alpha = B_a^\alpha(x, \dot{x}_0) du^a + N_k^\alpha(x, \dot{x}_0) dv^k, \quad \alpha = 1, 2, \dots, n.$$

For  $dv^k = 0$  these equations reduce to  $dx^\alpha = B_a^\alpha(x) du^a$ . These are the differential equations of the family of subspaces

$$x^\alpha = f^\alpha(u^1, \dots, u^m, C_{m+1}, \dots, C_n) \quad \alpha = 1, 2, \dots, n$$

$$\det I = \det \left[ \frac{\delta(x^1, x^2, \dots, x^n)}{\delta(u^1, \dots, u^m, C_{m+1}, \dots, C_n)} \right]$$

and  $C_{m+1}, \dots, C_n$  are arbitrary constants. From  $\det I \neq 0$  it follows that (1.3) may be written in the form

$$\begin{aligned} u^a &= u^a(x^1, x^2, \dots, x^n), & a &= 1, 2, \dots, m \\ C_k &= C_k(x^1, x^2, \dots, x^n), & k &= m+1, \dots, n \end{aligned}$$

Using these equations we obtain from (1.1)

$$\begin{aligned} \delta_a x^\alpha &= \delta_a f^\alpha(u^1, \dots, u^m, C_{m+1}, \dots, C_n) = \bar{B}_a^\alpha(u^1, \dots, u^m, C_{m+1}, \dots, C_n) \\ &= \bar{B}_a^\alpha[u^1(x^1, \dots, x^n), \dots, C_n(x^1, \dots, x^n)] = B_a^\alpha(x^1, \dots, x^n) \\ &(\delta_a = \delta / \delta u^a). \end{aligned}$$

For all  $m$  dimensional subspaces  $x^\alpha = f^\alpha(u^1, \dots, u^m, C_{m+1}, \dots, C_n) B_a^\alpha$  are the tangent vectors and  $N_k^\alpha$  are the normal vectors, according to (2.1). For the same fixed  $\dot{x}$  ( $\dot{x} = \dot{x}_0$ ) putting  $du^a = 0$  we obtain another family of subspaces

$$x^\alpha = g^\alpha(C_1, \dots, C_m v^{m+1}, \dots, v^n)$$

for which  $N_k^\alpha$  are the tangent vectors and  $B_a^\alpha$  are the normal vectors. For every fixed  $\dot{x}$  we obtain a similar orthogonal family of subspaces but the induced metric on each subspace is Riemannian. We have

$$g_{ab}(u, v) = g_{\alpha\beta}(x, \dot{x}_0) B_a^\alpha(x, \dot{x}_0) B_b^\beta(x, \dot{x}_0)$$

If we put  $v^k = \bar{C}_k$ ,  $k = m + 1, \dots, n$  we obtain

$$g_{ab} = g_{ab}(u, \bar{C}_{m+1}, \dots, \bar{C}_n),$$

a Riemannian metric on the subspace  $x^\alpha = x^\alpha(u^1, \dots, u^m, \bar{C}_{m+1}, \dots, \bar{C}_n)$ . The more interesting case is when  $B_a^\alpha = B_a^\alpha(x)$  on the whole  $F_n$  ( $\text{rank}[B_a^\alpha] = m$ ). The equations  $dx^\alpha = B_a^\alpha(x) du^a$  ( $dv^k = 0$ ) define a family of subspaces  $F_m$ ,  $x^\alpha = x^\alpha(u^1, \dots, u^m, \bar{C}_{m+1}, \dots, \bar{C}_n)$  for which  $B_a^\alpha(x)$  are the tangent vectors and  $N_k^\alpha(x, \dot{x})$  are the normal vectors because  $g_{\alpha\beta}(x, \dot{x}) B_a^\alpha(x) N_k^\alpha(x, \dot{x}) = 0$ . The induced metric is defined as usual by  $g_{ab}(u, \dot{u}, v, \dot{v}) = g_{\alpha\beta}(x, \dot{x}) B_a^\alpha(x) B_b^\beta(x)$  and it is a Finsler metric when  $\dot{v} = 0$  (i.e.  $\dot{x}^\alpha = B_a^\alpha(x) \dot{u}^a$ ) and  $v^k = \bar{C}_k$   $k = m + 1, \dots, n$  on the subspace

$$x^\alpha = x^\alpha(u^1, \dots, u^m, \bar{C}_{m+1}, \dots, \bar{C}_n).$$

The situation is similar when  $N_k^\alpha = N_k^\alpha(x)$ ,  $k = m + 1, \dots, n$  and  $B_a^\alpha = B_a^\alpha(x, \dot{x})$ , only then  $N_k^\alpha$  are the components of tangent vectors of the subspaces and  $B_a^\alpha$  are the normal vectors.

The induced differentials  $\bar{D}\xi^a$ ,  $\bar{D}\xi^k$  are defined by

$$\bar{D}\xi^a = B_a^\alpha D\xi^\alpha, \quad \bar{D}\xi^k = N_k^\alpha D\xi^\alpha.$$

For the special case when  $\xi^k = 0$  and  $\xi^a(u, v, \dot{u}, \dot{v}) = \xi^a(u, \dot{u})$ , where all  $v^k$  are fixed and  $\dot{v}^k = 0$  for  $k = m + 1, \dots, n$  we have the classical case where  $\dot{x}^a = B_a^\alpha \dot{u}^a$  and  $\xi^\alpha = B_a^\alpha \xi^a$ .

In 4 are given conditions when the tensors  $g_{ab}$  and  $g_{nk}$  will be recurrent with respect to different kinds of covariant differentiation.

## 2. The induced connection coefficients in a recurrent Finsler space.

In the Finsler space  $F_n$  the metric function is  $F(x, \dot{x})$ . Let us define  $m$  vector fields  $B_a^\alpha(x, \dot{x})$  and  $n - m$  vector fields  $N_k^\alpha(x, \dot{x})$

$$\alpha, \beta, \gamma, \delta, \varepsilon, \chi, \dots = 1, 2, \dots, n$$

$$a, b, c, d, e, f, \dots = 1, 2, \dots, m$$

$$k, l, m, n, p, q, \dots = m + 1, \dots, n$$

in such a way that these vector fields be linearly independent at each  $(x, \dot{x})$  and satisfy the relations

$$(2.1) \quad g_{\alpha\beta}(x, \dot{x}) B_a^\alpha(x, \dot{x}) N_k^\alpha(x, \dot{x}) = 0$$

for each  $a = 1, 2, \dots, m$ ,  $k = m + 1, \dots, n$ . Let us define

$$(2.2) \quad \text{a) } g_{ab} = g_{\alpha\beta} B_a^\alpha B_b^\beta \quad \text{b) } g_{kl} = g_{\alpha\beta} N_k^\alpha N_l^\beta$$

$$(2.3) \quad \text{a) } B_\beta^b = g^{ab} g_{\alpha\beta} B_a^\alpha \quad \text{b) } N_\alpha^k = g^{km} g_{\alpha\beta} N_m^\beta$$

where  $g_{\alpha\beta}$ ,  $B_a^\alpha$  and  $N_k^\beta$  are zero degree of homogeneity in  $\dot{x}$ ,  $(g^{ab})$  and  $(g^{km})$  are inverse metrics of  $(g_{ab})$  and  $(g_{km})$  respectively. From (2.2) and (2.3) we have

$$(2.4) \quad \begin{aligned} \text{a)} \quad & N_\alpha^k N_p^\alpha = g^{kl} g_{\alpha\beta} N_l^\beta N_p^\alpha = g^{kl} g_{lp} = \delta_p^k \\ \text{b)} \quad & B_\alpha^a B_b^\alpha = g^{ac} g_{\alpha\beta} B_c^\beta B_b^\alpha = g^{ac} g_{cb} = \delta_b^a. \end{aligned}$$

As usual

$$(2.5) \quad \delta_\beta^\alpha = B_a^\alpha B_\beta^a + N_k^\alpha N_\beta^k.$$

If  $\xi^\alpha(x, \dot{x})$  is a vectorfield in  $F_n$  homogeneous of degree zero in  $\dot{x}$ , then

$$\xi^\alpha = B_a^\alpha \xi^a + N_k^\alpha \xi^k.$$

We may write

$$(2.6) \quad dx^\alpha = B_a^\alpha du^a + N_k^\alpha dv^k$$

$$(2.7) \quad \dot{x}^\alpha = B_a^\alpha \dot{u}^a + N_k^\alpha \dot{v}^k.$$

Let us define the absolute differential which corresponds to the motion from  $(x, \dot{x})$  to  $(\dot{x} + dx, \dot{x} + d\dot{x})$  by  $D$ .

The induced differentials are defined by

$$(2.8) \quad \text{a)} \quad \bar{D}\xi^a = B_a^\alpha D\xi^\alpha \quad \text{b)} \quad \bar{D}\xi^k = N_k^\alpha D\xi^\alpha$$

and

$$(2.9) \quad D\xi^\alpha = B_a^\alpha \bar{D}\xi^a + N_k^\alpha \bar{D}\xi^k.$$

We shall use the notation

$$(2.10) \quad l^\alpha = F^{-1}\dot{x}^\alpha = F^{-1}(B_a^\alpha \dot{u}^a + N_k^\alpha \dot{v}^k) = B_a^\alpha l^a + N_k^\alpha l^k$$

where

$$(2.11) \quad l^a = F^{-1}\dot{u}^a, \quad l^k = F^{-1}\dot{v}^k.$$

From (2.9) we have

$$(2.12) \quad Dl^\alpha = B_a^\alpha \bar{D}l^a + N_k^\alpha \bar{D}l^k$$

where

$$Dl^\alpha = dl^\alpha + \Gamma_{0\gamma}^* dx^\gamma + A_{0\gamma}^\alpha Dl^\gamma.$$

We shall suppose that the metric tensor is determined by

$$(2.13) \quad g_{\alpha\beta}(x, \dot{x}) = 2^{-1} \dot{\delta}_\alpha \dot{\delta}_\beta F^2(x, \dot{x})$$

and that the space  $F_n$  is recurrent, i.e.

$$(2.14) \quad g_{\alpha\beta|\gamma} = \lambda_\gamma(x, \dot{x}) g_{\alpha\beta}.$$

$$(2.15) \quad g_{\alpha\beta} |_\gamma = \mu_\gamma(x, \dot{x}) g_{\alpha\beta}.$$

As

$$(2.16) \quad Dg_{\alpha\beta} = g_{\alpha\beta|\gamma}dx^\gamma + g_{\alpha\beta}|\gamma Dl^\gamma.$$

from (2.14) and (2.15) we obtain

$$(2.17) \quad Dg_{\alpha\beta} = K(x, \dot{x}, dx, Dl)g_{\alpha\beta}.$$

where

$$(2.18) \quad K(x, \dot{x}, dx, Dl) = \lambda_\gamma(x, \dot{x})dx^\gamma + \mu_\gamma(x, \dot{x})Dl^\gamma.$$

The absolute differential of  $g_{\alpha\beta}$  is

$$(2.19) \quad Dg_{\alpha\beta} = dg_{\alpha\beta} - (\Gamma_{\alpha\gamma}^{\delta}g_{\delta\beta} + \Gamma_{\beta\gamma}^{\delta}g_{\alpha\delta})dx^\gamma - (A_{\alpha\gamma}^{\delta}g_{\delta\beta} + A_{\beta\gamma}^{\delta}g_{\alpha\delta})Dl^\gamma.$$

The connection coefficients are determined in [2] under conditions  $\Gamma_{\alpha\beta\gamma}^* = \Gamma_{\gamma\beta\alpha}^*$  and  $A_{\alpha\beta\gamma} = A_{\beta\alpha\gamma}$ , but in [3] under conditions  $\Gamma_{\alpha\beta\gamma}^* = \Gamma_{\gamma\beta\alpha}^*$ ,  $A_{\alpha\beta\gamma} = A_{\gamma\beta\alpha}$ .

In this paper we shall use two last conditions.

The vector  $dx^\gamma$  and  $Dl^\gamma$  ( $\gamma = 1, 2, \dots, n$ ) are not linearly independent. As is known that in the non-recurrent Finsler space from  $g_{\alpha\beta}l^\alpha l^\beta = 1$  it follows that  $l_\alpha Dl^\alpha = 0$ . In a recurrent Finsler space from  $g_{\alpha\beta}l^\alpha l^\beta = 1$  we obtain using (2.14)–(2.16)

$$(2.20) \quad \lambda_\beta dx^\beta + (\mu_\beta + 2l_\beta)Dl^\beta = 0.$$

In [3] the induced connection coefficients are determined, but (2.20) was not taken into account. Here this will be done and we obtain a family of connection coefficients depending on some parameters. As in [3] we shall write

$$(2.21) \quad DB_a^\alpha = \bar{w}_a^d(d)B_d^\alpha + \bar{w}_a^m(d)N_m^\alpha$$

$$(2.22) \quad DN_k^\alpha = \bar{w}_k^d(d)B_d^\alpha + \bar{w}_k^m(d)N_m^\alpha$$

where

$$(2.23) \quad \bar{w}_y^x(d) = \bar{\Gamma}_{yb}^{*x}du^b + \bar{\Gamma}_{yk}^{*x}dv^k + \bar{A}_{yb}^x \bar{D}l^b + \bar{A}_{yk}^x \bar{D}l^k$$

$x = d \text{ or } x = m, \quad y = a \text{ or } y = k.$

From (2.1) and (2.17) we have

$$D(g_{\alpha\beta}B_a^\alpha N_k^\beta) = g_{\alpha\beta}(DB_a^\alpha)N_k^\beta + g_{\alpha\beta}B_a^\alpha DN_k^\beta = 0.$$

Substituting (2.21) and (2.22) into the above equation and using (2.2) we obtain

$$(2.24) \quad \bar{w}_{ak} = -\bar{w}_{ka} \Leftrightarrow g_{km}\bar{w}_a^m = -g_{ab}\bar{w}_k^b,$$

the same equation as in a non-recurrent Finsler space. If we express  $DB_a^\alpha$  by the connection coefficients of the space  $F_n$  and use (2.6) and (2.12) we get

$$(2.25) \quad DB_a^\alpha = (B_{a|\beta}^\alpha du^b + B_{a|\beta}^\alpha \bar{D}l^b)B_b^\beta + (B_{a|\beta}^\alpha dv^k + B_{a|\beta}^\alpha \bar{D}l^k)N_k^\beta,$$

where

$$(2.26) \quad \begin{aligned} \text{a) } B_{a|\beta}^\alpha &= \delta_\beta B_a^\alpha - \dot{\delta}_\gamma B_a^\alpha \Gamma_\beta^{\gamma*} + \Gamma_{\gamma\beta}^{\alpha*} B_a^\gamma & (\Gamma_\beta^{\gamma*} &= \Gamma_{\alpha\beta}^{\gamma*} \dot{x}^\alpha) \\ \text{b) } B_{a|\beta}^{\alpha|} &= F \dot{\delta}_\delta B_a^\alpha (\delta_\beta^\delta - A_{0\beta}^\delta) + A_{\delta\beta}^{\alpha} B_a^\delta & (A_{0\beta}^\delta &= A_{\alpha\beta}^\delta l^\alpha) \end{aligned}$$

If we substitute (2.6) and (2.12) into (2.20) using the notations

$$(2.27) \quad \lambda_b = B_b^\beta \lambda_\beta, \quad \lambda_k = N_k^\beta \lambda_\beta, \quad \mu_c = B_b^\beta \mu_\beta, \quad \mu_k = N_k^\beta \mu_\beta,$$

we obtain

$$(2.28) \quad 0 = \theta_a^\alpha(x, \dot{x}) [\lambda_b du^b + \lambda_k dv^k + (\mu_b + 2l_b) \bar{D}l^b + (\mu_k + 2l_k) \bar{D}l^k]$$

where  $\theta_a^\alpha$  is any parameter homogeneous of degree zero in  $\dot{x}$ . If we equate the right hand side of (2.21) with the sum of the right-hand sides of (2.25) and (2.28) we get an equation where on the both sides terms with factors  $du^b$ ,  $dv^k$ ,  $\bar{D}l^b$  and  $\bar{D}l^k$  are present. Equating the corresponding coefficients we obtain

$$\begin{aligned} du^b : \quad & \bar{\Gamma}_{ab}^{*d} B_d^\alpha + \bar{\Gamma}_{ab}^{*m} N_m^\alpha = B_{a|\beta}^\alpha B_b^\beta + \theta_a^\alpha \lambda_b \\ dv^k : \quad & \bar{\Gamma}_{ak}^{*d} B_d^\alpha + \bar{\Gamma}_{ak}^{*m} N_m^\alpha = B_{a|\beta}^\alpha N_k^\beta + \theta_a^\alpha \lambda_k \\ \bar{D}l^b : \quad & \bar{A}_{ab}^{*d} B_d^\alpha + \bar{A}_{ab}^{*m} N_m^\alpha = B_{a|\beta}^{\alpha|} B_b^\beta + \theta_a^\alpha (\mu_b + 2l_b) \\ \bar{D}l^k : \quad & \bar{A}_{ak}^{*d} B_d^\alpha + \bar{A}_{ak}^{*m} N_m^\alpha = B_{a|\beta}^{\alpha|} N_k^\beta + \theta_a^\alpha (\mu_k + 2l_k) \end{aligned}$$

Multiplying the above equations first by  $g_{\alpha\gamma} B_c^\gamma$  then by  $g_{\alpha\gamma} N_n^\gamma$  and using the notation  $\theta_{ac} = \theta_a^\alpha g_{\alpha\gamma} B_c^\gamma$ ,  $\theta_{an} = \theta_a^\alpha g_{\alpha\gamma} N_n^\gamma$  we obtain

$$(2.29) \quad \begin{aligned} \text{(a)} \quad & \bar{\Gamma}_{acb}^* = g_{\alpha\gamma} B_c^\gamma B_b^\beta B_{a|\beta}^\alpha + \theta_{ac} \lambda_b \\ \text{(b)} \quad & \bar{\Gamma}_{ack}^* = g_{\alpha\gamma} B_c^\gamma N_k^\beta B_{a|\beta}^\alpha + \theta_{ac} \lambda_k \\ \text{(c)} \quad & \bar{A}_{acb} = g_{\alpha\gamma} B_c^\gamma B_b^\beta B_{a|\beta}^{\alpha|} + \theta_{ac} (\mu_b + 2l_b) \\ \text{(d)} \quad & \bar{A}_{ack} = g_{\alpha\gamma} B_c^\gamma N_k^\beta B_{a|\beta}^{\alpha|} + \theta_{ac} (\mu_k + 2l_k) \\ \text{(e)} \quad & \bar{\Gamma}_{anb}^* = g_{\alpha\gamma} N_n^\gamma B_b^\beta B_{a|\beta}^\alpha + \theta_{an} \lambda_b \\ \text{(f)} \quad & \bar{\Gamma}_{ank}^* = g_{\alpha\gamma} N_n^\gamma N_k^\beta B_{a|\beta}^\alpha + \theta_{an} \lambda_k \\ \text{(g)} \quad & \bar{A}_{anb} = g_{\alpha\gamma} N_n^\gamma B_b^\beta B_{a|\beta}^{\alpha|} + \theta_{an} (\mu_b + 2l_b) \\ \text{(h)} \quad & \bar{A}_{ank} = g_{\alpha\gamma} N_n^\gamma N_k^\beta B_{a|\beta}^{\alpha|} + \theta_{an} (\mu_k + 2l_k). \end{aligned}$$

In a similar manner using the expression for  $DN_k^\alpha$  and the notations

$$\nu_{kc} = \nu_k^\alpha g_{\alpha\gamma} B_c^\gamma, \quad \nu_{kn} = \nu_k^\alpha g_{\alpha\gamma} N_n^\gamma,$$

where  $\nu_k^\alpha(x, \dot{x})$  is any parameter homogeneous of degree zero in  $\dot{x}$  we obtain

$$(2.30) \quad \begin{aligned} (a) \quad & \bar{\Gamma}_{kcb}^* = g_{\alpha\gamma} B_c^\gamma B_b^\beta N_{k|\beta}^\alpha + \nu_{kc} \lambda_b \\ (b) \quad & \bar{\Gamma}_{kcl}^* = g_{\alpha\gamma} B_c^\gamma N_l^\beta N_{k|\beta}^\alpha + \nu_{kc} \lambda_l \\ (c) \quad & \bar{A}_{kcb} = g_{\alpha\gamma} B_c^\gamma B_b^\beta N_{k|\beta}^\alpha + \nu_{kc} (\mu_b + 2l_b) \\ (d) \quad & \bar{A}_{kcl} = g_{\alpha\gamma} B_c^\gamma N_l^\beta N_{k|\beta}^\alpha + \nu_{kc} (\mu_l + 2l_l) \\ (e) \quad & \bar{\Gamma}_{knb}^* = g_{\alpha\gamma} N_n^\gamma B_b^\beta N_{k|\beta}^\alpha + \nu_{kn} \lambda_b \\ (f) \quad & \bar{\Gamma}_{knl}^* = g_{\alpha\gamma} N_n^\gamma N_l^\beta N_{k|\beta}^\alpha + \nu_{kn} \lambda_l \\ (g) \quad & \bar{A}_{knb} = g_{\alpha\gamma} N_n^\gamma B_b^\beta N_{k|\beta}^\alpha + \nu_{kn} (\mu_b + 2l_b) \\ (h) \quad & \bar{A}_{knl} = g_{\alpha\gamma} N_n^\gamma N_l^\beta N_{k|\beta}^\alpha + \nu_{kn} (\mu_l + 2l_l) \end{aligned}$$

The connection coefficients obtained in [3] are the special case of those obtained here, when we take  $\theta_a^\alpha = 0$  and  $\nu_k^\alpha = 0$ .

The parametres  $\theta_a^\alpha$  and  $\nu_k^\alpha$  cannot be chosen arbitrarily because of (2.24), from which we obtain

$$\begin{aligned} g_{nk} (\bar{\Gamma}_{ab}^* n^a du^b + \bar{\Gamma}_{al}^* n^a dv^l + \bar{A}_{ab}^* n^a \bar{D}l^b + \bar{A}_{al}^* n^a \bar{D}l^l) \\ = -g_{ad} (\bar{\Gamma}_{kb}^* d^a du^b + \bar{\Gamma}_{kl}^* d^a dv^l + \bar{A}_{kb}^* d^a \bar{D}l^b + \bar{A}_{kl}^* d^a \bar{D}l^l). \end{aligned}$$

From the above relation it follows

$$(2.31) \quad \begin{aligned} \bar{\Gamma}_{akb}^* &= -\bar{\Gamma}_{kab}^* & \bar{\Gamma}_{akl}^* &= -\bar{\Gamma}_{kal}^* \\ \bar{A}_{akb} &= -\bar{A}_{kab} & \bar{A}_{akl} &= -\bar{A}_{kal}. \end{aligned}$$

Substituting the connection coefficients from (2.29) and (2.30) into (2.31) and using the relation

$$g_{\alpha\gamma} B_{a|\beta}^\alpha N_k^\gamma + g_{\alpha\gamma} B_a^\alpha N_{k|\beta}^\gamma = 0$$

and the similar one with  $|\beta$  we obtain

$$(2.32) \quad \theta_{ak} = -\nu_{ka}.$$

**3. Different kinds of covariant differentiation.** From (2.7) and (2.12) we have

$$(3.1) \quad Dl^\alpha = B_a^\alpha \bar{D}l^a + N_k^\alpha \bar{D}l^k = (DB_a^\alpha) l^a + (DN_m^\alpha) l^m + B_a^\alpha dl^a + N_k^\alpha dl^k.$$

In we substitute from (2.21) and (2.22) the expression for  $DB_a^\alpha$  and  $DN_m^\alpha$  using the notations of [4]

$$(3.2) \quad \bar{\Gamma}_{0y}^{*x} = \bar{\Gamma}_{ay}^{*x} l^a + \bar{\Gamma}_{my}^{*x} l^m \quad x = d \text{ or } x = m$$

$$(3.3) \quad A_{0y}^x = \bar{A}_{ay}^x l^a + \bar{A}_{my}^x l^m \quad y = b \text{ or } y = k$$

we obtain

$$(3.4) \quad \bar{D}l^d = dl^d + \bar{\Gamma}_{0b}^* du^b + \bar{\gamma}_{0k}^* dv^k + \bar{A}_{0b}^d \bar{D}l^b + \bar{A}_{0k}^d \bar{D}l^k$$

$$(3.5) \quad \bar{D}l^m = dl^m + \bar{\Gamma}_{0b}^m du^b + \bar{\gamma}_{0k}^m dv^k + \bar{A}_{0b}^m \bar{D}l^b + \bar{A}_{0k}^m \bar{D}l^k.$$

From (2.11) we have

$$dl^d = F^{-1} d\dot{u}^d + \dot{u}^d dF^{-1}, \quad dl^m = F^{-1} d\dot{v}^m + \dot{v}^m dF^{-1}.$$

If we substitute the above equations into (3.4) and (3.5) we get

$$(3.6) \quad d\dot{u}^d = -F\bar{\Gamma}_{0b}^* du^b - F\bar{\Gamma}_{0k}^* dv^k + F(\delta_b^d - A_{0b}^d) \bar{D}l^b - F\bar{A}_{0k}^d \bar{D}l^k + \dot{u}^d F^{-1} dF$$

$$(3.7) \quad d\dot{v}^m = -F\bar{\Gamma}_{0b}^m du^b - F\bar{\Gamma}_{0k}^m dv^k - FA_{0b}^m \bar{D}l^b + F(\delta_k^m - \bar{A}_{0k}^m) \bar{D}l^k + \dot{v}^m F^{-1} dF.$$

For any vectorfield  $\xi^\alpha(x, \dot{x})$  in  $F_n$  we have from (2.9)

$$(3.8) \quad D\xi^\alpha = B_a^\alpha \bar{D}\xi^a + N_k^\alpha \bar{D}\xi^k = (DB_a^\alpha)\xi^a + (DN_k^\alpha)\xi^k + B_a^\alpha d\xi^a + N_k^\alpha d\xi^k.$$

Substituting  $d\dot{u}^d$  and  $d\dot{v}^m$  from (3.6) and (3.7) into

$$(3.9) \quad d\xi^a = \delta_d \xi^a du^d + \dot{\delta}_d \xi^k du^d + \delta_m \xi^a dv^m + \dot{\delta}_m \xi^a d\dot{v}^m$$

$$(3.10) \quad d\xi^k = \delta_d \xi^k du^d + \dot{\delta}_d \xi^k d\dot{u}^d + \delta_m \xi^k dv^m + \dot{\delta}_m \xi^k d\dot{v}^m$$

and so obtained  $d\xi^a$  and  $d\xi^k$  into (3.8) we obtain

$$(3.11) \quad \begin{aligned} D\xi^\alpha = & B_a^\alpha (\xi_{\top c}^a du^c + \xi_{\top m}^a dv^m + \xi^a|_c \bar{D}l^c + \xi^a|_m \bar{D}l^m) \\ & + N_n^\alpha (\xi_{\top c}^n du^c + \xi_{\top m}^n dv^m + \xi^{\bar{n}}|_c \bar{D}l^c + \xi^{\bar{n}}|_m \bar{D}l^m) \\ & + B_a^\alpha F^{-1} dF (\dot{\delta}_d \xi^a \dot{u}^d + \dot{\delta}_m \xi^a \dot{v}^m) + N_n^\alpha F^{-1} dF (\dot{\delta}_d \xi^n \dot{u}^d + \dot{\delta}_m \xi^n \dot{v}^m) \end{aligned}$$

where

$$(3.12) \quad \begin{aligned} (a) \quad \xi_{\top c}^x &= \delta_c \xi^x - F\dot{\delta}_d \xi^x \bar{\Gamma}_{0c}^{*d} - F\dot{\delta}_k \xi^x \bar{\Gamma}_{0c}^{*k} + \bar{\Gamma}_{bc}^{*x} \xi^b + \bar{\Gamma}_{kc}^{*x} \xi^k \\ (b) \quad \xi_{\top m}^x &= \delta_m \xi^x - F\dot{\delta}_d \xi^x \bar{\Gamma}_{0m}^{*d} - F\dot{\delta}_k \xi^x \bar{\Gamma}_{0m}^{*k} + \bar{\Gamma}_{bm}^{*x} \xi^b + \bar{\Gamma}_{km}^{*x} \xi^k \\ (c) \quad \xi^{\bar{a}}|_c &= F\dot{\delta}_d \xi^x (\delta_c^d - \bar{A}_{0c}^d) - F\dot{\delta}_k \xi^x \bar{A}_{0c}^k + \bar{A}_{bc}^x \xi^b + \bar{A}_{kc}^x \xi^k \\ (d) \quad \xi^{\bar{x}}|_m &= -F\dot{\delta}_d \xi^x \bar{A}_{0m}^d + F\dot{\delta}_k \xi^x (\delta_m^k - \bar{A}_{0m}^k) + \bar{A}_{bm}^x \xi^b + \bar{A}_{km}^x \xi^k \end{aligned}$$

$x = a$  or  $x = n$ .

Using the homogeneity conditions for  $\xi^a$  and  $\xi^k$  we have (see (1.2))

$$\dot{\delta}_d \xi^x \dot{u}^d + \dot{\delta}_m \xi^x \dot{v}^m = 0 \quad (x = a \text{ or } x = k),$$

so the last two terms in (3.11) are equal to zero and we obtain

$$(3.13) \quad D\xi^\alpha = B_a^\alpha \bar{D}\xi^a + N_n^\alpha \bar{D}\xi^n,$$

where

$$(3.14) \quad \bar{D}\xi^a = \xi_{\top c}^a du^c + \xi_{\top m}^a dv^m + \xi^a|_c \bar{D}l^c + \xi^a|_m \bar{D}l^m$$

$$(3.15) \quad \bar{D}\xi^n = \xi_{\top c}^n du^c + \xi_{\top m}^n dv^m + \xi^{\bar{n}}|_c \bar{D}l^c + \xi^{\bar{n}}|_m \bar{D}l^m.$$



For the metric tensor  $g_{\alpha\beta}$  the above formulae have the form:

$$(3.16) \quad \begin{aligned} Dg_{\alpha\beta} = & B_{\alpha\beta}^{ab}(g_{ab\top c}du^c + g_{ab\top k}dv^k + g_{ab\top c} \bar{D}l^c + g_{ab\top k} \bar{D}l^k \\ & + D_{\alpha\beta}^{nt}g(g_{nt\top c}du^c + g_{nt\top k}dv^k + g_{nt\top c} \bar{D}l^c + g_{nt\top k} \bar{D}l^k) \\ & + \hat{\theta}_{\alpha\beta}(\lambda_c du^c + \lambda_k dv^k + (\mu_c + 2l_c)\bar{D}l^c + (\mu_k + l_k)\bar{D}l^k), \end{aligned}$$

where  $\hat{\theta}_{\alpha\beta} = \hat{\theta}_{\alpha\beta}(x, \dot{x})$  is a tensor homogeneous of degree zero in  $\dot{x}$  and

$$(3.17) \quad \begin{aligned} g_{ab\top x} &= \delta_x g_{ab} - F\delta_d g_{ab} \bar{\Gamma}_{0x}^{*d} - F\delta_m g_{ab} \bar{\Gamma}_{0x}^{*m} - g_{db} \bar{\Gamma}_{ax}^{*d} - g_{bd} \bar{\Gamma}_{ax}^{*d} \\ & \quad (x = c \text{ or } x = k), \\ g_{nt\top x} &= \delta_x g_{nt} - F\delta_d g_{nt} \bar{\Gamma}_{0x}^{*d} - F\delta_m g_{nt} \bar{\Gamma}_{0x}^{*m} - g_{mt} \bar{\Gamma}_{nx}^{*m} - g_{nm} \bar{\Gamma}_{tx}^{*m} \\ & \quad (x = c \text{ or } x = k), \\ g_{ab\top c} &= F\delta_d g_{ab}(\delta_c^d - \bar{A}_{0c}^d) - F\delta_m g_{ab} \bar{A}_{0c}^m - g_{db} \bar{A}_{ac}^d - g_{ad} \bar{A}_{bc}^d, \\ g_{ab\top k} &= -F\delta_d g_{ab} \bar{A}_{0k}^d + F\delta_m g_{ab}(\delta_k^m - \bar{A}_{0k}^m) - g_{db} \bar{A}_{ak}^d - g_{ad} \bar{A}_{bk}^d, \\ g_{nt\top c} &= F\delta_d g_{nt}(\delta_c^d - \bar{A}_{0c}^d) - F\delta_m g_{nt} \bar{A}_{0c}^m - g_{mt} \bar{A}_{nc}^m - g_{nm} \bar{A}_{tc}^m, \\ g_{nt\top k} &= -F\delta_d g_{nt} \bar{A}_{0k}^d + F\delta_m g_{nt}(\delta_k^m - \bar{A}_{0k}^m) - g_{mt} \bar{A}_{nk}^m - g_{nm} \bar{A}_{tk}^m. \end{aligned}$$

The above relations are valid only on condition that

$$(3.18) \quad \delta_c g_{ab} \dot{u}^c + \delta_k g_{ab} \dot{v}^k = 0$$

which is satisfied because  $g_{ab}(u, v, \dot{u}, \dot{v})$ ,  $g_{nt}(u, v, \dot{u}, \dot{v})$  are homogeneous of degree zero in  $\dot{u}$  and  $\dot{v}$ .

In [3]  $\bar{D}l^a$  and  $\bar{D}l^k$  are defined by

$$(3.19) \quad \text{a) } \bar{D}l^a = dl^a + \bar{\Gamma}_{0c}^{*a} du^c + \bar{\Gamma}_{0k}^{*a} dv^k, \quad \text{b) } \bar{D}l^k = dl^k + \bar{\Gamma}_{0c}^{*k} du^c + \bar{\Gamma}_{0l}^{*k} dv^l.$$

These formulae are different from (3.4) and (3.5) of present paper, but they may be obtained as a special case of (3.4) and (3.5) if we put

$$\theta_a^\alpha = 0, \quad \nu_k^\alpha = 0, \quad \bar{A}_{0b}^d \bar{D}l^b + \bar{A}_{0k}^d \bar{D}l^k = 0, \quad \bar{A}_{0b}^m \bar{D}l^b + \bar{A}_{0k}^m \bar{D}l^k = 0.$$

Only under these conditions (3.19) and (2.12) are consistent. The conditions  $\bar{A}_{0b}^x \bar{D}l^b + \bar{A}_{0k}^x \bar{D}l^k = 0$   $x = d$ , or  $x = m$  are equivalent (according to (3.12) and (3.16) of [3]) to  $B_\alpha^d Dl^\beta (B_a^\alpha|_\beta l^a + N_k^\alpha|_\beta l^k) = 0$  and  $N_\alpha^m Dl^\beta (B_a^\alpha|_\beta l^a + N_n^\alpha|_\beta l^n) = 0$ .

Both conditions are satisfied when

$$(3.20) \quad Dl^\beta (B_a^\alpha|_\beta l^a + N_k^\alpha|_\beta l^k) = 0.$$

If we define  $\bar{D}l^a$  and  $\bar{D}l^m$  as we have done here by (3.4) and (3.5) then we do not have the restricted condition (3.20).  $g_{ab\top c}$ ,  $g_{ab\top k}$ ,  $g_{nt\top c}$ ,  $g_{nt\top k}$  given by (3.17) have more terms containing  $A_{0y}^x$  then the corresponding formulae (4.15) of [3].

If  $F_n$  satisfies  $g_{\alpha\beta}|_\gamma = 0$  i.e.  $\mu_\gamma = 0$  then  $A_{0\beta}^\alpha = 0$  and the condition (3.20) reduces to  $Dl^\beta[(\dot{\delta}_\beta B_a^\alpha)l^a + \dot{\delta}_\beta N_k^\alpha]l^k = 0$ . Using (2.6) and (2.7) we obtain

$$(3.21) \quad Dg_{\alpha\beta} = B_c^\delta g_{\alpha\beta|\delta} du^c + N_k^\delta g_{\alpha\beta|\delta} dv^k + B_c^\delta g_{\alpha\beta|\delta} \bar{D}l^c + N_k^\delta g_{\alpha\beta|\delta} \bar{D}l^k.$$

Comparing (3.21) with (3.16) we get

$$(3.22) \quad B_c^\delta g_{\alpha\beta|\delta} = B_{\alpha\beta}^{ab} g_{ab\top c} + N_{\alpha\beta}^{nt} g_{nt\top c} + \hat{\theta}_{\alpha\beta} \lambda_c$$

$$(3.23) \quad N_k^\delta g_{\alpha\beta|\delta} = B_{\alpha\beta}^{ab} g_{ab\top k} + N_{\alpha\beta}^{nt} g_{nt\top k} + \hat{\theta}_{\alpha\beta} \lambda_k$$

$$(3.24) \quad B_c^\delta g_{\alpha\beta|\delta} = B_{\alpha\beta}^{ab} g_{ab\bar{c}} + N_{\alpha\beta}^{nt} g_{nt\bar{c}} + \hat{\theta}_{\alpha\beta} (\mu_c + 2l_c)$$

$$(3.25) \quad N_k^\delta g_{\alpha\beta|\delta} = B_{\alpha\beta}^{ab} g_{ab\bar{k}} + N_{\alpha\beta}^{nt} g_{nt\bar{k}} + \hat{\theta}_{\alpha\beta} (\mu_k + 2l_k).$$

Multiplying (3.22) by  $B_\gamma^c$  and (3.23) by  $N_\gamma^k$  and adding these relations we get

$$(3.26) \quad g_{\alpha\beta|\gamma} = B_{\alpha\beta\gamma}^{abc} g_{ab\top c} + B_{\alpha\beta}^{ab} N_\gamma^k g_{ab\top k} + N_{\alpha\beta}^{nt} B_\gamma^c g_{nt\top c} + N_{\alpha\beta\gamma}^{ntk} g_{nt\top k} + \lambda_\gamma \hat{\theta}_{\alpha\beta}.$$

By the same process from (3.24) and (3.25) we obtain

$$(3.27) \quad g_{\alpha\beta|\gamma} = B_{\alpha\beta\gamma}^{abc} g_{ab\bar{c}} + B_{\alpha\beta}^{ab} N_\gamma^k g_{ab\bar{k}} + N_{\alpha\beta}^{nt} B_\gamma^c g_{nt\bar{c}} + N_{\alpha\beta\gamma}^{ntk} g_{nt\bar{k}} + \hat{\theta}_{\alpha\beta} (\mu_\gamma + 2l_\gamma).$$

**THEOREM 3.1.** *The necessary and sufficient conditions for  $g_{\alpha\beta|\gamma} = \lambda_\gamma g_{\alpha\beta}$  are*

$$(3.28) \quad \begin{array}{ll} \text{(a)} \quad g_{ab|c} = \lambda_c (g_{ab} - \hat{\theta}_{ab}) & \text{(c)} \quad g_{nt|c} = \lambda_c (g_{nt} - \hat{\theta}_{nt}) \\ \text{(b)} \quad g_{ab|k} = \lambda_k (g_{ab} - \hat{\theta}_{ab}) & \text{(d)} \quad g_{nt|k} = \lambda_k (g_{nt} - \hat{\theta}_{nt}) \end{array}$$

where

$$(3.29) \quad \lambda_\gamma = B_\gamma^c \lambda_c + N_\gamma^k \lambda_k, \quad \hat{\theta}_{\alpha\beta} = \hat{\theta}_{ab} B_{\alpha\beta}^{ab} + \hat{\theta}_{nk} N_{\alpha\beta}^{nk}, \quad \hat{\theta}_{alph\alpha\beta} B_\alpha^\alpha N_\beta^\beta = 0.$$

*Proof.* Substituting (3.28) and (3.29) into (3.26) we get

$$\begin{aligned} g_{\alpha\beta|\gamma} &= B_{\alpha\beta}^{ab} (B_\gamma^c \lambda_c + N_\gamma^k \lambda_k) (g_{ab} - \hat{\theta}_{ab}) \\ &\quad + N_{\alpha\beta}^{nt} (B_\gamma^c \lambda_c + N_\gamma^k \lambda_k) (g_{nt} - \hat{\theta}_{nt}) + \lambda_\gamma \hat{\theta}_{\alpha\beta} = \lambda_\gamma g_{\alpha\beta}. \end{aligned}$$

On the other hand if  $g_{\alpha\beta|\gamma} = \lambda_\gamma g_{\alpha\beta}$  then from  $N_\alpha^k B_c^\alpha = 0$ ,  $B_a^\alpha B_\alpha^c = \delta_a^c$ ,  $N_k^\alpha N_\alpha^n = \delta_k^n$  and (3.26) we obtain

$$\begin{aligned} g_{\alpha\beta|\gamma} B_{fed}^{\alpha\beta\gamma} &= \delta_f^a \delta_e^b \delta_d^c g_{ab\top c} + \lambda_d \hat{\theta}_{fe} \Rightarrow g_{fe\top d} = \lambda_d (g_{fe} - \hat{\theta}_{fe}) \\ g_{\alpha\beta|\gamma} B_f^\alpha B_e^\beta N_n^\gamma &= \delta_f^a \delta_e^b \delta_n^k g_{ab\top k} + \lambda_n \hat{\theta}_{fe} \Rightarrow g_{fe\top n} = \lambda_n (g_{fe} - \hat{\theta}_{fe}) \\ g_{\alpha\beta|\gamma} N_k^\alpha N_l^\beta B_d^\gamma &= \delta_k^n \delta_l^t \delta_d^c g_{nt\top c} + \lambda_d \hat{\theta}_{kl} \Rightarrow g_{kl\top d} = \lambda_d (g_{kl} - \hat{\theta}_{kl}) \\ g_{\alpha\beta|\gamma} N_p^\alpha N_l^\beta N_m^\gamma &= \delta_p^n \delta_l^t \delta_m^k g_{nt\top k} + \lambda_m \hat{\theta}_{pl} \Rightarrow g_{pl\top m} = \lambda_m (g_{pl} - \hat{\theta}_{pl}). \end{aligned}$$

**THEOREM 3.2.** *The necessary and sufficient conditions for  $g_{\alpha\beta}|_{\gamma} = \mu_{\gamma}g_{\alpha\beta}$  are*

$$(3.30) \quad \begin{aligned} \text{(a)} \quad g_{ab}|_c &= \mu_c g_{ab} - (\mu_c + 2l_c)\hat{\theta}_{ab}, & g_{nt}|_c &= \mu_c g_{nt} - (\mu_c + 2l_c)\hat{\theta}_{nt} \\ \text{(b)} \quad g_{ab}|_k &= \mu_k g_{ab} - (\mu_k + 2l_k)\hat{\theta}_{ab}, & g_{nt}|_k &= \mu_k g_{nt} - (\mu_k + 2l_k)\hat{\theta}_{nt} \end{aligned}$$

where

$$(3.31) \quad \mu_{\gamma} = B_{\gamma}^c \mu_c + N_{\gamma}^k \mu_k$$

The proof follows from (3.27) using the similar method as in the previous Theorem.

**4. Connection between the partial differentiation with respect to different variables.** In formulae (3.12) we can not calculate  $\delta_c \xi^x$ ,  $\delta_m \xi^x$ ,  $\dot{\delta}_d \xi^x$ ,  $\dot{\delta}_k \xi^x$  because we do not have the explicit expression  $x^{\alpha} = x^{\alpha}(u, v, \dot{u}, \dot{v})$  and  $\dot{x}^{\alpha} = \dot{x}^{\alpha}(u, v, \dot{u}, \dot{v})$ . This difficulty may be overcome in such a way that the mentioned expressions are substituted by others in which the partial derivatives with respect to  $x$  and  $\dot{x}$  are present. Starting from (2.8) and (2.28) we may write

$$(4.1) \quad \bar{D}\xi^{\alpha} = B_{\alpha}^a D\xi^{\alpha} + (\theta_b^{\alpha} \xi^b + \nu_m^{\alpha} \xi^m) B_{\alpha}^a D$$

$$(4.2) \quad \bar{D}\xi^n = N_{\alpha}^n D\xi^{\alpha} + (\theta_b^{\alpha} \xi^b + \nu_m^{\alpha} \xi^m) N_{\alpha}^n D$$

where

$$D = \lambda_c du^c + \lambda_k dv^k + (\mu_c + 2l_c)\bar{D}l^c + (\mu_k + 2l_k)\bar{D}l^k = 0.$$

On the other hand

$$(4.3) \quad D\xi^{\alpha} = \delta_{\delta} \xi^{\alpha} dx^{\delta} + \dot{\delta}_l \xi^{\alpha} d\dot{x}^l + \Gamma_{\beta\delta}^{\alpha} \xi^{\beta} dx^{\delta} + A_{\beta\delta}^{\alpha} \xi^{\beta} Dl^{\delta}.$$

Substituting

$$d\dot{x}^l = F(\delta_{\delta}^l - A_0^l{}_{\delta}) Dl^{\delta} - \Gamma_{\delta}^{*l} dx^{\delta} + F^{-1} dF \dot{x}^l$$

in (4.3) and using the notations

$$(4.4) \quad \xi_{,\delta}^x = \delta_{\delta} \xi^x - \dot{\delta}_l \xi^x \Gamma_{\delta}^{*l}$$

$$(4.5) \quad \xi_{;\delta}^x = F \dot{\delta}_l \xi^x (\delta_{\delta}^l - A_0^l{}_{\delta})$$

( $x = b$  or  $x = m$ ) we obtain

$$(4.6) \quad \begin{aligned} D\xi^{\alpha} &= (\xi^b B_{b|\delta}^{\alpha} + \xi^m N_{m|\delta}^{\alpha} + B_b^{\alpha} \xi_{,\delta}^b + N_m^{\alpha} \xi_{;\delta}^m)(B_c^{\delta} du^c + N_k^{\delta} dv^k) \\ &+ (\xi^b B_b^{\alpha}{}_{|\delta} + \xi^m N_m^{\alpha}{}_{|\delta} + B_b^{\alpha} \xi_{;\delta}^b + N_m^{\alpha} \xi_{;\delta}^m)(B_c^{\delta} \bar{D}l^c + N_k^{\delta} \bar{D}l^k). \end{aligned}$$

Substituting (4.6) into (4.1) and (4.2), using the notations of (2.29) and (2.3) after a comparison with (3.14) and (3.15) we get

$$(4.7) \quad \begin{aligned} \text{(a)} \quad \xi_{\top c}^x &= B_c^{\delta} \xi_{,\delta}^x + \bar{\Gamma}_{bc}^{*x} \xi^b + \bar{\Gamma}_{mc}^{*x} \xi^m \\ \text{(b)} \quad \xi_{\top k}^x &= N_k^{\delta} \xi_{,\delta}^x + \bar{\Gamma}_{bc}^{*x} \xi^b + \bar{\Gamma}_{mk}^{*x} \xi^m \\ \text{(c)} \quad \xi_{\top c}^x &= B_c^{\delta} \xi_{;\delta}^x + \bar{A}_{bc}^x \xi^b + \bar{A}_{mc}^x \xi^m \\ \text{(d)} \quad \xi_{\top k}^x &= N_k^{\delta} \xi_{;\delta}^x + \bar{A}_{cb}^x \xi^b + \bar{A}_{mk}^x \xi^m \end{aligned}$$

( $x = a$  or  $x = m$ ).

Comparing (3.12) with (4.7) we get

$$\begin{aligned}
 (4.8) \quad & (a) \quad \delta_c \xi^x - F \dot{\delta}_d \xi^x \bar{\Gamma}_{0c}^{*d} - F \dot{\delta}_k \xi^x \bar{\Gamma}_{0c}^{*k} = B_c^\delta \xi_{;\delta}^x \\
 & (b) \quad \delta_m \xi^x - F \dot{\delta}_d \xi^x \bar{\Gamma}_{0m}^{*d} - F \dot{\delta}_k \xi^x \bar{\Gamma}_{0m}^{*k} = N_m^\delta \xi_{;\delta}^x \\
 & (c) \quad F \dot{\delta}_d \xi^x (\delta_c^d - \bar{A}_{0c}^d) - F \dot{\delta}_k \xi^x \bar{A}_{0c}^k = B_c^\delta \xi_{;\delta}^x \\
 & (d) \quad -F \dot{\delta}_d \xi^x \bar{A}_{0m}^d + F \dot{\delta}_k \xi^x (\delta_m^k - \bar{A}_{0m}^k) = N_m^\delta \xi_{;\delta}^x \\
 & (x = a \text{ or } x = m).
 \end{aligned}$$

The same formulae hold when in (4.8)  $\xi^x$  is substituted by  $g_{ab}$  or  $g_{nt}$ . For  $g_{ab}$  (4.8a) takes the form

$$\begin{aligned}
 (4.9) \quad & \delta_c g_{ab} - F \dot{\delta}_d g_{ab} \bar{\Gamma}_{0c}^{*d} - F \dot{\delta}_m g_{ab} \bar{\Gamma}_{0c}^{*m} = B_c^\delta g_{ab;\delta} \\
 & = B_c^\delta [\delta_\delta (g_{\alpha\beta} B_a^\alpha B_b^\beta) - \dot{\delta}_\iota (g_{\alpha\beta} B_a^\alpha B_b^\beta) \Gamma_{\delta'}^*]
 \end{aligned}$$

where we have used (4.4) in which  $\xi^x$  is substituted by  $g_{ab}$ .

If we substitute (4.9),  $\bar{\Gamma}_{abc}^*$  and  $\bar{\Gamma}_{bac}^*$  defined by (2.29a) into

$$\begin{aligned}
 g_{ab\top c} &= \delta_c g_{ab} - F \dot{\delta}_d g_{ab} \bar{\Gamma}_{0c}^{*d} - F \dot{\delta}_m g_{ab} \bar{\Gamma}_{0c}^{*m} \\
 &\quad - g_{db} \bar{\Gamma}_{ac}^{*d} - g_{ad} \bar{\Gamma}_{bc}^{*d}
 \end{aligned}$$

we get

$$(4.10) \quad g_{ab\top c} = B_c^\gamma B_a^\alpha B_b^\beta g_{\alpha\beta|\gamma} - \lambda_c (\theta_{ab} + \theta_{ba}) = \lambda_c (g_{ab} - \hat{\theta}_{ab})$$

where we put  $\hat{\theta}_{ab} = \theta_{ab} + \theta_{ba}$ . It is evident that (4.10) and (3.28a) are the same formulae, but from (4.10) follows that  $g_{ab\top c} = \lambda_c g_{ab}$  when we choose such a connection coefficients  $\bar{\Gamma}_{abc}^*$  in which  $\theta_{ab} = 0$ .

Similarly, using (3.12c), (4.5) and (2.29c) we obtain

$$\begin{aligned}
 (4.11) \quad & g_{ab\overline{|c}} = F \dot{\delta}_d g_{ab} (\delta_c^d - \bar{A}_{0c}^d) - F \dot{\delta}_m g_{ab} \bar{A}_{0c}^m \\
 & \quad - g_{db} \bar{A}_{ac}^d - g_{ad} \bar{A}_{bc}^d \\
 & = B_c^\delta F \dot{\delta}_\iota (g_{\alpha\beta} B_a^\alpha B_b^\beta) (\delta_\delta^\iota - A_{0\delta}^\iota) - g_{\alpha\beta} B_b^\beta B_c^\delta B_a^\alpha |_\delta \\
 & \quad - g_{\beta\alpha} B_a^\alpha B_c^\delta B_b^\beta |_\delta - (\mu_c + 2l_c) (\theta_{ab} + \theta_{ba}) \\
 & \Rightarrow g_{ab\overline{|c}} = B_{abc}^{\alpha\beta\delta} (g_{\alpha\beta} |_\delta - (\mu_c + 2l_c) (\theta_{ab} + \theta_{ba})) \\
 & = \mu_c g_{ab} - (\mu_c + 2l_c) \hat{\theta}_{ab}
 \end{aligned}$$

(4.11) is the same as (3.30a). from (4.11) follows that  $g_{ab\overline{|c}} = \mu_c g_{ab}$  when we choose such connection coefficients  $\bar{A}_{abc}$  in which  $\theta_{ab} = 0$ .

We have

**THEOREM 4.1.** *If in the recurrent Finsler space the connection coefficients  $\bar{\Gamma}$  and  $\bar{A}$  defined by (2.29) and (2.30) in which  $\theta_{ab} = 0$  and  $\nu_{nk} = 0$  are used ( $\nu_{nk} + \nu_{kn} = \hat{\theta}_{nk}$ ) then*

$$\begin{aligned} g_{ab\top c} &= \lambda_c g_{ab}, & g_{ab\top k} &= \lambda_k g_{ab}, \\ g_{nt\top c} &= \lambda_c g_{nt}, & g_{nt\top k} &= \lambda_k g_{nt}, \\ g_{ab}\overline{|c} &= \mu_c g_{ab}, & g_{ab}\overline{|k} &= \mu_k g_{ab}, \\ g_{nt}\overline{|c} &= \mu_c g_{nt}, & g_{nt}\overline{|k} &= \mu_k g_{nt}. \end{aligned}$$

The part of proof are (4.10) and (4.11). The other formulae can be obtained in the similar way.

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