

NOTE ON STRONG SOLUTIONS OF A STOCHASTIC INCLUSION

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ABSTRACT

Two different definitions of strong solutions of a stochastic integral set-valued equation are discussed. A selection property of a set-valued stochastic integral is given.

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1. Introduction

In the theory of stochastic equations the definition of their solutions is quite natural. A process x is a *solution* of the equation

$$x_t = \int_0^t f_\tau(x) dM_\tau, \quad 0 \leq t < \infty \quad (1)$$

if the above is satisfied for all t .

In the set-valued approach there are two possibilities for defining a solution of a stochastic inclusion.

Let F be a set-valued predictable process and let the following stochastic inclusion be given:

$$x_t \in \int_0^t F_\tau(x) dM_\tau, \quad 0 \leq t < \infty \quad (2)$$

(for required definitions see the next section).

Definition A: A process x is a *solution of problem (2)* if it satisfies

$$x_t - x_s \in \int_s^t F_\tau(x) dM_\tau \quad (3)$$

for all $0 \leq s < t < \infty$.

Definition B: A process x is a *solution of problem (2)* if there exists an M -integrable selector f of $F(x)$ such that

$$x_t = \int_0^t f_\tau dM_\tau, \tag{4}$$

for all $t, 0 \leq t < \infty$.

Definition **A** is more natural because of its similarity to a single-valued case. In stochastic set-valued investigations the two definitions have been used. In [1,10,11] the solutions were investigated in the sense of **B**, while in [7,8] they were investigated in the sense of **A**. Avgerinos and Papageorgiou in [3] used a combination of these definitions. They investigated a random inclusion of the type

$$\dot{x}(\omega, t) \in A(\omega)x(\omega, t) + F(\omega, t, x(\omega, t))$$

and as a solution they meant a process satisfying the inclusion

$$\dot{x}(\omega, t) \in A(\omega)x(\omega, t) + f(\omega)(t)$$

for $f(\omega)$ being a selection of $F(\omega, \cdot, x(\omega, \cdot))$.

It is well known that, in the ordinary differential inclusion case, these two concepts of solutions coincide only for convex-valued set-valued functions (see e.g., Integral Representation Property in [2, p. 99]). The same is true for a stochastic inclusion with a Wiener process ([7, Th. 4.1]), but it is an open problem for the semimartingale case. It is clear that if x is a solution of problem (2) in the sense of definition **B**, it is also a solution in the sense of **A**. The purpose of this paper is to prove the converse, and this requires some selection-type theorem.

2. Preliminaries

Throughout the paper $(\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t \geq 0}, P)$ denotes a complete filtered probability space satisfying the usual hypothesis: (i) \mathcal{F}_0 contains all P -null sets of \mathcal{F} , (ii) $\mathcal{F}_t = \bigcap_{u > t} \mathcal{F}_u$, for all $t, 0 \leq t < \infty$; This means that a filtration $\{\mathcal{F}_t\}_{t \geq 0}$ is right continuous. By a *stochastic process* x on (Ω, \mathcal{F}, P) we mean a collection $(x_t)_{t \geq 0}$ of n -dimensional random variables $x_t: \Omega \rightarrow \mathbb{R}^n, t \geq 0$. The process x is said to be *adapted* if x_t belongs to \mathcal{F}_t (which means it is \mathcal{F}_t -measurable) for each $t \geq 0$. A stochastic process x is called *cádlág* if it a.s. has sample paths which are right continuous, with left limits. Similarly, a stochastic process x is said to be *cáglád* if it a.s. has sample paths which are left continuous, with right limits. The family of all adapted cádlág (cáglád) processes is denoted by $D [L]$.

Let $\mathcal{P}(\mathcal{F}_t)$ denote the smallest σ -algebra on $\mathbb{R}_+ \times \Omega$ with respect to which every cáglád adapted process is measurable in (t, ω) , i.e. $\mathcal{P}(\mathcal{F}_t) = \sigma(L)$. A stochastic process x is said to be *predictable* if x is $\mathcal{P}(\mathcal{F}_t)$ -measurable. The family of all such processes is denoted by \mathcal{P} . One has $\mathcal{P}(\mathcal{F}_t) \subset \beta_+ \otimes \mathcal{F}$, where β_+ denotes the Borel σ -algebra on \mathbb{R}_+ .

Denote $X^2 = \{x \in \mathcal{P} : \|x\|_{S^2} < \infty\}$, where $\|x\|_{S^2} = \|\sup_{t \geq 0} |x_t|\|_{L^2}$. It can be verified that $(X^2, \|\cdot\|_{S^2})$ is a Banach space (see e.g., [12, 13]).

Let \mathcal{M} [or \mathcal{M}_0] denote the set of all one-dimensional semimartingales [or vanishing at $t = 0$ respectively]. Given $M \in \mathcal{M}$, let $M = N + A$ be a decomposition of M , where N is a local martingale, A denotes a process with path of finite variation on compacts and $[N, N]$ denotes the quadratic variation process of N . Define

$$j_2(N, A) = \|[N, N]_\infty\|_{L^2}^{\frac{1}{2}} + \int_0^\infty |dA_s|_{L^2}$$

and

$$\|M\|_{\mathfrak{H}^2} = \inf_{M = \sum_{i=1}^N A_i} j_2(N, A),$$

where $\int_0^t |dA_s| = \int_0^t |dA_s|$ and the infimum is taken over all possible decompositions of M . Define $\mathfrak{H}^2 = \{M \in \mathcal{M}_0: \|M\|_{\mathfrak{H}^2} < \infty\}$. We also let $L(M) = \{H \in \mathcal{P}: H \text{ is integrable with respect to } M\}$ with a norm $\|H\|_M = \|H \cdot M\|_{\mathfrak{H}^2}$. Moreover, by $H \cdot M$ we denote $\int H_\tau dM_\tau$.

Let \mathbb{R}^n be the n -dimensional Euclidean space and $Cl(\mathbb{R}^n)$, $\text{Comp}(\mathbb{R}^n)$ and $\text{Conv}(\mathbb{R}^n)$ denote spaces of all nonempty closed, compact, compact and convex, respectively, subsets of \mathbb{R}^n . Denote by $\text{dist}(a, A)$ the distance between $a \in \mathbb{R}^n$ and $A \in Cl(\mathbb{R}^n)$. We put $\bar{h}(A, B) = \sup_{a \in B} \text{dist}(a, A)$, and $h(A, B) = \max\{\bar{h}(A, B), \bar{h}(B, A)\}$ for all $A, B \in Cl(\mathbb{R}^n)$.

Consider a set-valued stochastic process $\mathfrak{R} = (\mathfrak{R}_t)_{t \geq 0}$ with values in $Cl(\mathbb{R}^n)$, i.e. a family of \mathcal{F} -measurable set-valued mappings $\mathfrak{R}_t: \Omega \rightarrow Cl(\mathbb{R}^n)$ for each $t \geq 0$. We call \mathfrak{R} *predictable* if \mathfrak{R} is $\mathcal{P}(\mathcal{F}_t)$ -measurable in the sense of set-valued functions.

Given a predictable set-valued process $\mathfrak{R} = (\mathfrak{R}_t)_{t \geq 0}$ and $M \in \mathcal{M}_0$, let

$$\mathcal{I}_M(\mathfrak{R}) := \{H \in L(M): H_t \in \mathfrak{R}_t \text{ for all } t\}.$$

A set $\mathcal{I}_M(\mathfrak{R})$ is called a *subtrajectory integral* of \mathfrak{R} .

A predictable set-valued process \mathfrak{R} is said to be *integrable with respect to a semimartingale* M or, simply, *M -integrable*, if $\mathcal{I}_M(\mathfrak{R})$ is a nonempty set. It follows immediately from the properties of stochastic integrals with respect to semimartingales (see Th. 3.2 of [6]) and Kuratowski and Ryll-Nardzewski measurable selection theorem (see e.g. [9]), that every M -integrably bounded and predictable set-valued stochastic process \mathfrak{R} is M -integrable. Recall a set-valued stochastic process $\mathfrak{R} = (\mathfrak{R}_t)_{t \geq 0}$ is *M -integrably bounded* if there exists $m \in L(M) \cap X^2$ such that $h(\mathfrak{R}_t, \{0\}) \leq m_t$ a.s., for each $t \geq 0$.

3. Selection Properties of Integrals

Convention: In this section we employ a notation $\int_a^b H dM$ instead of $\int_a^b H_s dM_s$ for clarity of formulas.

Lemma 1: *Let M be a semimartingale in \mathfrak{H}^2 , let $x = (x_t)_{t \geq 0}$ be a càdlàg process and let a predictable set-valued process \mathfrak{G} be integrably bounded by a process $m = (m_t)_{t \geq 0}$, $m \in L(M)$. If $x_t - x_s \in cl_{L^2} \int_s^t \mathfrak{G} dM$ for every $0 \leq s < t < \infty$, then for all stopping times α, β , $0 \leq \alpha < \beta < \infty$, there exists a sequence $(g^n) \subset cl_{L(M)} \mathcal{I}_M(\mathfrak{G})$ such that*

$$\lim_{n \rightarrow \infty} \left\| (x_\beta - x_\alpha) - \int_\alpha^\beta g^n dM \right\|_{L^2} = 0.$$

Proof: Let $\alpha_n = k \cdot 2^{-n}$ for ω such that $(k-1)2^{-n} \leq \alpha(\omega) < k2^{-n}$ and $\beta_n = k \cdot 2^{-n}$ for ω such that $(k-1)2^{-n} \leq \beta(\omega) < k2^{-n}$. Let $A_k^n = \{\omega: \alpha \geq k \cdot 2^{-n}\}$ and $B_k^n = \{\omega: \beta \geq k \cdot 2^{-n}\}$. Then we have

$$[0, \alpha_n] = (\{0\} \times \Omega) \cup \left(\bigcup_{k=0}^{\infty} (k \cdot 2^{-n}, (k+1)2^{-n}] \times A_k^n \right),$$

$$[0, \beta_n] = (\{0\} \times \Omega) \cup \left(\bigcup_{k=0}^{\infty} (k \cdot 2^{-n}, (k+1)2^{-n}] \times B_k^n \right).$$

Now, for each $n = 1, 2, \dots$ we obtain

$$x_{\alpha_n} = x_0 + \sum_{k=0}^{\infty} I_{A_k^n}(x_{(k+1)2^{-n}} - x_{k2^{-n}})$$

and

$$x_{\beta_n} = x_0 + \sum_{k=0}^{\infty} I_{B_k^n}(x_{(k+1)2^{-n}} - x_{k2^{-n}}).$$

Since $A_k^n \subset B_k^n$ then

$$x_{\beta_n} - x_{\alpha_n} = \sum_{k=0}^{\infty} I_{B_k^n \setminus A_k^n}(x_{(k+1)2^{-n}} - x_{k2^{-n}}).$$

For every $k = 0, 1, \dots$ and $n = 1, 2, \dots$ we can select $g^{n,k} \in \mathcal{F}_M(\mathcal{G})$ such that

$$\| x_{(k+1)2^{-n}} - x_{k2^{-n}} - \int_{k2^{-n}}^{(k+1)2^{-n}} g^{n,k} dM \|_{L^2} < \epsilon / (3 \cdot 2^k)$$

and put

$$g^n = I_{[0, \alpha_n]} \bar{g} + \sum_{k=0}^{\infty} I_{(k2^{-n}, (k+1)2^{-n}] \times B_k^n \setminus A_k^n} \cdot g^{n,k} + I_{(\beta_n, \infty)} \bar{g},$$

where $\bar{g} \in \mathcal{F}_M(\mathcal{G})$ is an arbitrary selector.

It is easy to see that g^n belongs to $cl_{L(M)} \mathcal{F}_M(\mathcal{G})$ because of decomposability of $\mathcal{F}_M(\mathcal{G})$ and the Lebesgue Dominated Convergence Theorem. Moreover,

$$\int_{\alpha_n}^{\beta_n} g^n dM = \sum_{k=0}^{\infty} I_{B_k^n \setminus A_k^n} \int_{k2^{-n}}^{(k+1)2^{-n}} g^{n,k} dM.$$

Since $|g_t^n(\omega)| \leq m_t(\omega)$ for every (t, ω) , we obtain

$$\| \int_{\alpha}^{\beta} g^n dM - \int_{\alpha_n}^{\beta_n} g^n dM \|_{L^2} \leq \sqrt{8} \| \int_0^{\infty} I_{(\alpha, \beta] \Delta (\alpha_n, \beta_n)} m dM \|_{\mathfrak{JG}^2},$$

where $A \Delta B$ denotes the set $(A \setminus B) \cup (B \setminus A)$. Therefore,

$$\begin{aligned} & \| x_{\beta} - x_{\alpha} - \int_{\alpha}^{\beta} g^n dM \|_{L^2} \\ & \leq \| x_{\beta} - x_{\alpha} - (x_{\beta_n} - x_{\alpha_n}) \|_{L^2} + \| x_{\beta_n} - x_{\alpha_n} - \int_{\alpha_n}^{\beta_n} g^n dM \|_{L^2} \\ & \quad + \sqrt{8} \| \int_0^{\infty} I_{(\alpha, \beta] \Delta (\alpha_n, \beta_n)} m dM \|_{\mathfrak{JG}^2}. \end{aligned}$$

Since $(x_t)_{t \geq 0}$ and the stochastic integral are càdlàg processes, $\alpha_n \rightarrow \alpha$, $\beta_n \rightarrow \beta$ as $n \rightarrow \infty$, we can select n_0 so great that first and third components are less than $\epsilon/3$ for $n > n_0$.

Next we have

$$\begin{aligned} & \|x_{\beta_n} - x_{\alpha_n} - \int_{\alpha_n}^{\beta_n} g^n dM\|_{L^2} \\ &= \left\| \sum_{k=0}^{\infty} I_{B_k^n \setminus A_k^n} [x_{(k+1)2^{-n}} - x_{k2^{-n}} - \int_{k2^{-n}}^{(k+1)2^{-n}} g^{n,k} dM] \right\|_{L^2} \\ &\leq \sum_{k=0}^{\infty} \epsilon / (3 \cdot 2^k) = \epsilon/3 \text{ for } n = 1, 2, \dots \end{aligned}$$

Since $\epsilon > 0$ is arbitrary and fixed, we obtain

$$\lim_{n \rightarrow \infty} \left\| (x_\beta - x_\alpha) - \int_\alpha^\beta g^n dM \right\|_{L^2} = 0. \quad \square$$

Theorem 1: Let M be a semimartingale in \mathbb{H}^2 and let m be a process in $L(M) \cap X^2$. Suppose \mathfrak{R} is a predictable set-valued process integrably bounded by m . If $x = (x_t)_{t \geq 0}$ is a càdlàg process such that $x_t - x_s \in cl_{L^2} \int_s^t \mathfrak{R} dM$ a.s. for every stopping time T and $s, t, T \leq s \leq t \leq \infty$, then for every $\epsilon > 0$ there exists a process $H \in cl_{L(M)} \mathfrak{F}_M(\mathfrak{R})$ such that

$$\sup_{t \geq T} \left\| x_t - x_T - \int_T^t H dM \right\|_{L^2} < \epsilon.$$

Proof: Let $\epsilon > 0$ be fixed. By the Fundamental Theorem of Local Martingales and the Bichteler-Dellacherie Theorem M has a decomposition $M = N + A$ such that the jumps of the local martingale N are bounded by $\epsilon(3C_2 \|m\|_{S^2})^{-1}$. Define recursively

$$\begin{aligned} T_0 &= T \\ T_{k+1} &= \inf \left\{ t \geq T_k : \left(\int_{T_{k-1}}^t d[N, N] \right)^{1/2} + \int_{T_{k-1}}^t |dA| \geq \epsilon(3C_2 \|m\|_{S^2})^{-1} \right. \\ &\quad \left. \text{or } |x_t - x_{T_{k-1}}| > \epsilon/3 \right\}. \end{aligned}$$

Then (T_k) increase to infinity a.s. [12, p. 192].

By Lemma 1, for every $k = 1, 2, \dots$, there exists a selector $H_k \in \mathfrak{F}_M(\mathfrak{R})$ such that

$$\left\| x_{T_k} - x_{T_{k-1}} - \int_{T_{k-1}}^{T_k} H_k dM \right\|_{L^2} < \frac{1}{2^k} \cdot \epsilon/3.$$

Next, take any $H_0 \in \mathfrak{F}_M(\mathfrak{R})$ and define $H = H_0 I_{[0, T]} + \sum_{k=1}^{\infty} H_k I_{[T_{k-1}, T_k]}$. Let us claim that $H \in cl_{L(M)} \mathfrak{F}_M(\mathfrak{R})$. Indeed, the set $cl_{L(M)} \mathfrak{F}_M(\mathfrak{R})$ is closed in $L(M)$ and decomposable.

Then $H_n = H_0 I_{[0, T)} + \sum_{k=1}^n H_k I_{[T_{k-1}, T_k)}$ belongs to $\mathfrak{F}_M(\mathfrak{R})$. Since H_n tends to H for all (t, ω) and $|H_n| < m \in L(M)$ for each $n = 1, 2, \dots$, then by the Lebesgue Dominated Convergence Theorem H_n tends to H in $L(M)$ [12].

Now we have

$$\begin{aligned} \sup_{t \geq T} \|x_t - x_T - \int_T^t H dM\|_{L^2} &= \sup_{k \geq 1} \sup_{T_{k-1} \leq t < T_k} \|x_t - x_T - \int_T^t H dM\|_{L^2} \\ &\leq \sup_{k \geq 1} \sup_{T_{k-1} \leq t < T_k} \|x_t - x_{T_{k-1}}\|_{L^2} + \sup_{k \geq 2} \left\| \sum_{i=1}^{k-1} (x_{T_i} - x_{T_{i-1}} - \int_{T_{i-1}}^{T_i} H dM) \right\|_{L^2} \\ &\quad + \sup_{k \geq 1} \sup_{T_{k-1} \leq t < T_k} \left\| \int_{T_{k-1}}^t H dM \right\|_{L^2} = I_1 + I_2 + I_3. \end{aligned}$$

By the definition of T_k we obtain $\sup_{T_{k-1} \leq t < T_k} |x_t - x_{T_{k-1}}| < \epsilon/3$ for $k = 1, 2, \dots$, and a.e. $\omega \in \Omega$. Therefore, $I_1 < \epsilon/3$.

$$\begin{aligned} I_2 &\leq \sup_{k \geq 2} \sum_{i=1}^{k-1} \left\| x_{T_i} - x_{T_{i-1}} - \int_{T_{i-1}}^{T_i} H_i dM \right\|_{L^2} \\ &\leq \sum_{i=1}^{\infty} \left\| x_{T_i} - x_{T_{i-1}} - \int_{T_{i-1}}^{T_i} H dM \right\|_{L^2} \leq \epsilon/3 \sum_{i=1}^{\infty} \frac{1}{2^i} = \epsilon/3. \end{aligned}$$

Now let us observe that

$$\begin{aligned} \left\| \int_{T_{k-1}}^t H dM \right\|_{L^2} &\leq \|H \cdot I_{(T_{k-1}, t]} \cdot M\|_{S^2} \leq C_2 \|H \cdot I_{(T_{k-1}, t]} \cdot M\|_{\mathfrak{H}^2} \\ &\leq C_2 \|m\|_{S^2} \left(\left(\int_{T_{k-1}}^t d[N, N] \right)^{1/2} + \int_{T_{k-1}}^t |dA| \right)_{L^2}. \end{aligned}$$

Therefore, by the definition of (T_k) we get $I_3 \leq \epsilon/3$ and we are done. □

Theorem 2: *Let all assumptions of Theorem 1 be satisfied. If, moreover, \mathfrak{R} takes on convex values, then there exists a process $H \in cl_{L(M)} \mathfrak{F}_M(\mathfrak{R})$ such that*

$$x_t = x_T + \int_T^t H dM \quad \text{a.s. for each } t \geq T.$$

Proof: By virtue of Theorem 1, there exists a sequence (H^n) in $cl_{L(M)} \mathfrak{F}_M(\mathfrak{R})$ such that

$$\sup_{t \geq T} \|x_t - x_T - \int_T^t H^n dM\|_{L^2} \rightarrow 0 \text{ as } n \rightarrow \infty.$$

We show that the set (H^n) is weakly compact in $L(M)$. Since

$$\|H\|_M \leq \left(\int_{\Omega} \int H^2 d[N, N] dP \right)^{1/2} + \left(\int_{\Omega} \left(\int |H| |dA| \right)^2 \right)^{1/2},$$

then this norm is weaker from the norm defined by the sum of norms in $\mathcal{L}^2(\Omega, \mathcal{L}^2(\mathbb{R}_+, \mu))$ and $\mathcal{L}^2(\Omega, \mathcal{L}^1(\mathbb{R}_+, \nu))$, where μ and ν denote measures generated by $[N, N]$ and $|A|$ respectively. The set (H^n) is integrably bounded, so it is weakly compact in the first space mentioned above by [4, Th. II.9]. It is also weakly compact in the second space, because the weak compactness of bounded sets in $\mathcal{L}^2(\Omega, E)$ and $\mathcal{L}^1(\Omega, E)$ is equivalent ([4]) and it follows by [9, Th. 2.1] that the set of selectors of integrable bounded set-valued functions is weakly compact in $\mathcal{L}^1(\Omega, \mathcal{L}^1(\nu)) = \mathcal{L}^1(\Omega \times \mathbb{R}_+, P \times \nu)$. Therefore, we deduce that (H^n) has a weak cluster point H in $cl_{L(M)} S_M(\mathcal{R})$.

On the other hand, $x_t - x_T$ and $\int_T^t H dM$ are weak cluster points of a weak convergent sequence $\int_T^t H^n dM$ in $L^2(\mathcal{F}_t)$ for each $t \geq T$. Therefore $x_t - x_T$ is a modification of $(\int_T^t H dM)_{t \geq T}$. Then, by [12, I. Th. 2],

$$x_t = x_T + \int_T^t H dM \text{ a.s. for each } t \geq T. \quad \square$$

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